

## Lecture II

In the last lecture we computed

$$\frac{d}{dt} \int_{\gamma(t)}^{\gamma(\gamma+t\psi\gamma)} k ds = - \int_{t=0}^t k \psi ds = - \int_0^t k ds < 0$$

If  $\psi = k$  then this is decreasing  
(and it is the fastest decreasing  
direction)

Def: The curve shortening flow  
is the deformation of a curve in the  
normal direction with a speed  
equal to its curvature.

More precisely, we consider

$$\gamma: I \times [0, \infty) \rightarrow \mathbb{R}^2$$

$$\frac{d\gamma}{dt} = k \nu = \gamma_{ss}$$

k is the  
signed  
curvature

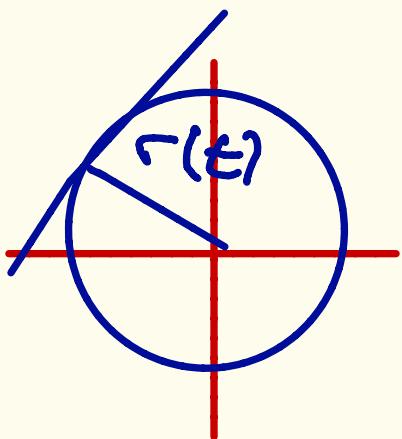
Remark: For each  $t$   $\gamma(t, \cdot)$  is  
a curve.

Example 1 :

$$\vec{r}(\theta, t)$$

Assume that  $\vec{r}(t) (\cos\theta, \sin\theta) = \vec{r}(\theta, t)$   
is a solution to curve shortening  
flow. Find  $r(t)$ .

$$\frac{d\theta}{dt} = r'(t) (\cos\theta, \sin\theta)$$



$$\delta K = \frac{1}{r(t)}$$

$$\gamma = -(\cos\theta, \sin\theta)$$

$$\Rightarrow r'(t) (\cos\theta, \sin\theta) = -\frac{1}{r} (\cos\theta, \sin\theta)$$

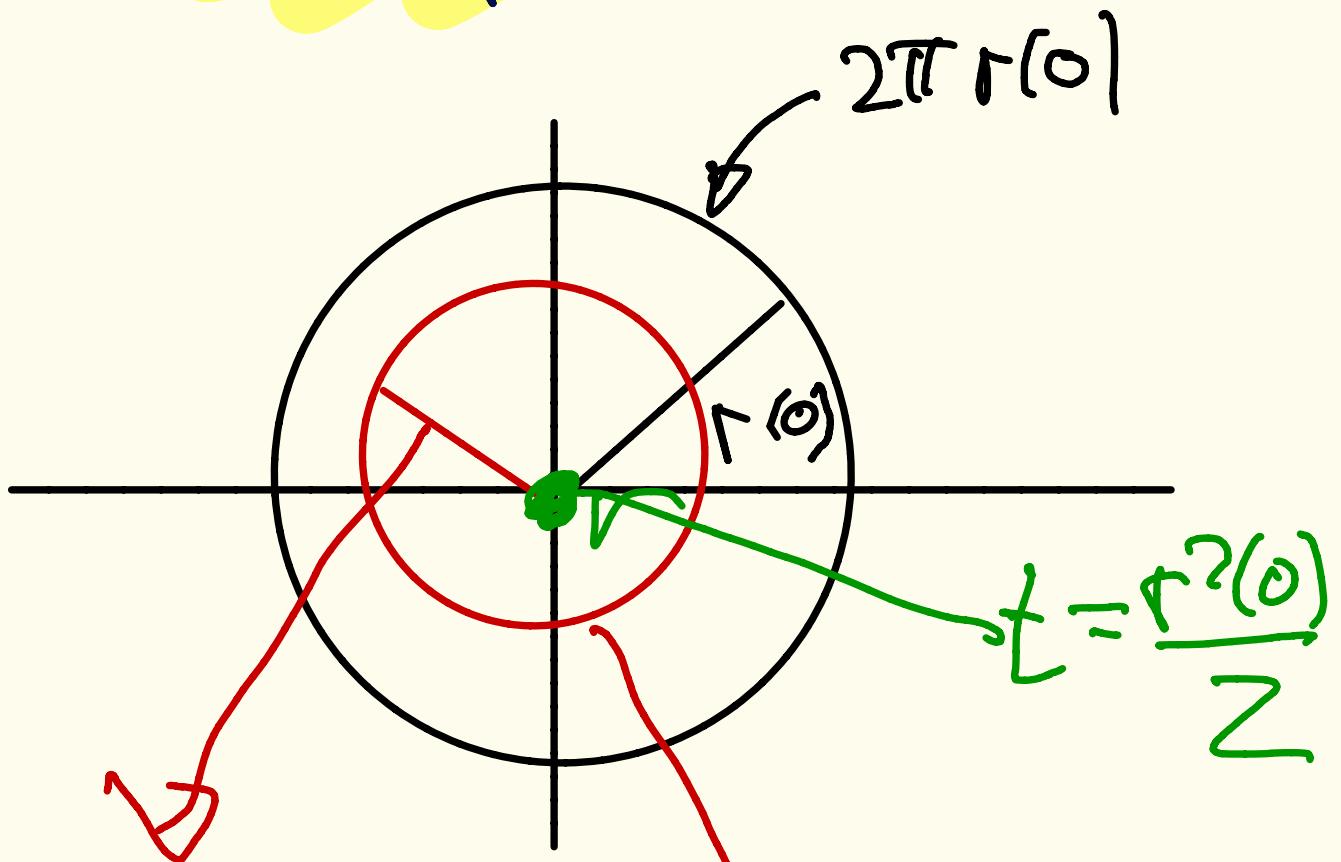
$$\Rightarrow (r^2)' = 2rr' = -2 / \int_0^{\theta} \{ d\sigma \}$$

