

If we assume $\bar{U} = U_0 + \varepsilon \bar{U}_1 + \dots$

$$\Rightarrow (1 + (h_p')^2) \frac{\partial^2 \bar{U}_0}{\partial s^2} + (\alpha^2 + \beta^2) \frac{\partial \bar{U}_0}{\partial s} = 0$$

$$\Rightarrow \bar{U}_0 = A(r) + B(r) \exp\left(-\frac{(\alpha^2 + \beta^2)s}{1 + (h_p')^2}\right)$$

Boundary conditions imply:

$$U_0(0, r) = g$$

$$\lim_{s \rightarrow \infty} \bar{U}_0(s, r) = \int_0^{h_p(r)} f(\alpha s + \beta r, \beta s - \alpha r) ds + g(x_0, y_0)$$

The solution can be pieced together as usual.

Burger's Equation

Suppose we want to model the density $g(x, t)$ of cars on a stretch of highway.



$g(x, t)$ - traffic density (#cars/length)
 $q(x, t)$ - traffic flow (#cars/hour)

N of cars in (a, b) is

$$N = \int_a^b g(x, t) dx$$

$$\Rightarrow \frac{dN}{dt} = q(a) - q(b) \quad (\text{Conservation Law}).$$

$$\Rightarrow \int_a^b \frac{dg(x, t)}{dt} dx = q(a) - q(b)$$

$$\Rightarrow \int_a^b \frac{dg(x, t)}{dt} dx = - \int_a^b \frac{dq}{dx} dx.$$

Take limit as $(b-a) \rightarrow 0$ we get

$$\frac{dg}{dt} = - \frac{dq}{dx}$$

We need a constitutive law.

Let v be the velocity of cars.

$$\Rightarrow q = s \cdot v.$$

Assume $v = v(s)$, velocity only depends on density.

$$\Rightarrow \frac{ds}{dt} + q'(s) \frac{\partial s}{\partial x} = 0.$$

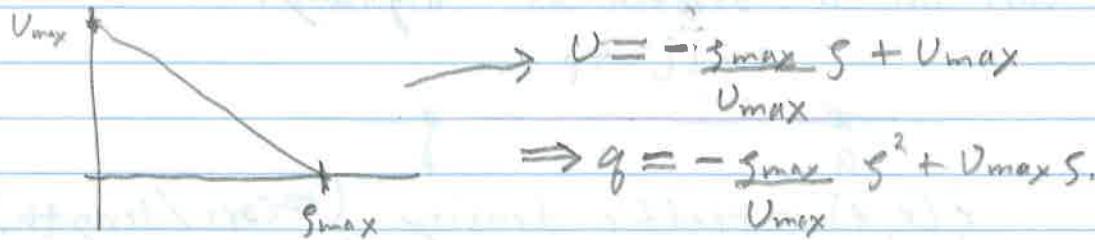
This is like advection with a changing speed.
The function $q'(s)$ is the density wave velocity.

Simple Traffic Model.

1. v should be decreasing.

2. $v(0) = v_{\max}$ (speed limit)

3. $v(s_{\max}) = 0$ (+traffic jam).



This gives us:

$$\frac{ds}{dt} + v_{\max} \left(1 - \frac{2s}{s_{\max}}\right) \frac{\partial s}{\partial x} = 0.$$

Red light green light.

