1 1-D Wave Equation

$$u_{tt} = c^2 u_{xx} = 0 \tag{1.1}$$

for $x \in \mathbb{R}$ and t > 0 with u(x, 0) = f(x), $u_t(x, 0) = g(x)$. D'Alembert's formula:

$$u(x,t) = \frac{1}{2} \bigg[f(x+ct) + f(x-ct) + \frac{1}{c} \int_{x-ct}^{x+ct} g(y) dy \bigg].$$
$$u(A) + u(C) = u(B) + u(D).$$
(1.2)

Geometric identity:

$$A$$

$$B$$

$$C$$

$$x$$

Figure 1.1. Sketch for the geometric identity.

We have: C^2 solution of $(1.1) \Leftrightarrow (1.2)$ for every characteristic parallogram.

1.1 Boundary conditions

Good and bad boundary conditions:

$$0 = u_t + c \, u_x,$$

supposing c > 0.

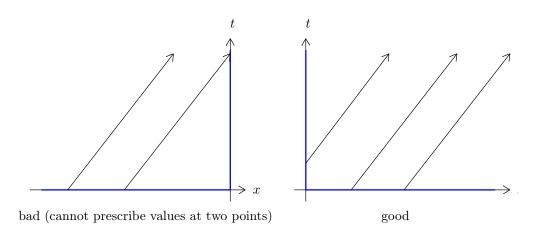


Figure 1.2. Good and bad boundary conditions for the transport equation.

Example:

$$u_{tt} - c^2 u_{xx} = 0, \quad x \in (0, \infty), t > 0$$

 $u(x,0) = f(x), u_t(x,0) = g(x)$ for $x \in \mathbb{R}$. u(0,t) = 0 for $t \ge 0$ with the assumption that f(0) = 0.

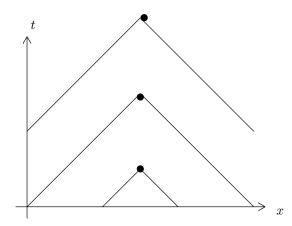


Figure 1.3. Domain of dependence.

The dependency on ICs outside of the domain is solved by the *method of reflection*. Extend u to all of \mathbb{R} , say \tilde{u} .

$$\begin{split} \tilde{u}(x,t) &= \frac{1}{2} \bigg[\, \tilde{f}(x+c\,t) + \tilde{f}(x-c\,t) + \frac{1}{c} \int_{x-ct}^{x+ct} \, \tilde{g}(y) \, dy \, \bigg] . \\ \\ \tilde{u}(0,t) &= \frac{1}{2} \bigg[\, \tilde{f}(c\,t) + \tilde{f}(c\,t) + \frac{1}{c} \int_{ct}^{ct} \, \tilde{g}(y) \, dy \, \bigg] . \\ \\ \\ \tilde{u}(x,t) &= \begin{cases} \, u(x,t) & x \ge 0, \\ - u(-x,t) & x < 0. \end{cases} \end{split}$$

Choose odd extension:

Similarly for
$$\tilde{f}$$
, \tilde{g} . Then $\tilde{u}(0,t) = 0 = u(0,t)$. $u(x,t) = \tilde{u}(x,t)$ for $x > 0$.

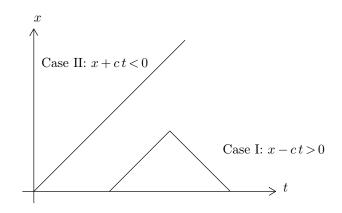


Figure 1.4. Different cases arising for the determination of the domain of dependence.

Case 1: D'Alembert as before. Case 2:

$$u(x,t) = \frac{1}{2} \left[f(x+ct) + \underbrace{f(ct-x)}_{\text{odd ext.}} + \frac{1}{c} \int_{ct-x}^{x+ct} g(y) \, dy \right].$$

If $g \equiv 0$, this corresponds to reflection as follows:

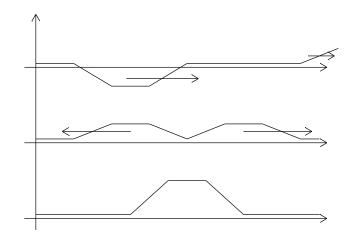


Figure 1.5. Series of snapshots of solutions with g = 0.

Initial boundary value problem:

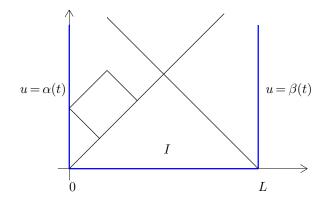


Figure 1.6. Initial boundary value problem. We can satisfy the parallelogram identity using geometry. For arbitrary α, β the equation need not have a continuous solution:

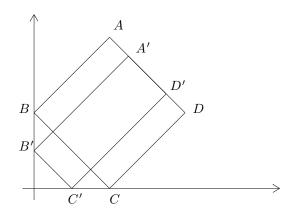


Figure 1.7. Discontinuous solutions in corners.

Assume $u \in C((0, L] \times (0, \infty))$.

$$u(B) = \alpha(B),$$

$$u(C) = f(C).$$

$$\begin{split} u(A) + u(C) &= u(B) + u(D). \ A \to D \Rightarrow u(A) \to u(D), \ u(C) &= u(B) \Rightarrow \lim_{t \to 0} \alpha(t) = \lim_{x \to 0} f(x). \ \text{Similarly,} \\ \text{if we want } u \in C^1, \text{ this requires } \alpha'(0) &= g(0), \text{ etc.} \end{split}$$

1.2 Method of Spherical Means

$$\partial_t^2 u - c^2 \Delta u = 0$$

for all $x \in \mathbb{R}^n$ and t > 0 with

$$u(x,0) = f(x),$$

 $u_t(x,0) = g(x).$

If $h: \mathbb{R}^n \to \mathbb{R}$, let

$$M_h(x,r) = \frac{1}{\omega_n r^{n-1}} \int_{S(x,r)} h(y) dS_y$$
$$= \frac{1}{\omega_n} \int_{|\omega|=1} h(x+r\omega) dS_\omega.$$

Assume that h is continuous. Then

- 1. $\lim_{r\to 0} M_h(x,r) = h(x)$ for every $x \in \mathbb{R}^n$.
- 2. $M_h(x, r)$ is a continuous and even function.