$$\Rightarrow r^2(t) - r^2(0) = -2t$$

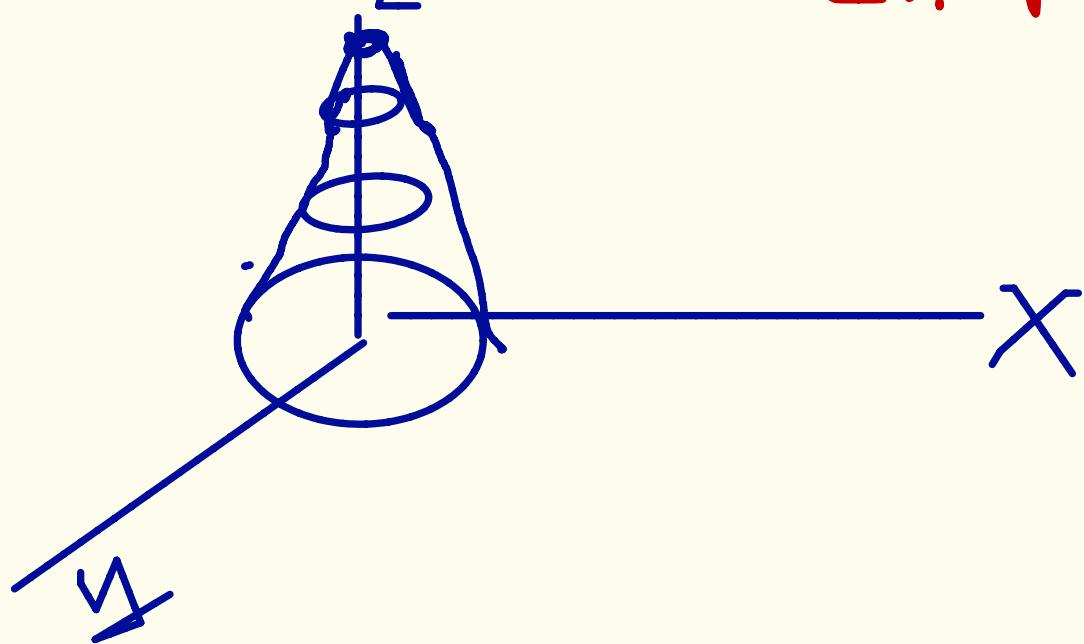
$$r(t) = \sqrt{r^2(0) - 2t}$$

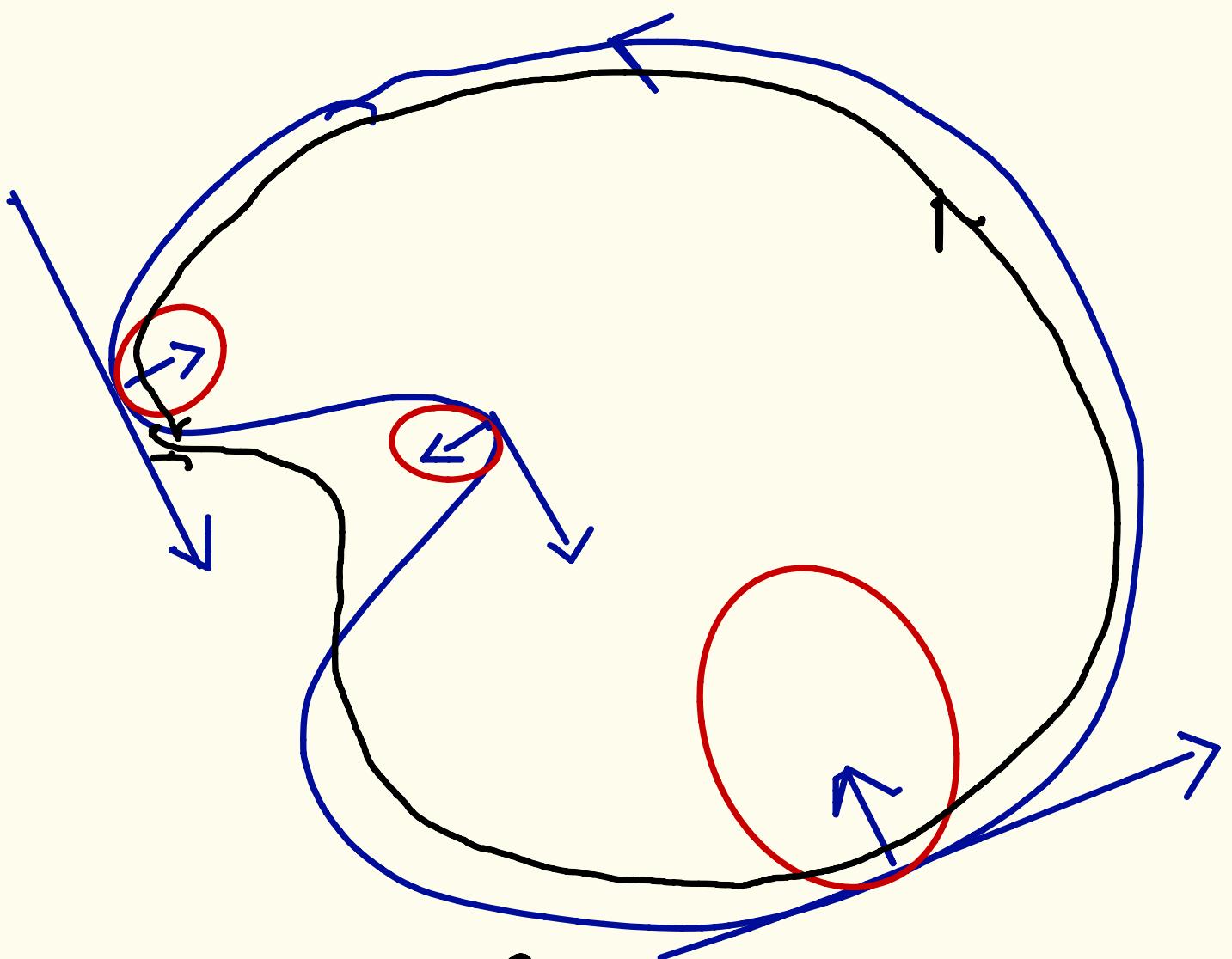
$$\Rightarrow \vec{r}(\theta, t) = \sqrt{r^2(0) - 2t} (\cos\theta, \sin\theta)$$

What does the previous example represent?