$$\frac{ds}{dt} + (1-2s) \frac{ds}{dx} = 0$$

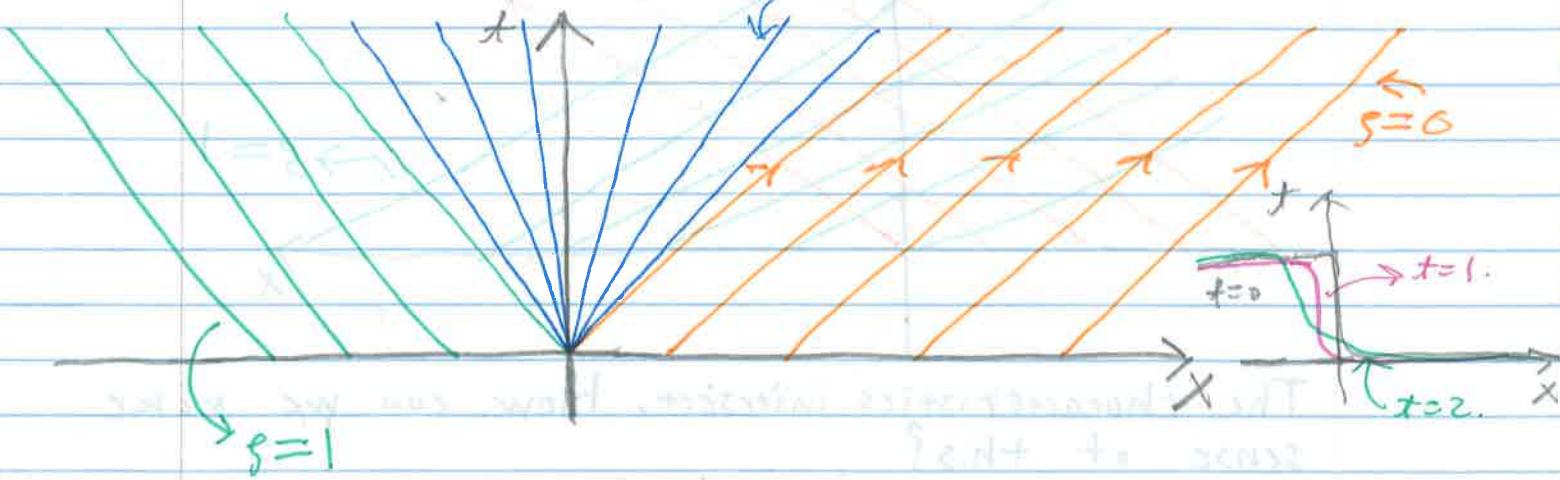
$$s(x, 0) = \begin{cases} 1, & x < 0 \\ 0, & x > 0. \end{cases}$$

Characteristics:

$$\frac{dx}{dt} = 1-2s, \quad \frac{ds}{dt} = 0.$$

$$\Rightarrow x(t) = (1 - 2s_0)t + x_0$$

$$s(t) = s_0 \quad 0 < s < 1$$



What happens at $x=0$? s can take any value so the slope rotates from -1 to 1 . This is known as a rarefaction wave.

Green light + red light,

$$\frac{\partial s}{\partial t} + (1 - 2s) \frac{\partial s}{\partial x} = 0$$

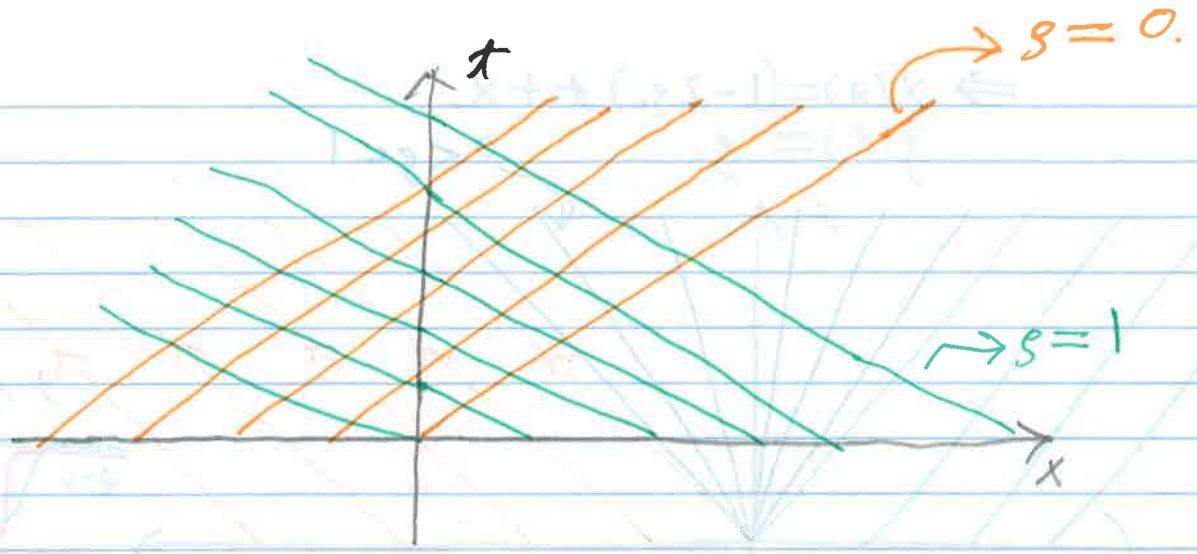
$$s(x, 0) = 0, \quad x < 0, \\ s(0, t) = 1, \quad t > 0$$