If $h \in C^2(\mathbb{R}^n)$, then

$$\Delta_x M_h(x,r) = \frac{\partial^2}{\partial r^2} M_h + \frac{n-1}{r} \frac{\partial M_h}{\partial r}.$$

If you view M_h as a function $M_h: \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$ which is spherically symmetric, then the above equation states that the Laplacian in the first n variables equals the Laplacian in the second n. Spherical means of

$$\partial_t^2 u - c^2 \Delta_x u = 0.$$

Then

$$\partial_t^2 M_u - c^2 \Delta_x M_u = 0$$

and

$$\partial_t^2 M_u - \left[\frac{\partial^2}{\partial_r^2 M_u} + \frac{n-1}{r}\frac{\partial M_u}{\partial r}\right] = 0.$$

1.3 Wave equation in \mathbb{R}^n

$$\Box u := u_{tt} - c^2 \Delta u = 0 \tag{(*)}$$

for $x \in \mathbb{R}^n \times (0, \infty)$ with u = f and $u_t = g$ for $x \in \mathbb{R}^n$ and t = 0. Now do Fourier analysis: If $h \in L^1(\mathbb{R}^n)$, consider

$$\hat{h}(\xi) := \int_{\mathbb{R}^n} e^{-ix\xi} h(x) dx.$$

If we take the FT of (*), we get

$$\hat{u}_{t\,t} + c^2 |\xi|^2 \hat{u} = 0$$

for $\xi \in \mathbb{R}^n$ and t > 0, $\hat{u}(\xi, 0) = \hat{f}$, $\hat{u}(\xi, 0) = \hat{g}$. $\hat{u}(\xi, t) = A\cos(c|\xi|t) + B\sin(c|\xi|t)$. Use ICs to find

$$\hat{u}(\xi,t) = \hat{f}(\xi)\cos(c|\xi|t) + \hat{g}(\xi)\frac{\sin(c|\xi|t)}{c|\xi|}.$$

Analogous caclulation for heat equation:

$$u_t - u_{xx} = 0 \Rightarrow \hat{u}_t + |\xi|^2 \hat{u} = 0, \quad \hat{u}(\xi, 0) = \hat{f}$$

yields $\hat{u}(\xi, t) = e^{-|\xi|^2 t} \hat{f}(\xi)$. Then observe that multiplication becomes convolution.

Observe that

$$\cos(c|\xi|t) = \partial_t \left(\frac{\sin(c|\xi|t)}{c|\xi|}\right).$$

If we could find a k(x,t) such that

$$\frac{\sin(c|\xi|t)}{c|\xi|} = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-i\xi \cdot x} k(x,t) dx,$$

this would lead to a solution formula

$$u(x,t) = \int_{\mathbb{R}^n} k(x-y,t)g(y)dy + \partial_t \int_{\mathbb{R}^n} k(x-y,t)f(y)dy.$$

Suppose n = 1, we know that our solution formula must coincide with D'Alembert's formula

$$u(x,t) = \frac{1}{2} \bigg[f(x+ct) + f(x-ct) + \frac{1}{c} \int_{x-ct}^{x+ct} g(y) \, dy \bigg].$$

Here

$$k(x,t) = \frac{1}{2c} \mathbf{1}_{\{|x| \le ct\}},$$

$$\partial_t k(x,t) = \frac{1}{2} [\delta_{\{x=ct\}} + \delta_{\{x=-ct\}}].$$

Solution formula for n = 3:

Theorem 1.1. $u \in C^{\infty}(\mathbb{R}^3 \times \mathbb{R})$ is a solution to the wave equation with C^{∞} initial data f, g if and only if

$$u(x,t) = \int_{S(x,ct)} [t g(y) + f(y) + Df(y)(y-x)] dS_y.$$

Here,

$$k(x,t) = \frac{1}{4\pi c^2 t} \cdot dS_y |_{|x|=ct} = t \cdot \text{uniform measure on } \{|x|=ct\}.$$

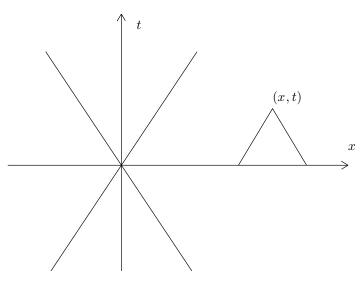


Figure 1.8.

1.4 Method of spherical means

Definition 1.2. Suppose $h: \mathbb{R}^n \to \mathbb{R}$ is continuous. Define $M_h: \mathbb{R}^n \times \mathbb{R} \to \mathbb{R}$ by

$$M_h(x,r) = \int_{S(x,r)} h(y) dS_y = \frac{1}{\omega_n} \int_{|\omega|=1} h(x+r\omega) \cdot d\omega.$$

Notice that

$$\lim_{r \to 0} M_h(x, r) = h(x)$$

if h is continuous.

Darboux's equation: Suppose $h \in C^2(\mathbb{R}^n)$. Then

$$\Delta_x M_h(x) = \frac{\partial^2}{\partial r} M_h + \frac{n-1}{r} \cdot \frac{\partial M_h}{r}.$$

Proof. Similar to the mean value property for Laplace's equation.

$$\begin{split} \int_0^r \Delta_x M_h(x,\rho)\rho^{n-1} \cdot d\rho &= \int_0^r \Delta_x \frac{1}{\omega_n} \int_{|\omega|=1} h(x+\rho\omega) \cdot d\omega \rho^{n-1} d\rho \\ &= \int_{B(0,r)} \Delta_x h(x+y) \cdot dy = \frac{1}{\omega_n} \int_{S(0,r)} \frac{\partial h}{\partial n_y}(x+y) dy \\ (y=r\omega, dy=r^{n-1}d\omega) &= \frac{1}{\omega_n} \int_{S(0,r)} Dh(x+y) \cdot n_y dy \\ &= \frac{r^{n-1}}{\omega_n} \int_{|\omega|=1} \frac{d}{dr} (h(x+r\omega) \cdot d\omega = r^{n-1} \frac{\partial M_h}{\partial r}. \end{split}$$

Then

$$\int_0^r \Delta_x M_h(x,\rho) \rho^{n-1} \cdot d\rho = r^{n-1} \frac{d}{dr} M_h.$$

Differentiate

$$\Delta_x M_h r^{n-1} = \frac{d}{dr} \left[r^{n-1} \cdot \frac{dM_h}{dr} \right]$$
$$= r^{n-1} \cdot \frac{d^2}{dr^2} + (n-1)r^{n-2} \frac{dM_h}{dr}.$$

Altogether

$$\Delta_x M_h = \frac{\partial^2 M_h}{\partial r^2} + \frac{(n-1)}{r} \frac{\partial M_h}{\partial r}.$$

Look at spherical means of (*):

$$u_{tt} - c^2 \Delta u = 0$$

Assume $u \in C^2(\mathbb{R}^n \times (0, \infty))$. Take spherical means:

$$M_{u_{tt}} = (M_u)_{tt},$$

which means

$$\partial_t^2 \oint_{S(x,r)} u(y,t) dS_y = \oint_{S(x,r)} \partial_t^2 u(y,t) dy,$$

$$(M_u)_{tt} = M_{u_{tt}}.$$

And

$$M_h(\Delta_x u) \stackrel{\text{Darboux}}{=} \frac{\partial^2 M_h}{\partial r^2} + (n-1) \frac{\partial M_h}{\partial r}.$$

Therefore, we have

$$(M_u)_{tt} = c^2 \left[\frac{\partial^2 M_h}{\partial r^2} + (n-1) \frac{\partial M_h}{\partial r} \right]$$

If n = 1, we can solve by D'Alembert. For n = 3:

$$\frac{\partial^2}{\partial r^2}(r M_h) = \frac{\partial}{\partial r} \left(r \frac{\partial M_h}{\partial r} + M_h \right) = r \frac{\partial^2 M_h}{\partial r^2} + 2 \cdot \frac{\partial M_h}{\partial r}$$

