# Recovery-Based A Posteriori Error Estimators for Elliptic Equations

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Recent Advances in A Posteriori Error Estimation and Adaptive Methods, SIAM Annual Meeting, 2008



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   L2 Projection Recovery Estimators

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   Higher-order Finite Elements?

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  - 1-D P2 Element Example
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  - Concluding Remarks

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# Scalar Elliptic Equations

Scalar Elliptic Equations

 $-\nabla \cdot (A(x)\nabla u) + \mathbf{b} \cdot \nabla u + cu = f$  in  $\Omega \subset \mathcal{R}^d$ 

with boundary conditions

u = 0 on  $\Gamma_D$  and  $\mathbf{n} \cdot A \nabla u = 0$  on  $\Gamma_N$ 

• Let  $X v = \mathbf{b} \cdot \nabla v + c v$ , rewrite the equation as

 $-\nabla \cdot (A(x)\nabla u) + X u = f \text{ in } \Omega \subset \mathcal{R}^d$ 

Diffusion Dominant Case only

L2 Projection Recovery Estimators Higher-order Finite Elements?

# L<sup>2</sup> Projection Recovery

The finite element solution u<sub>h</sub> ∈ U<sub>k</sub>, U<sub>k</sub> (k ≥ 1) is the piecewise continuous k − th degree polynomial finite element space.

#### $(A \nabla u_h, \nabla v) + (X u_h, v) = (f, v) \quad \forall v \in \mathcal{U}_k$

- Quantity to recover: the flux  $\sigma = -A \nabla u \in H(div)$
- Recovered flux σ<sub>h</sub> lies in H(div) conforming finite element space RT<sub>k-1</sub> or BDM<sub>k</sub>.
- Find  $\sigma_h \in RT_{k-1}/BDM_k$ , s.t.

#### $(\mathbf{A}^{-1}\sigma_h, \tau) = -(\nabla u_h, \tau) \quad \forall \tau \in \mathbf{R}T_{k-1}/\mathbf{B}DM_k$



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L2 Projection Recovery Estimators Higher-order Finite Elements?

# L<sup>2</sup> Projection Error Estimators

• L<sup>2</sup> projection error estimator

$$\xi_{L2} = \|A^{1/2} \nabla u_h + A^{-1/2} \sigma_h\|_{0,\Omega}$$

When Linear Elements and Diffusion Dominated, even for discontinuous A

$$\xi_{L2} \sim \|\boldsymbol{A}^{1/2} \nabla (\boldsymbol{u} - \boldsymbol{u}_h)\|_{0,\Omega}$$



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L2 Projection Recovery Estimators Higher-order Finite Elements?

# Existing recovery based error estimators for higher order finite elements

- (Bank, Xu, and B. Zhang 2007) Superconvergence, gradient recovery
- (Naga and Z. Zhang 2005) Polynomial Preserving Recovery of the gradient on mildly structured mesh
- (Bartels and Carstensen 2002) Averaging Scheme for the gradient, Poisson equations



L2 Projection Recovery Estimators Higher-order Finite Elements?

#### Why *L*<sup>2</sup> recovery works for linear elements?

#### Residual based error estimator:

$$\eta_{Res}^2 := \sum_{e \in \mathcal{E}} h_e \| [A \nabla u_h \cdot \mathbf{n}] \|_{0,e}^2 + \sum_{K \in \mathcal{T}} h_K^2 \| f + \nabla \cdot (A \nabla u_h) - X u_h \|_{0,K}^2$$

 (Carstensen and Verfürth 1999), for the linear element case, edge jump terms are dominant, and element residual terms are higher order terms.

• 
$$\eta_{edge}^2 = \sum_{e \in \mathcal{E}} h_e \| [A \nabla u_h \cdot \mathbf{n}] \|_{0,e}^2$$

•  $\xi_{L2} \sim \eta_{edge}$ 

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L2 Projection Recovery Estimators Higher-order Finite Elements?

# Why L<sup>2</sup> recovery may fail for higher order elements?

- (D.Yu 91), for rectangular grids, edge jump terms are dominant for the odd-order element case, while element residual terms are dominant for the even-order element case.
- Simple L<sup>2</sup> projection recovery of the flux may fail for higher order finite elements.



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L2 Projection Recovery Estimators Higher-order Finite Elements?

## How to fix it?

Recover a  $\sigma$ , such that element residual terms are higher order terms.