Characteristics:

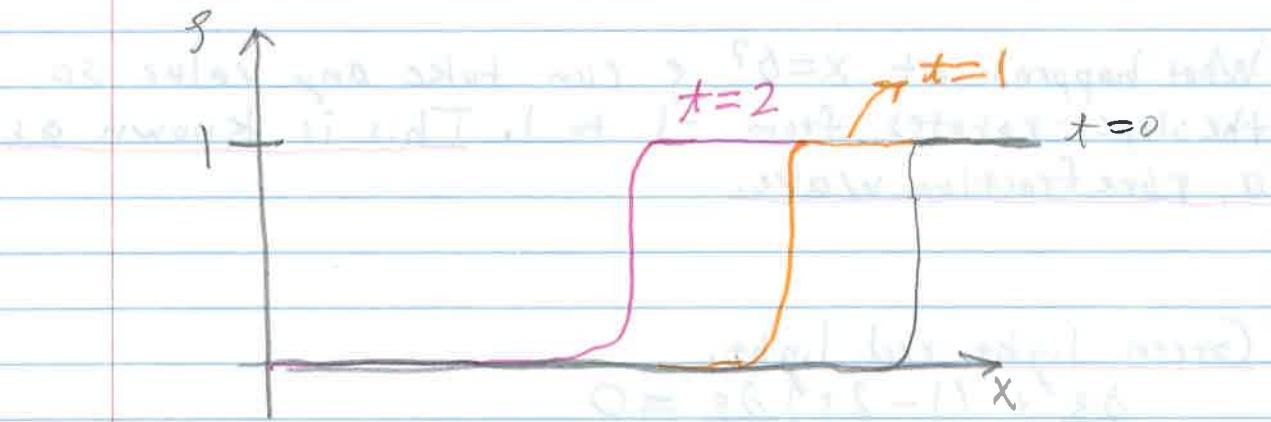
$$\frac{dx}{dt} = 1 - 2s, \quad \frac{ds}{dt} = 0$$

$$\Rightarrow x = (1 - 2s)t + x_0, \quad s = s_0$$

$$\text{or } t = \frac{1}{1 - 2s_0}x + t_0, \quad s = s_0$$



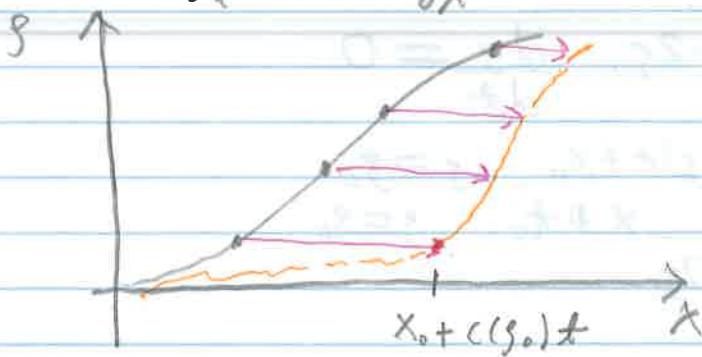
The characteristics intersect. How can we make sense of this?