So if n=3, we have

$$(r M_u)_{tt} = c^2 \frac{\partial^2}{\partial r^2} (r M_h)$$

This is a 1D wave equation (in r!). Solve for $r M_h$ by D'Alembert.

$$M_{h}(x,r,t) = \frac{1}{2r} \left[(r+ct)M_{f}(x,r+ct) + \underbrace{(r-ct)}_{a}M_{f}(x,r-ct) \right] + \underbrace{\frac{1}{2cr} \int_{r-ct}^{r+ct} r'M_{g}(x,r')dr}_{b} + \underbrace{\frac{1}{2cr} \int_{r-ct}^{r+c$$

Pass to limit $r \rightarrow 0$ in b)

$$\frac{1}{2cr} \int_{r-ct}^{r+ct} r' M_g(x,r') dr' = \frac{1}{2cr} \int_{ct-r}^{ct+r} r' M_g(x,r') dr'$$

 M_g is even, $r M_g$ is odd. So

$$\begin{split} \lim_{r \to 0} \mathbf{b}) &= \frac{1}{c} \cdot c \, t \, M_g(x, c \, t) = t \, M_g(x, c \, t) \\ & t \, M_g(x, c \, t) = t \! \int_{|x-y|=ct} \! g(y) dS_y. \end{split}$$

Similarly, a): $(M_f \text{ even in } r)$

$$= \frac{1}{2}[M_f(x, r+ct) + M_f(x, ct-r)] + \frac{1}{2r}ct [M_f(x, ct+r) - M_f(x, ct-r)]$$
$$\lim_{r \to 0} * = M_f(x, ct) + ct \partial_2 M_f(x, ct) = \partial_t (t M_f(x, ct)).$$

For any $\varphi \in C^{\infty}(\mathbb{R}^3)$ define

$$(K_t * \varphi)(x) := t \int_{|x-y|=ct} \varphi(y) dS_y.$$

Then if $f, g \in C^{\infty}$, our solution to $\Box u = 0$ is

$$u(x,t) = (K_t * g)(x) + \partial_t (K_t * f)(x).$$

Aside: Check that

$$\int_{|y|=ct} e^{-i\xi \cdot y} dS_y = \frac{\operatorname{sinc}(ct|\xi|)}{c|\xi|}.$$

Remark 1.3. Huygens' principle:

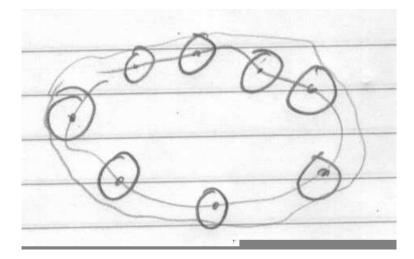


Figure 1.9. Huygens' principle.

We consider data f,g with compact support. Let

$$\Sigma(t) = \operatorname{supp}(u(x,t)) \subset \mathbb{R}^3,$$

where obviously

$$\Sigma(0) = \operatorname{supp}(f) \cup \operatorname{supp}(g).$$

Then Huygens' principle is stated as

$$\Sigma(t) \subset \{x: \operatorname{dist}(x,\Sigma(0)) = c\,t\}$$

Example 1.4. Consider radial data g and $f \equiv 0$.

$$u(x,t) = t \int_{|x-y|=ct} g(y) dS_y.$$
$$u(x,t) \neq 0 \Leftrightarrow S(x,ct) \cap B(0,\rho) \neq \emptyset$$

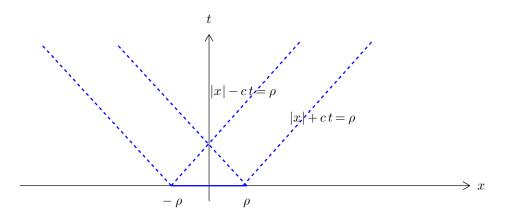


Figure 1.10. How radial data g spreads in time.

Focusing: Assume g = 0, f radial.

$$\begin{aligned} u(x,t) &= \partial_t (t \, M_f(x,ct)) = M_f(x,ct) + t \, \partial_t M_f(x,ct) \\ \partial_t M_f(x,ct) &= \partial_t \left(\int_{|x-y|=ct} f(y) dS_y \right) \\ &= \partial_t \left(\int_{|\omega|=1} f(x+ct\omega) d\omega \right) \\ &= \int_{|\omega|=1} Df(x+ct\omega) \cdot (c\omega) d\omega \\ &= c \int_{|\omega|=1} \frac{\partial f}{\partial n_\omega} (x+ct\omega) d\omega. \end{aligned}$$

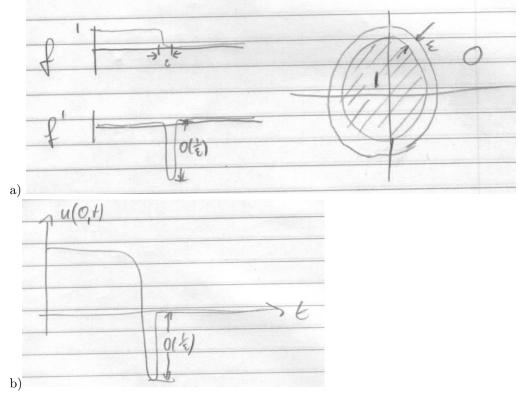


Figure 1.11. a) Spread of data with radial f. b) The sharp dropoff in u(0,t).

$$u(x,t) = \oint_{|x-y|=ct} f(y) \, dS_y + c t \oint_{|x-y|=ct} \frac{\partial f}{\partial n_y} dS_y.$$

Thus

$$||u(x,t)||_{\infty} \notin C ||u(x,0)||_{\infty}.$$

More precisely, there exists a sequence $u_0^{\varepsilon} \in C^{\infty}(\mathbb{R}^n)$ and t_{ε} such that

$$\lim_{\varepsilon \downarrow 0} \frac{\sup_x |u^{\varepsilon}(x, t_{\varepsilon})|}{\sup_x |u_0^{\varepsilon}(x)|} = +\infty.$$

Contrast with solution in n = 1:

$$||S(t)u_0||_{L^p} \leqslant ||u_0||_{L^p}, \quad 1 \leqslant p \leqslant \infty,$$

where S(t) is the shift operator. "=" solution to the wave equation.

Littman's Theorem $S_3(t) =$ solution operator for wave equation in \mathbb{R}^3 .

$$\sup_{f \in L^{p}(\mathbb{R}^{3})} \frac{\|S_{3}(t)u_{0}\|_{L^{p}}}{\|u_{0}\|_{L^{p}}} = +\infty$$

1.5 Hadamard's Method of Descent

Trick: Treat as 3-dimensional wave equation.

