

Homework #3.

#3.4.12

Construct an example in which the system $\dot{x} = f(x, r)$ has no fixed points for $r < 0$ and four branches for $r > 0$.

Solution:

$$\dot{x} = r + (x-1)^2(x+1)^2 \text{ works.}$$

#3.5.8

Show that the equation $\dot{u} = au + bu^3 - cu^5$ can be rewritten as $\frac{dx}{d\tau} = rx + x^3 - x^5$.

Solution:

Let $\tau = \alpha t$ and $x = \beta u$ where α, β are to be selected later. Computing we have that

$$\frac{du}{dt} = \frac{d\tau}{dt} \frac{du}{d\tau} = \frac{\alpha}{\beta} \frac{dx}{d\tau}$$

Therefore,

$$\frac{\alpha}{\beta} \frac{dx}{d\tau} = \frac{a}{\beta} x + \frac{b}{\beta^3} x^3 - \frac{c}{\beta^5} x^5$$

$$\Rightarrow \frac{dx}{d\tau} = \frac{a}{\alpha} x + \frac{b\beta^{2/3}}{\alpha} x^3 - \frac{c\beta^{4/5}}{\alpha} x^5$$

Consequently, if we set

$$\frac{b\beta^{2/3}}{\alpha} = 1 \text{ and } \frac{c\beta^{4/5}}{\alpha} = 1$$

$$\Rightarrow c\beta^{4/5} = b\beta^{2/3} \text{ and } \alpha = c\beta^{4/5}$$

$$\Rightarrow \beta^{2/15} = \frac{b}{c} \text{ and } \alpha = c\beta^{4/5}$$

$$\Rightarrow \beta = \left(\frac{b}{c}\right)^{15/2} \text{ and } \alpha = \frac{b^6}{c^5}$$

then

$$\frac{dx}{d\tau} = rx + x^3 - x^5$$

With

$$r = \frac{ac^5}{b^6}$$

#3.7.5.

Consider the system

$$\dot{g} = K_1 s_0 - K_2 g + \frac{K_3 g^2}{K_4 + g^2}$$

a.) Show the system can be put in the dimensionless form

$$\frac{dx}{d\tau} = s - rx + \frac{x^2}{1+x^2}$$

Solution:

Let $\tau = \alpha t$ and $g = \beta X$. Then,

$$\frac{dg}{dt} = \alpha \beta \frac{dX}{d\tau} = K_1 s_0 - K_2 \beta X + \frac{K_3 \beta^2 X^2}{K_4 + \beta^2 X^2}$$

$$\Rightarrow \frac{dX}{d\tau} = \frac{K_1 s_0}{\alpha \beta} - \frac{K_2 X}{\alpha} + \frac{K_3 \beta X^2}{\alpha (K_4 + \beta^2 X^2)}$$

$$= \frac{K_1 s_0}{\alpha \beta} - \frac{K_2 X}{\alpha} + \frac{K_3}{\alpha \beta} \cdot \frac{X^2}{(K_4/\beta^2 + X^2)}$$

Set

$$\frac{K_1 s_0}{\alpha \beta} = 1 \text{ and } \frac{K_4}{\beta^2} = 1$$

$$\Rightarrow \beta = K_4 \text{ and } \alpha = \frac{K_3}{K_4}$$

In these units

$$\frac{dx}{d\tau} = s - rx + \frac{x^2}{1+x^2}$$

where

$$s = \frac{K_1 s_0}{K_3} \text{ and } r = \frac{K_2}{K_3}$$

b.) Show that if $s=0$ there are two fixed points if $r < r_c$.

Solution:

If $s=0$ the system is given by:

$$\frac{dx}{dt} = x(-r + \frac{x}{1+x^2}) = f(x)$$

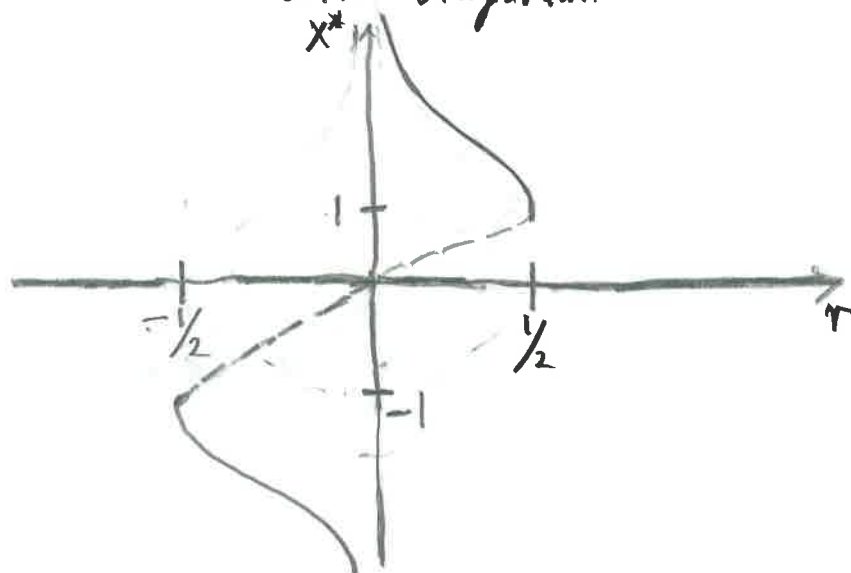
Fixed points are then given by

$$x=0 \text{ and } x = \frac{-r \pm \sqrt{r^2 - 4}}{2}$$

The condition that the other fixed point exists is then $\frac{1}{2} < r < \frac{1}{2}$.
The stability of the fixed point at the origin can be determined from:

$$f'(0) = -r,$$

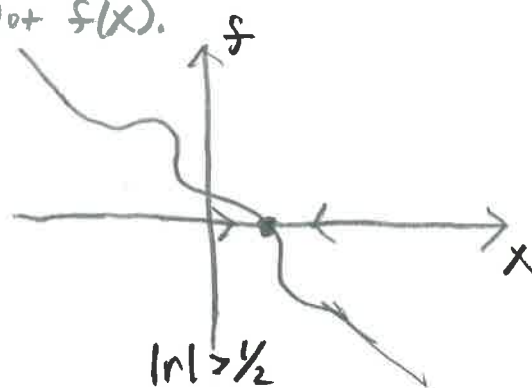
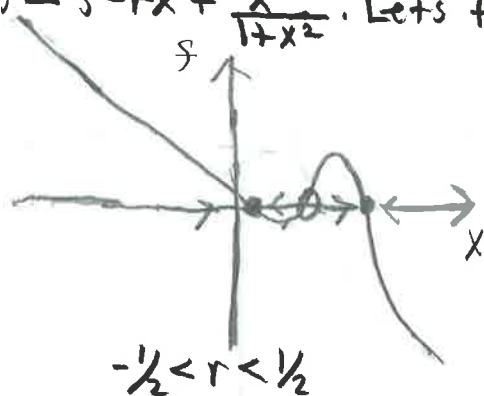
i.e. 0 is always stable which implies the other fixed points are unstable.
Below is a bifurcation diagram.



c.) What happens if $g(0)=0$ and $s = \epsilon < 1$ and then s suddenly becomes zero. Does the gene turn off?

Solution:

Let $f(x) = s - rx + \frac{x^2}{1+x^2}$. Let's first plot $f(x)$.



Consequently, if $-\frac{1}{2} < r < \frac{1}{2}$ the gene may not return. In particular if $S > (r - \sqrt{\frac{1}{r^2} - 4})/2$ then we expect the system to shift equilibrium to the fixed point $X = (1/r + \sqrt{1/r^2 - 4})/2$.

#4.3.6

On S^1 draw the phase portrait for $\dot{\theta} = \nu + \sin(\theta) + \cos(2\theta)$ and classify bifurcations that occur as ν is varied.

Solution:

$$\dot{\theta} = \nu + \sin(\theta) + \cos(2\theta) = \nu + \sin(\theta) + 1 - 2\sin^2(\theta)$$

Therefore, for $|w| < 2$ fixed points satisfy:

$$\begin{aligned} \sin(\theta) &= -\frac{1 \pm \sqrt{1 + 8(\nu + 1)}}{4} \\ &= -\frac{1 \pm \sqrt{9 + 8\nu}}{4} \end{aligned}$$

The further condition for the existence of the roots is then

$$\nu > -8/9$$

Consequently, for $-8/9 < \nu < 2$, we have four roots. However, we now need to check when these roots are in the interval $(-1, 1)$.

$$-1 < -\frac{1 \pm \sqrt{9 + 8\nu}}{4} < 1$$

$$\Rightarrow -5 < \pm \sqrt{9 + 8\nu} < 3$$

$$\Rightarrow 9 + 8\nu < 25 \text{ or } 9 + 8\nu < 9$$

$$\Rightarrow \nu < 2 \text{ or } \nu < 0$$

In summary:

1. If $\nu < -8/9$ or $\nu > 2$ then there are no fixed points.
2. If $-8/9 < \nu < 0$ there are four fixed points.
3. If $0 < \nu < 2$ there are two fixed points.

The phase portraits are as follows:



$$U < -\frac{8}{9}$$



$$-\frac{8}{9} < U < 0$$



$$0 < U < 2$$



$$2 < U$$

#4.4.1

Find the condition on the coefficients for which it is valid to approximate $mL^2\ddot{\theta} + b\dot{\theta} + mgL\sin\theta = \Gamma$ by the equation $b\dot{\theta} + mgL\sin\theta = \Gamma$.

Solution:

Let $\chi = \alpha t$. Then

$$mL^2\alpha^2 \frac{d^2\theta}{d\chi^2} + b\alpha \frac{d\theta}{d\chi} + mgL\sin\theta = \Gamma$$

$$\Rightarrow \frac{L^2\alpha^2}{gL} \frac{d^2\theta}{d\chi^2} + \frac{b\alpha}{mgL} \frac{d\theta}{d\chi} + \sin\theta = \frac{\Gamma}{mgL}$$

Set $\alpha = \frac{mgL}{b}$. Then the condition is that:

$$\frac{L^2}{gL} \left(\frac{mgL}{b}\right)^2 = \frac{L^3 \cdot g \cdot m^2}{b^2} \ll 1.$$