H(div) Problem Recovery New Error Estimator Analysis of the New Error Estimator

## An H(div) Problem Recovery

• Find  $\sigma_h \in RT_{k-1}/BDM_k$ , s.t.,

$$(A^{-1}\sigma_h, \tau) + (\nabla \cdot \sigma_h, \nabla \cdot \tau) = (-\nabla u_h, \tau) + (f - Xu_h, \nabla \cdot \tau) \quad \forall \tau \in RT_{k-1}/BDM_k$$

Too costly to solve?
 Fast Full-Multigrid H(div) Solvers or Direct Solvers



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H(div) Problem Recovery New Error Estimator Analysis of the New Error Estimator

#### **New Error Estimator**

$$\xi_{hdiv,\mathcal{K}} = \|\boldsymbol{A}^{-1/2}\boldsymbol{\sigma}_h + \boldsymbol{A}^{1/2}\nabla \boldsymbol{u}_h\|_{0,\mathcal{K}}.$$

$$\xi_{hdiv} = \|A^{-1/2}\sigma_h + A^{1/2}\nabla u_h\|_{0,\Omega}$$



H(div) Problem Recovery New Error Estimator Analysis of the New Error Estimator



- $e = u u_h$ .
- Notation:  $||h g(x)||_0 = (\sum_{K \in \mathcal{T}} h_K^2 ||g||_{0,K}^2)^{1/2}$

Reliability bound.

 $\|oldsymbol{A}^{1/2}
ablaoldsymbol{e}\|_0\leq oldsymbol{C}(\xi_{\mathit{hdiv}}+\|oldsymbol{h}(\mathit{f}-\mathit{X}\mathit{u}_habla\cdotoldsymbol{\sigma}_h)\|_0)$ 

• Is  $\|h(f - Xu_h - \nabla \cdot \sigma_h)\|_0$  is of higher order compared to  $\xi_{hdiv}$ ?



H(div) Problem Recovery New Error Estimator Analysis of the New Error Estimator

# Analysis

- $e = u u_h$ .
- Notation:  $||h|g(x)||_0 = (\sum_{K \in \mathcal{T}} h_K^2 ||g||_{0,K}^2)^{1/2}$
- Reliability bound.

 $\|A^{1/2} \nabla e\|_0 \leq C(\xi_{hdiv} + \|h(f - Xu_h - \nabla \cdot \boldsymbol{\sigma}_h)\|_0)$ 

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H(div) Problem Recovery New Error Estimator Analysis of the New Error Estimator

• Since  $(f - Xu_h - \nabla \cdot \sigma_h, \nabla \cdot \tau) = (\nabla u_h + A^{-1}\sigma_h, \tau)$ , we can prove

$$\|f - Xu_h - \nabla \cdot \boldsymbol{\sigma}_h\|_0 \leq C\xi_{hdiv} + \|R - \mathcal{P}_{k-1}R\|_0$$

Where  $R = f - Xu_h - \nabla \cdot \sigma_h$ , and  $\mathcal{P}_{k-1}$  is the  $L^2$  projection operator onto the discontinuous piecewise polynomial space of degree k - 1 with respect to the triangulation  $\mathcal{T}$ .

•  $||h(f - Xu_h - \nabla \cdot \sigma_h)||_0$  is of higher order compared to  $\xi_{hdiv}$ .

 $\|A^{1/2} \nabla e\|_0 \leq C \xi_{hdiv} + h.o.t$ 



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Two Criteria for Recovery Based Error Estimators 1-D P2 Element Example 2-D P2 Element Example

# Two Criteria for Recovery Based Error Estimators

- Optimality of the mesh
  - Smooth solution and uniform mesh
    - Poisson equation  $-\Delta u = f$  and  $u \in H^{1+k}$ ,
    - *u<sub>h</sub>* ∈ *U<sub>k</sub>* is the finite element solution in the piecewise continuous *k*-th degree finite element space.
    - $T_h$  is the mesh with uniform mesh size h
    - *N*: Number of the unknowns  $\approx h^{-d}$ , d = 1, 2, or 3.
    - $\bullet \ \|\nabla \boldsymbol{e}\|_0 \leq \boldsymbol{C} \boldsymbol{h}^k \|\boldsymbol{D}^{1+k} \boldsymbol{u}\|_0 = \boldsymbol{C} \boldsymbol{N}^{-k/d}$
    - The slope of  $\log(N)$ - $\log(\|\nabla e\|_0)$  line is -k/d.
  - Adaptive mesh generated by error indicators: should have similar error decay.
- Effectivity index —