Notation: $x \in \mathbb{R}^2$, $\tilde{x} = (x, x_3) \in \mathbb{R}^3$. If $h: \mathbb{R}^2 \to \mathbb{R}$, define $\tilde{h}: \mathbb{R}^3 \to \mathbb{R}$ by $\tilde{h}(\tilde{x}) = \tilde{h}((x, x_3) = h(x)$. Suppose u solves $\partial_t^2 u - c^2 \Delta_x u = 0$ for $x \in \mathbb{R}^2$ and t > 0 with u(x, 0) = f(x) and $u_t(x, t) = g(x)$. Then

$$\partial_t^2 \tilde{u} - c^2 \Delta_{\tilde{x}} = 0$$

$$\tilde{u}(\tilde{x}, 0) = \tilde{f}(x)$$

$$\tilde{u}_t(\tilde{x}, 0) = \tilde{g}(x)$$

for $\tilde{x} \in \mathbb{R}^3$, t > 0.

$$\tilde{u}(\tilde{x}, \tilde{t}) = \partial_t (\tilde{K}_t * \tilde{f}) + \tilde{K}_t * \tilde{g}$$

where

$$\begin{split} \tilde{K}_t * \tilde{h} &= t \oint_{|\tilde{x} - \tilde{y}| = ct} \tilde{h}(y) dS_y \\ &= t \oint_{|\tilde{\omega}| = 1} \tilde{h}(x + ct\,\tilde{\omega}) d\,\tilde{\omega} \end{split}$$

with $\tilde{\omega} \in \mathbb{R}^3 = (\omega, \omega_3)$ for $\omega \in \mathbb{R}^2$. Then

$$h(\tilde{x} + ct\,\tilde{\omega}) = h(x + ct\,\omega).$$
$$\int_{|\tilde{\omega}|=1} h(x + ct\,\omega\,d\,\tilde{\omega}.$$
$$\omega_3 = \pm\sqrt{1 - |\omega|^2} = \pm\sqrt{1 - (\omega_1^2 + \omega_2^2)}.$$

Then

$$\frac{\partial \omega_3}{\partial \omega_i} = \frac{-\omega_i}{\sqrt{1 - |\omega|^2}}$$

for i = 1, 2. Thus the Jacobian is

 $\tilde{\omega} = (\omega, \omega_3)$. On $|\tilde{\omega}| = 1$, we have

$$\sqrt{1 + \left(\frac{\partial\omega_3}{\partial\omega_1}\right)^2 + \left(\frac{\partial\omega_3}{\partial\omega_2}\right)^2} = \frac{1}{\sqrt{1 - |\omega|^2}}.$$
$$h(x + ct\,\omega)d\tilde{\omega} = \frac{2t}{2}\int \frac{h(x + ct\,\omega)}{d\omega_1}d\omega_1$$

$$t \oint_{|\tilde{\omega}|=1} h(x+c\,t\,\omega)d\tilde{\omega} = \frac{2t}{4\pi} \int_{|\omega|\leqslant 1} \frac{h(x+c\,t\,\omega)}{\sqrt{1-|\omega|^2}} d\omega_1 d\omega_2.$$

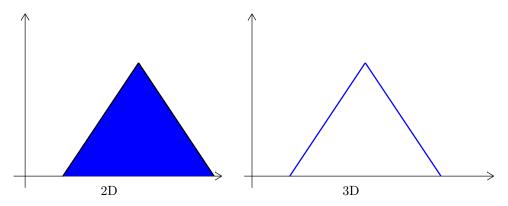


Figure 1.12. Domains of dependence, conceptually, for 2D and 3D.

1.6 Hadamard's Solution for all odd $n \ge 3$

[cf. Evans, 4.3?] n = 2k + 1, $k \ge 1$. k = (n - 1)/2, c = 1. The general formula is

$$u(x,t) = \partial_t (K_t * f) + K_t * g$$

where for any $h \in C_c^{\infty}$ we have

$$(K_t * h)(x) = \frac{\omega_n}{\pi^k 2^{k+1}} \left(\frac{1}{t} \cdot \frac{\partial}{\partial t}\right)^{(n-3)/2} \left[t^{n-2} f_{|x-y|=t} h(y) dS_y \right].$$

Check: If n=3, $\omega_n=4\pi$, so we get our usual formula.

Now, Consider $g \equiv 0$ in $u_{tt} - \Delta u = 0$, $x \in \mathbb{R}^{2k+1}$, t > 0, u(x, 0) = f(x), $u_t(x, 0) = 0$. Extend u to t < 0 by u(x, -t) = u(x, t) (which is OK because $\partial_t u = 0$ at t = 0)

Consider for t > 0

$$\begin{array}{lll} v(x,t) &:=& \displaystyle \frac{1}{(4\pi t)^{1/2}} \int_{\mathbb{R}} e^{-s^2/4t} u(x,s) ds \\ &=& \displaystyle \int_{\mathbb{R}} k(s,t) u(x,s) \, ds \end{array}$$

Find solution for the heat equation in 1D. Use that $\partial_t k = \partial_s^2 k$.

$$\begin{aligned} \partial_t v &= \int_{\mathbb{R}} \partial_t k \, u(x,s) ds \\ &= \int_{\mathbb{R}} k(s,t) \partial_s^2 u(x,s) ds \\ &= \int_{\mathbb{R}} k(s,t) \Delta_x u(x,s) ds = \Delta_x \int_{\mathbb{R}} k(s,t) u(x,s) ds. \end{aligned}$$

 $\partial_t v = \Delta_x v, \; x \in \mathbb{R}^n, \; t > 0.$ Also, as $t \to 0, \; v(x,t) \to f(x).$ Therefore,

$$\begin{aligned} v(x,t) &= \frac{1}{(4\pi t)^{n/2}} \int_{\mathbb{R}^n} e^{-|y|^2/4t} f(x-y) dy \\ &= \frac{1}{(4\pi t)^{n/2}} \int_0^\infty e^{-r^2/4t} r^{n-1} \oint f(x-r\omega) \cdot d\omega \, dr \\ &= \frac{\omega_n}{(4\pi t)^{n/2}} \int_0^\infty e^{-r^2/4t} r^{n-1} M_f(x,r) dr \end{aligned}$$

Change variables using $\lambda = 1/4t$ and equate (*) and (#) (what are * and #?)

$$\int_0^\infty e^{-\lambda r^2} u(x,r) dr = \frac{\omega_n}{2} \cdot \frac{1}{\pi^k} \int_0^\infty e^{-\lambda r^2} \lambda^k r^{n-1} M_f(x,r) dr$$

Then, use the Laplace transform for $h \in L^1(\mathbb{R}_+)$:

$$h^{\#}(\lambda) = \int_{0}^{\infty} e^{-\lambda \varphi} h(p) d\varphi.$$

Basic fact: $h^{\#}$ is invertible. Observe that

$$\frac{d}{dr}(e^{-\lambda r^2}) = -\lambda e^{-\lambda r^2}.$$

In particular,

$$\left(-\frac{1}{2r}\cdot\frac{d}{dr}\right)^k e^{-\lambda r^2} = \lambda^k e^{-\lambda r^2}.$$

Therefore

$$\begin{split} \int_0^\infty \lambda^k e^{-\lambda r^2} r^{n-1} M_f(x,r) dr &= \frac{(-1)^k}{2^k} \int_0^\infty \left(\frac{1}{r} \cdot \frac{d}{dr}\right)^k e^{-\lambda r^2} (r^{2k} M_f(x,r)) dr \\ &= \frac{1}{2^k} \int_0^\infty e^{-\lambda r^2} \left[r \cdot \left(\frac{1}{r} \cdot \frac{d}{dr}\right)^k (r^{2k-1} M_f(x,r)) \right] dr. \end{split}$$

Now have Laplace transforms on both sides, use uniqueness of the Laplace transform to find

$$u(x,t) = \frac{\omega_n}{\pi^{k} 2^{k+1}} t \left(\frac{1}{t} \cdot \frac{\partial}{\partial t}\right)^k \left[t^{n-2} M_f(x,t)\right]$$
$$= \frac{\omega_n}{\pi^{k} 2^{k+1}} t \left(\frac{1}{t} \cdot \frac{\partial}{\partial t}\right)^{(n-3)/2} \left[t^{n-2} M_f(x,t)\right]$$

2 Distributions

Let $U \subset \mathbb{R}^n$ be open.