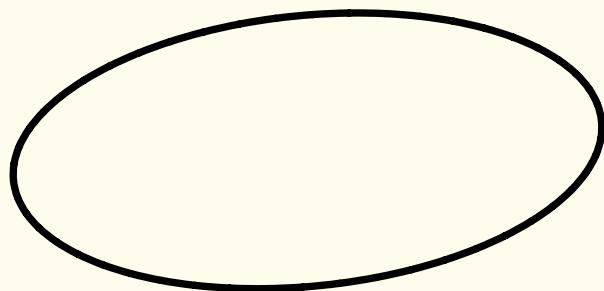


$$\sqrt{r^2(0)-2t} \rightarrow 2\pi r(t)$$

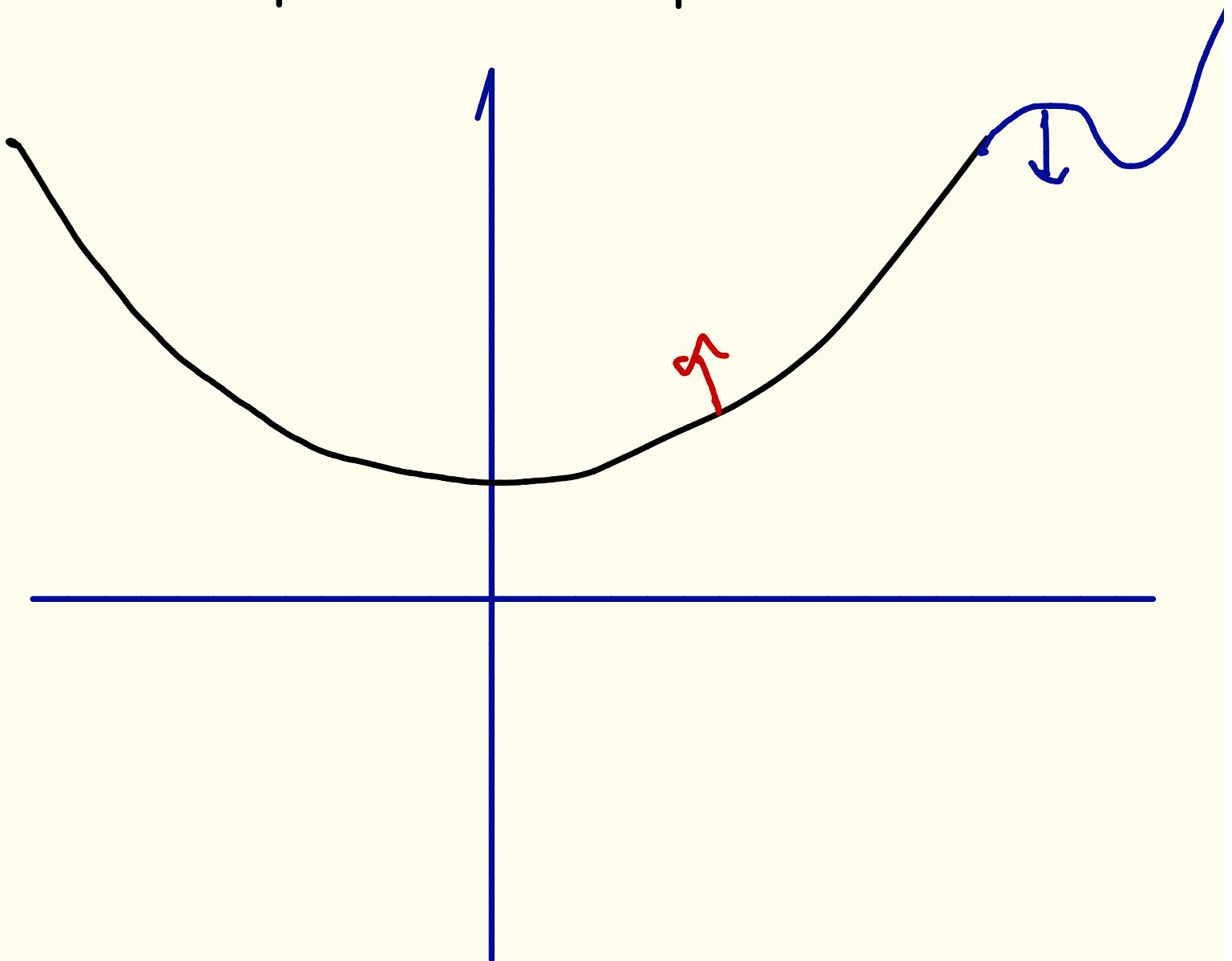
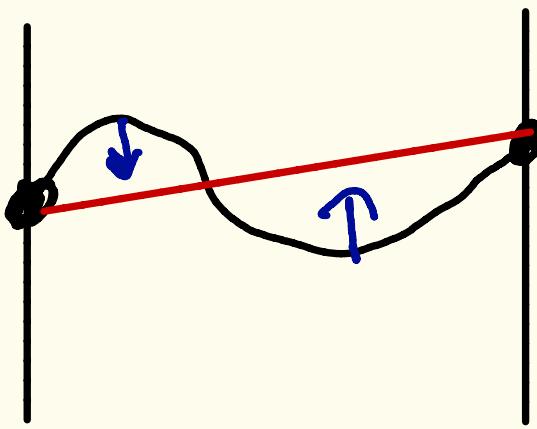