Shock Waves.

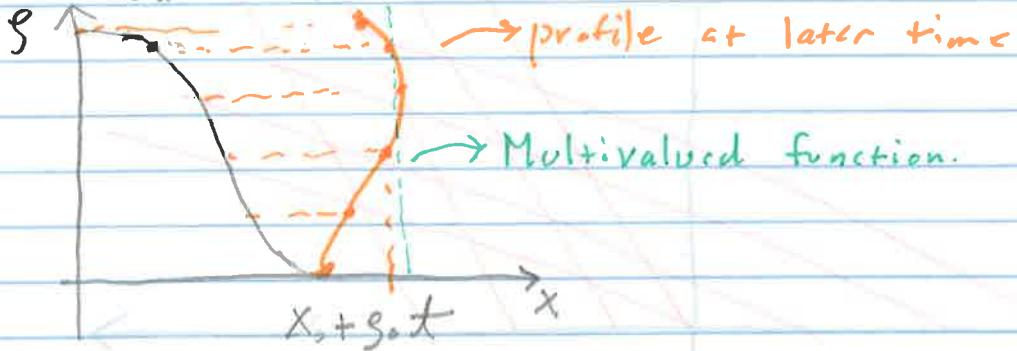
Consider the general P.D.E.

$$\frac{\partial s}{\partial t} + c(s) \frac{\partial s}{\partial x} = 0$$



Let's look at

$$\frac{\partial g}{\partial t} + g \frac{\partial g}{\partial x} = 0$$

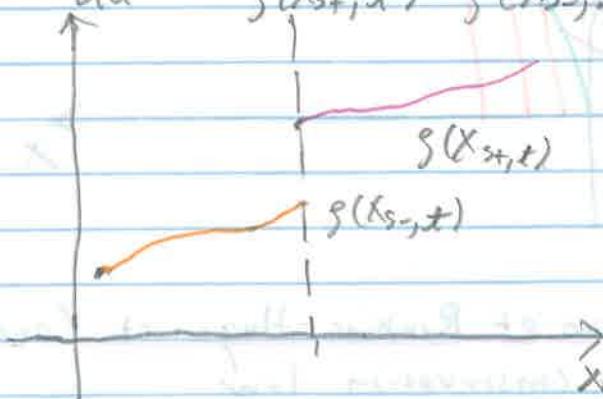


Physically, there cannot be a multivalued solution.

At a value $x_s(t)$ there should be a jump or a shock. Since g is conserved to the left and to the right of the shock we must have

$$g(x_{s-}, t) \left[v(x_{s-}, t) - \frac{dx_s}{dt} \right] = g(x_s, t) \left[v(x_s, t) - \frac{dx_s}{dt} \right]$$

$$\Rightarrow \frac{dx_s}{dt} = \frac{g(x_s, t) - g(x_{s-}, t)}{g(x_s, t) - g(x_{s-}, t)} = \frac{[g]}{[g]} \quad (\text{Rankine-Hugoniot condition})$$



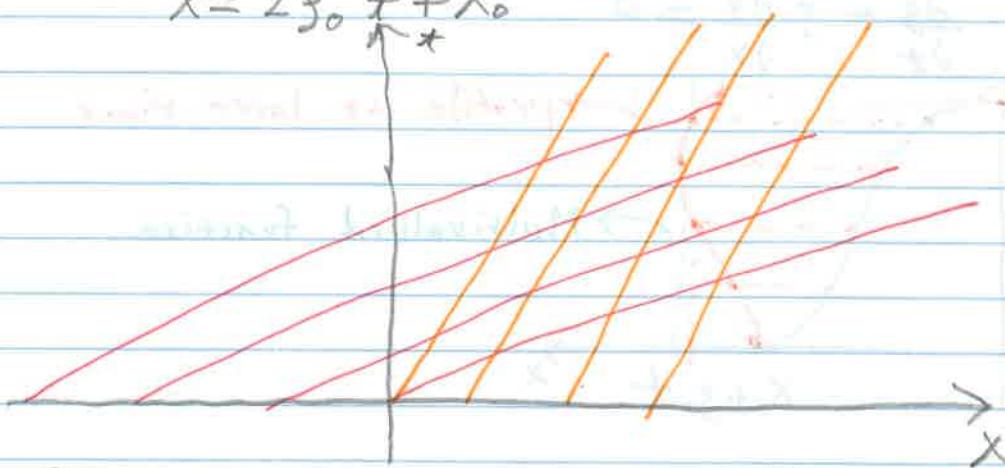
Example:

$$\frac{\partial g}{\partial t} + 2g \frac{\partial g}{\partial x} = 0$$

$$g(x, 0) = \begin{cases} 4, & x < 0 \\ 3, & x > 0 \end{cases}$$

The characteristics are:

$$x = 2s_0 t + x_0$$

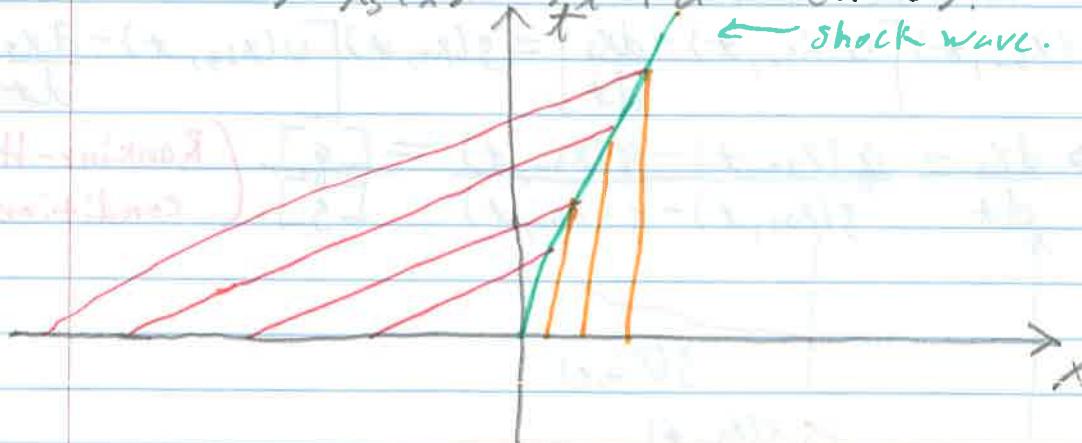


For our system we know $g'(s) = 2s \Rightarrow g(s) = s^2$.
The R-K-Hugoniot condition implies

$$\frac{dx_s}{dt} = \frac{g(4) - g(3)}{4 - 3} = 7$$

$$\Rightarrow x_s(t) = 7t + d \quad (d=0)$$

\leftarrow shock wave.



Alternate Derivation of Rankine-Hugoniot Condition.

We have the conservation law

$$\frac{d}{dt} \int_a^b g dx = g(a, t) - g(b, t)$$

Suppose we have a shock located at $x_s(t)$.

$$\frac{d}{dt} \left[\int_a^{x_s(t)} g(x, t) dx + \int_{x_s(t)}^b g(x, t) dx \right] = g(a, t) - g(b, t)$$

$$\Rightarrow \int_a^{x_s(t)} \frac{ds}{dt} dx + \frac{dx_s}{dt} g(x_s^-, t) + \int_{x_s(t)}^b \frac{ds}{dt} dx - \frac{dx_s}{dt} g(x_s^+, t) \\ = q(a, t) - q(b, t).$$

Now away from the shock

$$\frac{\partial g}{\partial t} = -\frac{\partial g}{\partial x}$$

$$\Rightarrow q(a, t) - q(x_s^-, t) + \frac{dx_s}{dt} g(x_s^-, t) + q(x_s^+, t) - q(b, t)$$

$$-\frac{dx_s}{dt} g(x_s^+, t) = q(a, t) - q(b, t)$$

$$\Rightarrow \frac{dx_s}{dt} = \frac{q(x_s^-, t) - q(x_s^+, t)}{g(x_s^-, t) - g(x_s^+, t)} \quad \begin{pmatrix} \text{Rankine-Hugoniot} \\ \text{Condition} \end{pmatrix}$$

Viscosity Solutions.