Definition 2.1. The set of test functions D(U) is the set of $C_c^{\infty}(U)$ (C^{∞} with compact support). The topology on this set is given by $\varphi_k \to \varphi$ in D(U) iff

- a) there is a fixed compact set $F \subset U$ such that supp $\varphi_k \subset F$ for every k
- b) $\sup_F |\partial^{\alpha} \varphi_k \partial^{\alpha} \varphi| \to 0$ for every multi-index α .

Definition 2.2. A distribution is a continuous linear functional on D(U). We write $L \in D'(U)$ and (L, φ) .

Definition 2.3. [Convergence on D'] A sequence $L_k \xrightarrow{D'} L$ iff $(L_k, \varphi) \to (L, \varphi)$ for every test function φ .

Example 2.4. $L_{loc}^p(U) := \{f: U \to \mathbb{R}: f \text{ measurable}, \int_{U'} |f|^p dx < \infty \forall U' \subset \subset U \}.$ An example of this is $U = \mathbb{R}$ and $f(x) = e^{x^2}$.

We associate to every $f \in L^p_{loc}(U)$ a distribution L_f (here: $1 \leq p \leq \infty$).

$$(L_f, \varphi) := \int_U f(x) \varphi(x) dx$$

Suppose $\varphi_k \xrightarrow{D} \varphi$. Need to check

$$(L_f, \varphi_k) \to (L_f, \varphi).$$

Since $\operatorname{supp} \varphi_k \subset F \subset \subset U$, we have

$$\begin{aligned} \left| (L_f, \varphi_k) - (L_f, \varphi) \right| &= \left| \int_F f(x)(\varphi_k - \varphi(x)) dx \right| \\ &\leqslant \underbrace{\left(\int_F |f(x)| dx \right)}_{\text{bounded}} \underbrace{\sup_F |\varphi_k - \varphi|}_{\to 0}. \end{aligned}$$

If q > p,

$$\int_{F} |f(x)|^{p} dx \leq \left(\int_{F} 1 dx\right)^{1-p/q} \left(\int_{F} |f(x)|^{q}\right)^{1/q}$$

Thus, $L^q_{\text{loc}}(U) \subset L^p_{\text{loc}}(U)$ for every $p \leq q$. (*Note:* This is not true for $L^p(U)$.)

Example 2.5. If μ is a *Radon measure* on *U*, then we can define

$$(L_{\mu}, \varphi) = \int_{U} \varphi(x) \mu(dx).$$

Example 2.6. If $\mu = \delta_y$,

$$(L_{\mu},\varphi) = \varphi(y).$$

Definition 2.7. If L is a distribution, we define $\partial^{\alpha}L$ for every multi-index α by

$$(\partial^{\alpha}L,\varphi) := (-1)^{|\alpha|} (L,\partial^{\alpha}\varphi).$$

This definition is motivated through integration by parts, noting that the boundary terms do not matter since we are on a bounded domain.

Example 2.8. If L is generated by δ_0 ,

$$(\partial^{\alpha}L,\varphi) = (-1)^{\alpha}\partial^{\alpha}\varphi(0)$$

Theorem 2.9. $\partial^{\alpha}: D' \to D'$ is continuous. That is, if $L_k \xrightarrow{D} L$, then $\partial^{\alpha} L_k \xrightarrow{D} \partial^{\alpha} L$.

Proof. Fix $\varphi \in D(U)$. Consider

$$\begin{array}{rcl} (\partial^{\alpha}L_{k},\varphi) & \to & (\partial^{\alpha}L,\varphi) \\ & \parallel & \parallel \\ (-1)^{\alpha}(L_{k},\partial^{\alpha}\varphi) & \to & (-1)^{\alpha}(L,\partial^{\alpha}\varphi). \end{array}$$

Definition 2.10. Suppose P is a partial differential operator of order N, that is

$$P = \sum_{|\alpha| \leqslant N} c_{\alpha}(x) \partial^{\alpha}$$

with $c_{\alpha} \in C^{\infty}(U)$.

Example 2.11. $P = \Delta$ is an operator of order 2. $P = \partial_t - \Delta$. $P = \partial_t^2 - c^2 \Delta$.

Fundamental solution for Δ :

$$\Delta K(x-y) = \delta_y \quad \text{in } D'.$$

All this means is for every $\varphi \in D$

$$\int_U \Delta K(x-y)\varphi(x)dx = \int_U \varphi(x)\delta_y(dx) = \varphi(y)$$

Definition 2.12. We say that u solves Pu = 0 in D' iff

$$(u, P^{\dagger}\varphi) = 0$$

for every test function φ . Here, P^{\dagger} is the adjoint operator obtained through integration by parts: If $c_{\alpha}(x) = c_{\alpha}$ independent of x, then

$$P^{\dagger} = \sum_{|\alpha| \leqslant N} (-1)^{|\alpha|} c_{\alpha} \partial^{\alpha}.$$

Example 2.13. $P = \partial_t - D \Rightarrow P^{\dagger} = -\partial_t - \Delta$.

Example 2.14. More nontrivial examples of distributions:

1. Cauchy Principal Value (PV) on \mathbb{R} :

$$(L,v) := \lim_{\varepsilon \to 0} \int_{|x| \ge \varepsilon} \frac{\varphi(x)}{(x)} dx.$$
$$(L,\varphi) = \sum_{k=1}^{\infty} \left(\frac{d^k}{dx^k}\varphi\right) \left(\frac{1}{k}\right),$$

which is well-defined because φ has compact support.

Uniform convergence in topology?

 $2. \ U$

2.1 The Schwartz Class

Definition 2.15. $S(\mathbb{R}^n)$ Set $\varphi \in C^{\infty}(\mathbb{R}^n)$ with rapid decay:

$$\|\varphi\|_{\alpha,\beta} := \sup |x^{\alpha}\partial^{\beta}(x)| < \infty$$

for all multiindices α, β . Topology on this class: $\varphi_k \to \varphi$ on $\mathcal{S}(\mathbb{R}^n)$ iff $\|\varphi_k - \varphi\|_{\alpha,\beta} \to 0$ for all α, β .