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    - $\|\nabla e\|_0 \leq Ch^k \|D^{1+k}u\|_0 = CN^{-k/d}.$
    - The slope of log(N)-log(||∇e||₀) line is -k/d.
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Two Criteria for Recovery Based Error Estimators **1-D P2 Element Example** 2-D P2 Element Example

#### A 1-D P2 element example

-u'' = f on (0, 1), u(0) = u(1) = 0, with the right-hand side function  $f = 30x^4 - 20x^3$  and the exact solution  $u = x^5(1 - x)$ .



Figure: True solution u



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Two Criteria for Recovery Based Error Estimators **1-D P2 Element Example** 2-D P2 Element Example

#### L<sup>2</sup> projection error estimator fails

 $u_h \in \mathcal{U}_2$  is the quadratic finite element solution.  $L^2$  projection recovery: Find  $\sigma_h \in \mathcal{U}_2$ ,s.t.,  $(\sigma_h, \tau) = -(u'_h, \tau) \ \forall \tau \in \mathcal{U}_2$  $\xi_{L2} = \|\sigma + u'_h\|_0$ 



Two Criteria for Recovery Based Error Estimators 1-D P2 Element Example 2-D P2 Element Example

#### Error estimator $\xi_{hdiv}$

 $u_h \in \mathcal{U}_2$  is the quadratic finite element solution. Recover  $\sigma_h \in \mathcal{U}_2$ 

$$(\sigma_h, \tau) + (\sigma'_h, \tau') = -(u'_h, \tau) + (f, \tau') \quad \forall \tau \in \mathcal{U}_2$$

Error Estimator

 $\xi_{hdiv} = \|\sigma_h + u_h'\|_0$ 



Two Criteria for Recovery Based Error Estimators **1-D P2 Element Example** 2-D P2 Element Example

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Image: A matrix

# For $P_2$ element, error estimator $\xi_{hdiv}$ works



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Two Criteria for Recovery Based Error Estimators 1-D P2 Element Example 2-D P2 Element Example

# 2-D P2 Element Example

Interface problem

$$\begin{cases} -\nabla \cdot (a\nabla u) = f \text{ in } \Omega = (-1, 1)^2 \\ u = g \text{ on } \partial \Omega \end{cases}$$

with a = R in  $(0, 1)^2 \cup (-1, 0)^2$  and 1 in  $(-1, 0) \times (0, 1) \cup (0, 1) \times (-1, 0)$ 

• Exact solution  $u(r, \theta) = r^{\alpha} \mu(\theta) \in H^{1+\alpha-\epsilon}(\Omega)$  with

$$\mu(\theta) = \begin{cases} \cos((\frac{\pi}{2} - \sigma)\alpha) \cdot \cos((\theta - \frac{\pi}{2} + \rho)\alpha) & \text{if } 0 \le \theta \le \frac{\pi}{2}, \\ \cos(\rho\alpha) \cdot \cos((\theta - \pi + \sigma)\alpha) & \text{if } \frac{\pi}{2} \le \theta \le \pi, \\ \cos(\sigma\alpha) \cdot \cos((\theta - \pi - \rho)\alpha) & \text{if } \pi \le \theta \le \frac{3\pi}{2}, \\ \cos((\frac{\pi}{2} - \rho)\alpha) \cdot \cos((\theta - \frac{3\pi}{2} - \sigma)\alpha) & \text{if } \frac{3\pi}{2} \le \theta \le 2\pi. \end{cases}$$

• Example when  $\alpha = 0.5$ , then  $R \approx 5.828427124746190$  **PURDUE**  $\rho = \pi/4$ , and  $\sigma \approx -2.3561944901923448$ .

Two Criteria for Recovery Based Error Estimators 1-D P2 Element Example 2-D P2 Element Example

Concluding Remarks



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Two Criteria for Recovery Based Error Estimators 1-D P2 Element Example 2-D P2 Element Example



Zhiqiang Cai, Shun Zhang

**Recovery-Based A Posteriori Error Estimators** 

# **Concluding Remarks**

- An Extension of L<sup>2</sup> Recovery
- Flux Recovery for Higher Order Finite Elements
- No Regularity Assumptions are Required