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Another example:

We look for a solution of the form  $(x, u(x) + \varphi) = \gamma(x, t)$

$$\frac{d\gamma}{dt} = (0, 1) \stackrel{x}{=} k \cdot \gamma / \cdot \gamma$$

$$\hookrightarrow (0, \frac{1}{x}) \cdot \gamma = k = \frac{u_{xx}}{(1+u_x^2)^{3/2}}$$

$$s(x) = \int |\partial_x(\lambda, t)| d\lambda$$

$$= \int_0^x |(1, u_x)| d\lambda = \int_0^x \sqrt{1+u_x^2} (\lambda, t) d\lambda$$

$$\frac{ds}{dx} = \sqrt{1+u_x^2} \cdot \frac{dx}{ds}$$

$$\stackrel{\text{chain rule}}{=} \left( \frac{d}{dx} \right)_0 \cdot \frac{dx}{ds}$$

$$\gamma_s(x, t) = \partial_x(x, t) \cdot \frac{dx}{ds} \stackrel{\text{chain rule}}{=}$$

$$= \frac{(1, u_x)}{\sqrt{1+u_x^2}} = \varphi \rightsquigarrow \gamma = \frac{(-u_x, 1)}{\sqrt{1+u_x^2}}$$

$$\gamma_{ss} = \left[ \frac{(0, u_{xx})}{\sqrt{1+u_x^2}} - \varphi \cdot \frac{u_{xx} u_x}{(1+u_x^2)} \right] \frac{dx}{ds} \rightsquigarrow K = \frac{\gamma_{ss} \cdot \gamma}{\frac{u_{xx}}{(1+u_x^2)^{3/2}}}$$