Example 2.16. If $\varphi \in D(\mathbb{R}^n)$ then $\varphi \in \mathcal{S}(\mathbb{R}^n)$. If $\varphi_k \to \varphi$ in $D(\mathbb{R}^n) \Rightarrow \varphi_k \to \varphi$ in $\mathcal{S}(\mathbb{R}^n)$.

Example 2.17. $\varphi(x) = e^{-|x|^2}$ is in $\mathcal{S}(\mathbb{R}^n)$, but not in $D(\mathbb{R}^n)$.

$$\partial^{\beta} \varphi(x) = \underbrace{P_{\beta}(x)}_{\text{Polynomial}} e^{-|x|^2},$$

so $||x^{\alpha}\partial^{\beta}\varphi(x)||_{L^{\infty}(\mathbb{R}^{n})} < \infty.$

Example 2.18. $e^{-(1+|x|^2)^{\varepsilon}} \in \mathcal{S}(\mathbb{R}^n)$ for every $\varepsilon > 0$.

Example 2.19.

$$\frac{1}{(1+|x|^2)^N} \in C^\infty,$$

but not in $\mathcal{S}(\mathbb{R}^n)$ for any N. For example,

$$\sup_{x} \left| \frac{x^{\alpha}}{(1+|x|^2)^N} \right| = \infty$$

if $\alpha = (3N, 0, ..., 0)$.

We can define a *metric* on $\mathcal{S}(\mathbb{R}^n)$:

$$\rho(\varphi, \psi) = \sum_{k=0}^{\infty} \frac{1}{2^k} \sum_{|\alpha|+|\beta|=k} \frac{\|\varphi-\psi\|_{\alpha,\beta}}{1+\|\varphi-\psi\|_{\alpha,\beta}}.$$

Claim: $\varphi_k \to \varphi$ in $\mathcal{S}(\mathbb{R}^n) \Leftrightarrow \rho(\varphi_k, \varphi) \to 0$.

Theorem 2.20. $\mathcal{S}(\mathbb{R}^n)$ is a complete metric space.

Proof. Arzelà-Ascoli.

2.2 Fourier Transform

Motivation: For the wave equation, we find formally that

$$\mathcal{F}K_t = \frac{\sin c |\xi| t}{c |\xi|}.$$

Definition 2.21. The Fourier transform on $\mathcal{S}(\mathbb{R}^n)$ is given by

$$(\mathcal{F}\varphi)(\xi) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-ix\cdot\xi}\varphi(x)dx.$$

For brevity, also let $\hat{\varphi}(\xi) = (\mathcal{F}\varphi)(\xi)$.

Theorem 2.22. \mathcal{F} is an isomorphism of $\mathcal{S}(\mathbb{R}^n)$, and $\mathcal{FF}^* = \mathrm{Id}$, where

$$(\mathcal{F}^*\varphi)(\xi) = (\mathcal{F}\varphi)(-\xi).$$

2.2.1 Basic Estimates

$$\begin{aligned} |\hat{\varphi}(\xi)| &\leq \frac{1}{(2\pi)^{n/2}} \int |\varphi(x)| \mathrm{d}x \\ &= \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} (1+|x|)^{n+1} \frac{|\varphi(x)|}{(1+|x|)^{n+1}} \mathrm{d}x \\ &\leqslant C \| (1+|x|)^{n+1} \|_{\infty} < \infty. \end{aligned}$$

Also,

$$\partial_{\xi}^{\beta} \hat{\varphi}(\xi) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} \partial_{\xi}^{\beta} e^{-ix \cdot \beta} \varphi(x) dx$$
$$= \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} (-ix)^{\beta} e^{-ix \cdot \beta} \varphi(x) dx$$
$$\Rightarrow \|\partial_{\xi}^{\beta} \hat{\varphi}(\xi)\|_{L^{\infty}} \leqslant C \|(1+|x|)^{n+1} x^{\beta} \varphi\|_{L^{\infty}}.$$

Thus show $\hat{\varphi} \in C^{\infty}(\mathbb{R}^n)$:

$$(-i\xi)^{\alpha}\hat{\varphi}(\xi) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} (-i\xi)^{\alpha} e^{-ix\cdot\xi} \varphi(x) dx$$
$$= \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} \partial_x^{\alpha} (e^{-ix\cdot\xi}) \varphi(x) dx$$
$$= \frac{(-1)^{|\alpha|}}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-ix\cdot\xi} \partial_x^{\alpha} \varphi(x) dx$$
$$\Rightarrow \|\xi^{\alpha}\hat{\varphi}(\xi)\|_{L^{\infty}} \leqslant C \|(1+|x|)^{n+1} \partial_x^{\alpha}\varphi\|_{L^{\infty}}.$$

Combine both estimates to find

$$\|\hat{\varphi}\|_{\alpha,\beta} = \|\xi^{\alpha}\partial_{\xi}^{\beta}\hat{\varphi}\|_{L^{\infty}} \leqslant C\|(1+|x|)^{n+1}x^{\beta}\partial_{x}^{\alpha}\varphi\|_{L^{\infty}}$$

Example 2.23. If $\varphi(x) = e^{-|x|^2/2}$. Then $\hat{\varphi}(\xi) = e^{-|\xi|^2/2}$. $\mathcal{F}\varphi = \varphi$.

2.2.2 Symmetries and the Fourier Transform

1. Dilation: $(\sigma_{\lambda}\varphi)(x) = \varphi(x/\lambda)$.

$$\mathcal{F}(\varphi(x/\lambda))(\xi) = \frac{\lambda^n}{\mathbb{R}^n} \int_{\mathbb{R}^n} e^{-ix \cdot \xi} \varphi(x/\lambda) \mathrm{d}(x/\lambda) = \lambda^n (\mathcal{F}\varphi)(\xi\lambda).$$

Thus $\widehat{\sigma_{\lambda}\varphi} = \lambda^n \sigma_{1/\lambda} \hat{\varphi}$.

2. Translation $\tau_h \varphi(x) = \varphi(x-h)$ for $h \in \mathbb{R}^n$. $\mathcal{F}(\tau_h \varphi)(\xi) = e^{-ih \cdot \xi} \hat{\varphi}(\xi)$.

2.2.3 Inversion Formula

For every $\varphi \in \mathcal{S}(\mathbb{R}^n)$

$$\varphi(x) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{ix \cdot \xi} \hat{\varphi}(\xi) \mathrm{d}\xi$$

 $\varphi(x) = \mathcal{F}^* \hat{\varphi} = (\mathcal{RF})\hat{\varphi}, \text{ where } (\mathcal{R}\varphi)(x) = \varphi(-x).$

Proof. (of Schwartz's Theorem) Show $\mathcal{F}^*\mathcal{F}e^{-|x|^2/2} = e^{-|x|^2/2}$.

Extend to dilations and translations. Thus find $\mathcal{F}^*\mathcal{F} = \text{Id}$ on \mathcal{S} , because it is so on a dense subset. \mathcal{F} is 1-1, \mathcal{F}^* is onto \Rightarrow but $\mathcal{F}^* = \mathcal{RF}$, so the claim is proven.