One point of view is that discontinuous solutions cannot describe reality. There must be some small effect that removes non-smoothness.

$$U_t + U U_x = \varepsilon U_{xx} \quad (\text{Burger's equation})$$

Conservation
law

Viscosity
(diffusion, friction, etc.)

Example

$$U(x, 0) = \begin{cases} 1, & x < 0 \\ 0, & x > 0 \end{cases}$$

Outer Solution:

$$U_t + U \cdot \partial_x U = 0$$

Characteristics:

$$\frac{dx}{dt} = U_0 \Rightarrow x(t) = U_0 t + C$$

$$\frac{dU_0}{dt} = 0 \Rightarrow U_0(t) = d.$$

We know the characteristics intersect. We must add an inner layer to correct non-second differentiability.

Let

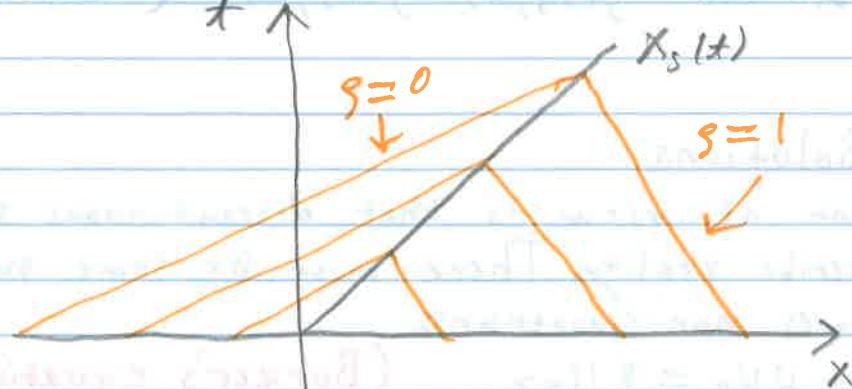
$$X = \frac{x - X_0(t)}{\varepsilon^\alpha} \Rightarrow \frac{d}{dt} = \frac{\partial X}{\partial t} \frac{d}{\partial X} + \frac{d}{\partial t}, \frac{d}{dx} = \frac{\partial X}{\partial x} \frac{d}{\partial X}$$

$$\frac{\partial}{\partial t} U_0 - \varepsilon^{-\alpha} s'(t) \frac{\partial}{\partial x} U_0 + \varepsilon^{-\alpha} U_0 \frac{\partial}{\partial x} U_0 = \varepsilon^{1-2\alpha} \frac{\partial^2}{\partial x^2} U_0$$

Letting $\alpha = 1$ we obtain:

$$-s'(t) \frac{\partial U_0}{\partial X} + U_0 \frac{\partial}{\partial X} = \frac{\partial^2 U_0}{\partial X^2}$$

$$\Rightarrow -s'(t) U_0 + \frac{1}{2} U_0^2 = \frac{\partial U_0}{\partial X} + A(t)$$



$$\lim_{X \rightarrow -\infty} U_0 = 0 \quad \text{and} \quad \lim_{X \rightarrow \infty} U_0 = 1$$

$$\Rightarrow 0 = A(t)$$

$$-s'(t) + \frac{1}{2} = 0$$

$$\Rightarrow s'(t) = \frac{1}{2}, \quad (\text{Rankine Hugoniot Condition})$$

$$\Rightarrow s(t) = \frac{1}{2}t$$

So we now need to solve:

$$\frac{1}{2} U_0 + \frac{1}{2} U_0^2 = \frac{\partial U_0}{\partial X}$$

$$\Rightarrow U_0(X, t) = \frac{1}{1 + B(t) e^{-X/2}}$$

$B(t)$ has to be determined at $O(\epsilon)$