$$\frac{1}{\sqrt{1+U_x^2}} = \frac{U_{xx}}{(1+U_x^2)^{3/2}}$$

$$\Rightarrow \frac{U_{xx}}{1+U_x^2} = 1$$

$$\Rightarrow (\arctan U_x)_x = 1 \quad / \int dx$$

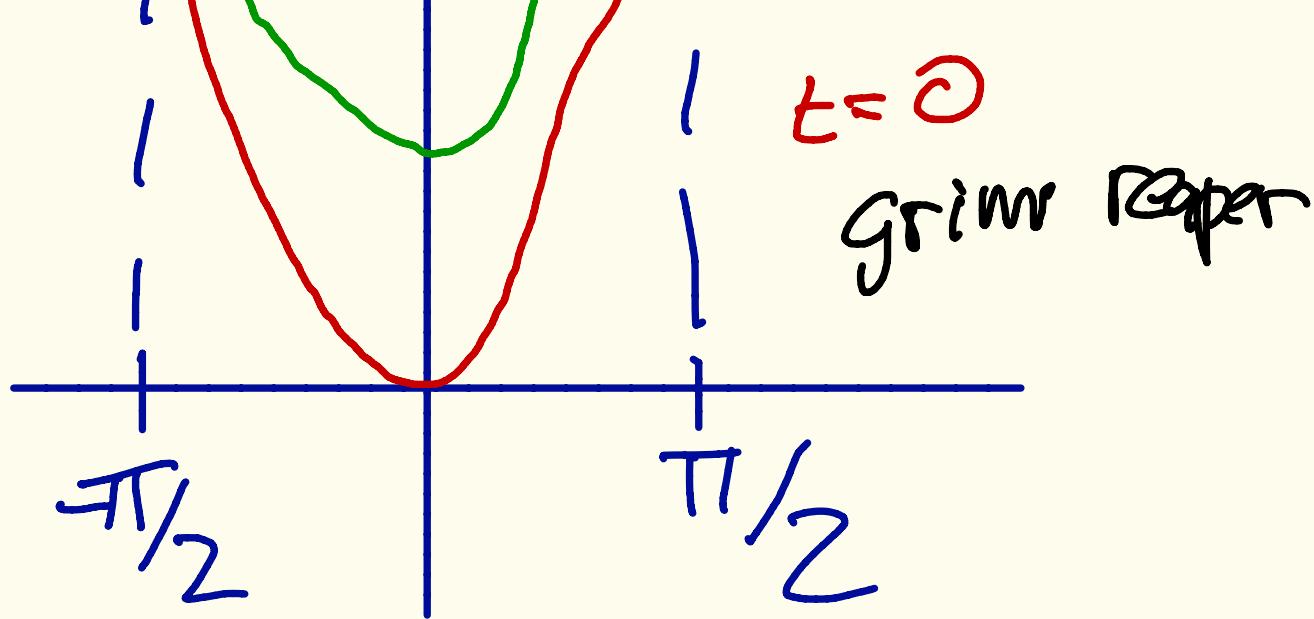
$$\arctan U_x = x$$

$$\Rightarrow \frac{du}{dx} = \tan x = \frac{\sin x}{\cos x}$$

$$u(x) = -\ln(\cos x)$$

$$\Rightarrow (x, -\ln(\cos x) + C)$$

$x \in (-\pi/2, \pi/2)$



# The maximum principle

- We change now the topic for a bit.

Assume that we have a solution to an ODE of the form

$$-af'' + bf' + c(x) = 0 \text{ for } x \in (0, l)$$

Assume  $a > 0$  and  $c > 0$ .

Claim:  $f$  does not have a  $\underset{x_0}{\text{maximum}}$  (minimum) in the interior

Proof: If  $f$  has a maximum at  $x_0$   
 $f'(x_0) = 0, f''(x_0) \leq 0$

$$0 < c(x_0) = -af''(x_0) + b\cancel{f'(x_0)} \leq 0$$

This contradicts that  $c > 0$

$\rightarrow \leftarrow //$

Remark: The same statement is true for the minimum if  $c < 0$

Claim: If  $f$  satisfies the same as before but  $c \geq 0$ , the same statements hold.

Idea of the proof:

Check the equation satisfied by  $f_\varepsilon = f(x) + \varepsilon e^{Lx}$

$$f'_\varepsilon(x) = f' + \varepsilon L e^{Lx}$$

$$f''_\varepsilon(x) = f'' + \varepsilon L^2 e^{Lx}$$

$$\begin{aligned} -a f''_\varepsilon + b f'_\varepsilon &= -a f'' + b f' + (\varepsilon L b - \varepsilon L^2 a) \\ &= \underbrace{-c}_{-c\varepsilon} + (\varepsilon L b - \varepsilon L^2 a) e^{Lx} \end{aligned}$$

Eligiendo  $L$  adecuado  $c\varepsilon > 0$

$\Rightarrow f_\varepsilon$  cumple las hipótesis del caso anterior  $f_\varepsilon(x) \leq \max\{f_\varepsilon(0), f_\varepsilon(H)\}$

$\leadsto$  we conclude by taking  $\varepsilon \rightarrow 0$

# An application of the maximum principle

Assume that  $f_1$  and  $f_2$  satisfy:

$$-af_i'' + bf_i' + c = 0 \text{ and } f_i(0) = f_i(1)$$

$$\text{Then: } f_1 \equiv f_2$$

Proof:

Check the equation satisfied

$$g = f_1 - f_2$$

$$g' = f_1' - f_2' ; g'' = f_1'' - f_2''$$

$$\begin{aligned} \text{so } -ag'' + bg' &= (-af_1'' + bf_1') - (-af_2'' + bf_2') \\ &= -c - (-c) = 0 \end{aligned}$$

$$g(0) = f_1(0) - f_2(0) = 0$$

$$g(1) = f_1(1) - f_2(1) = 0$$

$$\max g = 0 = \min g$$

$$\Rightarrow g \equiv 0 \Rightarrow f_1 = f_2 //$$

We will be interested in equations of the form

$$-af_{xx} + bf_x + c = f_t$$

Following the ideas before, we can define

$$\hat{f}(t) = \max_{x \in [0,1]} f(x, t)$$

If  $\hat{f}$  is regular enough we would have

$$c \leq \hat{f}_t \quad (\text{or } \hat{f} = f(1, t) \text{ or } \hat{f} = f(0, t))$$

In particular, if  $c \geq 0$ ,  $\hat{f}$  is increasing

Similarly we can define

$$\tilde{f} = \min_{x \in [0,1]} f(x, t)$$

and

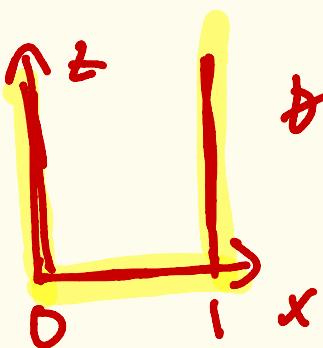
$$\tilde{f}_t \leq c \quad (\text{or } \tilde{f} = f(0, t) \text{ or } \tilde{f} = f(1, t))$$

If  $c \leq 0$ ,  $\tilde{f}$  is decreasing.

Then

$$\max_{x,z} f(x, t) = \max \left\{ \max_x f(x, 0), \max_t f(0, z), f(1, z) \right\}$$

Rem



this is usually  
called the  
parabolic boundary

Now we return to CSF:

Assume that  $(x, u_1(x,t))$  and  $(x, u_2(x,t))$  are solutions to CSF.

Assume in addition that

$$1) u_1(x,0) > u_2(x,0), \quad x \in [-1,1]$$

$$2) u_1(\pm 1,t) > u_2(\pm 1,t)$$

Then  $u_1(x,t) > u_2(x,t)$  for every  
 $x \in [-1,1]$   
and  $t \in [0,T)$

Exercise: Show that

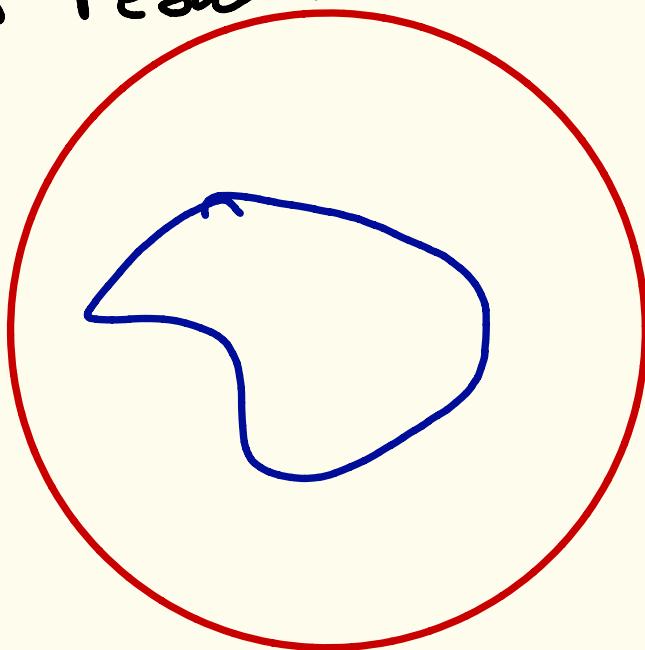
$$(u_i)_t = \frac{(u_i)_{xx}}{1 + (u_i)_x^2}$$

Proof:



Theorem If  $\gamma_1(x, t)$  and  $\gamma_2(x, t)$  are two bounded closed curves such that  $\gamma_1(x, 0) \cap \gamma_2(x, 0) = \emptyset$  Then  $\gamma_1(x, t) \cap \gamma_2(x, t) = \emptyset$  while the solutions are defined.

Proof : If they touch at some point, we can locally (after rotation and translation) write them as graphs and apply the previous result.



Corollary: If  $\gamma(x,t)$  is a compact (bounded) curve the solution can exist at most for a finite point.