Theorem 2.24. \mathcal{F} defines a continuous linear operator from $L^1(\mathbb{R}^n) \to L^\infty(\mathbb{R}^n)$, with

$$\|\hat{f}\|_{L^{\infty}} \leqslant \frac{1}{(2\pi)^n} \|f\|_{L^1}.$$

Theorem 2.25. \mathcal{F} defines an isometry of $L^2(\mathbb{R}^n)$.

Theorem 2.26. \mathcal{F} defines a continuous linear operator from $L^p(\mathbb{R}^n) \to L^{p'}(\mathbb{R}^n)$ with $1 \leq p \leq 2$ and

$$\frac{1}{p} + \frac{1}{p'} = 1.$$

Ideas:

- Show $\mathcal{S}(\mathbb{R}^n)$ dense in $L^p(\mathbb{R}^n)$ with $1 \leq p < \infty$.
- Extend \mathcal{F} from \mathcal{S} to L^p .

Proposition 2.27. $C_c^{\infty}(\mathbb{R}^n)$ is dense in $\mathcal{S}(\mathbb{R}^n)$.

Proof. Take a function

$$\eta_N(x) := \begin{cases} 1 & |x| \le N - 1, \\ 0 & |x| \ge N + 1. \end{cases}$$

Given $\varphi \in \mathcal{S}(\mathbb{R}^n)$, consider $\varphi_N := \varphi \eta_N$.

$$\partial^{\alpha}\varphi_n = \partial^{\alpha}(\varphi\eta_N) = \sum_{|\alpha'| \leqslant |\alpha|} \partial^{\alpha'}\varphi \partial^{\alpha-\alpha'}\eta_N.$$

So $||x^{\beta}\partial^{\alpha}\varphi_N||_{L^{\infty}} < \infty$.

Theorem 2.28. $C_c^{\infty}(\mathbb{R}^n)$ is dense in $L^p(\mathbb{R}^n)$ for $1 \leq p < \infty$.

Proof. By Mollification. Choose $\eta \in C_c^{\infty}(\mathbb{R}^n)$ with $\operatorname{supp}(\eta) \subset B(0,1)$ and

For any *n*, define
$$\eta_N(x) = N^n \eta(Nx)$$
. Then
$$\int_{\mathbb{R}^n} \eta_N(x) dx = 1.$$

To show:

$$f * \eta_N \xrightarrow{L^p} f$$

 $\int_{\mathbb{R}^n} \eta(x) \mathrm{d}x = 1.$

for any $f \in L^p(\mathbb{R}^n)$.

Step 1: Suppose $f(x) = \mathbf{1}_Q(x)$ for a rectangle Q. In this case, we know $\eta_N * f = f$ at any x with $\operatorname{dist}(x, \partial Q) \ge 1/N$. Therefore, $\eta_N * f \to f$ a.e. as $N \to \infty$.

$$\int_{\mathbb{R}^n} |\eta_N * f(x) - f(x)|^p \mathrm{d}x \to 0$$

by Dominated Convergence.

(Aside: Density of C_c^{∞} in $\mathcal{S}(\mathbb{R}^n)$. (Relation to Proposition 2.27?) Given $\varphi \in \mathcal{S}(\mathbb{R}^n)$, consider $\varphi_N := \varphi \eta_N$. We have $\|\varphi_N - \varphi\|_{\alpha,\beta} \to 0$ for every α, β . In particular, we have

$$\|(|x|^{n+1}+1)(\varphi_n-\varphi)\|_{L^{\infty}} \to 0.$$
$$\int_{\mathbb{R}^n} |\varphi_n-\varphi| \mathrm{d}x = \int_{\mathbb{R}} \frac{1+|x|^{n+1}}{(1+x)^{n+1}} |\varphi_n-\varphi| \mathrm{d}x \leqslant \left(\int_{\mathbb{R}} \frac{1}{1+|x|^{n+1}} \mathrm{d}x\right) ...?$$

End aside.)

Step 2: Step functions are dense in $L^p(\mathbb{R}^n)$ for $1 \leq p < \infty$.

Step 3: "Maximal inequality", i.e.

$$\|f*\eta_N\|_{L^p} \leqslant C \|f\| L^p,$$

which we obtain by Young's inequality.

$$\|f * \eta_N\|_{L^p} \leqslant C_p \|\eta_N\|_{L^1} \|f\|_{L^p} = C_p \|\eta\|_{L^1} \|f\|_{L^p},$$

where the constant depends on η , but not on N.

Step 4: Suppose $f \in L^p(\mathbb{R}^n)$. Pick g to be a step function such that $||f - g||_{L^p} < \varepsilon$ for $1 \leq p < \infty$. Then

$$\begin{split} \|f * \eta_N - f\|_{L^p} &\leqslant \|f * \eta_N - g * \eta_N\|_{L^p} + \|g * \eta_N - g\|_{L^p} + \|f - g\|_{L^p} \\ &\leqslant (C_p \|\eta\|_{L^1} + 1) \|f - g\|_{L^p} + \|g * \eta_N - g\|_{L^p}. \end{split}$$

Onwards to prove the L^2 isometry, we define

$$(f,g)_{L^2(\mathbb{R}^n)} := \int_{\mathbb{R}^n} f(x)\overline{g(x)} \mathrm{d}x.$$

Proposition 2.29. (Plancherel) Suppose $f, g \in \mathcal{S}(\mathbb{R}^n)$. Then

$$\left(\mathcal{F}\!f,\mathcal{F}\!g\right)_{L^2(\mathbb{R}^n)} \!=\! \left(f,g\right)_{L^2(\mathbb{R}^n)}$$

Proof.

$$(\mathcal{F}f, \mathcal{F}g)_{L^{2}(\mathbb{R}^{n})} \stackrel{\text{Definition}}{=} \int_{\mathbb{R}^{n}} \hat{f}(\xi)\overline{\hat{g}(\xi)} \mathrm{d}\xi$$

$$= \int_{\mathbb{R}^{n}} \bar{g}(x) \left(\frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^{n}} e^{ix \cdot \xi} \bar{f}(\xi) \mathrm{d}\xi\right) \mathrm{d}x$$

$$= \int_{\mathbb{R}^{n}} f(x) \bar{g}(x) dx.$$

Definition 2.30. $\mathcal{F}: L^1(\mathbb{R}^n) \to \dot{C}(\mathbb{R}^n)$ is the extension of $\mathcal{F}: \mathcal{S}(\mathbb{R}^n) \to \mathcal{S}(\mathbb{R}^n)$ to $L^1(\mathbb{R}^n)$, where

$$\dot{C}(\mathbb{R}^n) := \{h: \mathbb{R}^n \to \mathbb{R} \text{ such that } h(x) \to 0 \text{ as } |x| \to \infty \}.$$

Proposition 2.31. This extension is well-defined.

Proof. Suppose

$$\begin{array}{ccc} \varphi_k & \stackrel{L^1}{\to} & f \\ \psi_k & \stackrel{L^1}{\to} & f \end{array}$$

Then $\|\mathcal{F}\varphi_k - \mathcal{F}\psi_k\| \to 0$:

$$\begin{aligned} (\hat{\varphi}_{k} - \hat{\psi}_{k})(\xi) &| &= \left. \frac{1}{(2\pi)^{n/2}} \right| \int_{\mathbb{R}^{n}} e^{-ix \cdot \xi} (\varphi_{k} - \psi_{k}) \right| \\ &\leqslant \left. \frac{1}{(2\pi)^{n/2}} \|\varphi_{k} - \psi_{k}\|_{L^{1}} \\ &\leqslant \left. \frac{1}{(2\pi)^{n/2}} [\|\varphi_{k} - f\|_{L^{1}} + \|f - \psi_{k}\|_{L^{1}}] \to 0. \end{aligned}$$

Warning: There is something to be proved for $L^2(\mathbb{R}^n)$ because

$$\frac{1}{(2\pi)^{n/2}}\int \! e^{-ix\cdot\xi}f(x)\mathrm{d}x$$

is not defined when $f \in L^2(\mathbb{R}^n)$. However $\mathcal{F}f$ in the sense of L^2 -lim $\mathcal{F}\varphi_N$ where $\varphi_N \in \mathcal{S}(\mathbb{R}^n) \to f$ in L^2 . We had proven

$$\begin{split} \left\| \hat{f} \right\|_{L^{\infty}} &\leqslant \ \frac{1}{(2\pi)^{n/2}} \| f \|_{L^{1}}, \\ \left\| \hat{f} \right\|_{L^{2}} &= \ \| f \|_{L^{2}}. \end{split}$$

Definition 2.32. A linear operator $K: \mathcal{S}(\mathbb{R}^n) \to \mathcal{S}(\mathbb{R}^n)$ is of type (r, s) if

$$\|K\varphi\|_{L^s} \leqslant C(r,s) \|\varphi\|_{L^r}$$

Example 2.33. \mathcal{F} is of type $(1, \infty)$ and (2, 2).

Theorem 2.34. (Riesz-Thorin Convexity Theorem) Suppose K is of type (r_i, s_i) for i = 0, 1. Then K is of type (r, s) where

$$\frac{1}{r} = \frac{\theta}{r_0} + \frac{1-\theta}{r_1},$$
$$\frac{1}{s} = \frac{\theta}{s_0} + \frac{1-\theta}{s_1}$$
$$C(r,s) \leqslant C_0^{\theta} C_1^{1-\theta}.$$

for $0 \leq \theta \leq 1$. Moreover,

Proof. Yosida/Hadamard's 3-circle theorem (maximum principle).

Corollary 2.35. $\mathcal{F}: \mathcal{S} \to \mathcal{S}$ has a unique extension $\mathcal{F}: L^p(\mathbb{R}^n) \to L^{p'}(\mathbb{R}^n)$ where $1 \leq p \leq 2$ and 1/p' + 1/p = 1.

Summary:

- $\mathcal{F}: \mathcal{S} \to \mathcal{S}$ isomorphism
- $\mathcal{F}: L^1 \to \dot{C}$ (either by extension or directly) not an isomorphism
- $\mathcal{F}: L^2 \to L^2$ (by extension) isomorphism
- $\mathcal{F}: L^p \to L^{p'}$ (by interpolation)

Definition 2.36. $\mathcal{S}'(\mathbb{R}^n)$ is the space of continuous linear functionals on $\mathcal{S}(\mathbb{R}^n)$, called the space of tempered distributions. Its topology is given by $L_k \to L$ in \mathcal{S}' iff

$$(L_k, \varphi) \to (L, \varphi)$$

for all $\varphi \in \mathcal{S}$.

Altogether, we have $D \subset S \subset S' \subset D'$.

Example 2.37. 1. Suppose $f \in L^1$. Define a tempered distribution

$$(f,\varphi) := \int_{\mathbb{R}^n} f\varphi,$$

which is obviously continuous.

- 2. (A non-example) If $f(x) = e^{|x|^2}$, then $f \in L^1_{loc}$, so it defines a distribution, but not a tempered distribution.
- 3. $f(x) = e^{-|x|^2} \in \mathcal{S}(\mathbb{R}^n)$, but

4. If
$$f$$
 is such that

$$\int_{\mathbb{R}^n} V$$

 $\int f\varphi = \infty.$

$$\left\|\,(1+|x|^2)^{-\,M}\!f\,\right\|_{L^1}\!<\!\infty$$

for some M, then $f \in \mathcal{S}'$.

Proof.
$$|(f,\varphi)| = \left| \int f\varphi \right| \leq \left\| (1+|x|^2)^{-M} f \right\|_{L^1} \left\| (1+|x|^2)^M \varphi \right\|_{L^{\infty}}.$$

Proposition 2.38. Suppose $L \in S'$. Then there exists C > 0, $N \in \mathbb{N}$ such that

$$|(L,\varphi)| \leqslant C \|\varphi\|_{N} \tag{2.1}$$

for every $\varphi \in \mathcal{S}(\mathbb{R}^n)$, where

$$\|\varphi\|_N \! = \! \sum_{|\alpha|, |\beta| \leqslant N} \, \left\| x^\alpha \partial^\beta \varphi \right\|_{L^\infty} \! .$$

Corollary 2.39. A distribution $L \in D'$ defines a tempered distribution \Leftrightarrow there exist c, N such that (2.1) holds for $\varphi \in \mathcal{S}(\mathbb{R}^n)$.

Proof. Suppose (2.1) is not true. Then there exist φ_k , N_k such that

$$|(L,\varphi_k)| > k \|\varphi_k\|_{N_k}.$$

Let

Then

$$\left\|\psi_k\right\|_{N_k} = \frac{1}{k} \to 0.$$

 $\psi_k := \frac{\varphi_k}{\|\varphi_k\|_{N_k}} \cdot \frac{1}{k}.$

But $|(L, \psi_k)| > 1$. But $\psi_k \to 0$ in $\mathcal{S}(\mathbb{R}^n) \Rightarrow L$ not continuous.

Definition 2.40. If $K: S \to S$ is linear, continuous, then the transpose of K is the linear operator such that for every $L \in S'$

$$(L, K\varphi) = (K^t L, \varphi)$$

Theorem 2.41. a) $\mathcal{S}(\mathbb{R}^n)$ is dense in $\mathcal{S}'(\mathbb{R}^n)$.

b) $D(\mathbb{R}^n)$ is dense in $D'(\mathbb{R}^n)$.

Proof. Mollification, but first verify some properties. Fix $\eta \in D(\mathbb{R}^n)$,

$$\int_{\mathbb{R}^n} \eta = 1$$

Let $\eta_m(x) = m^n \eta(m x)$. We want to say $\eta_m * L$ is a C^{∞} function for a distribution L.

Definition 2.42. $L \in D'(\mathbb{R}^n), \eta \in D(\mathbb{R}^n), \eta * L$ is the distribution defined by

$$(\eta * L, \varphi) = (L, (R\eta) * \varphi),$$

where $R\eta(x) = \eta(-x)$. If L were a function f,

$$\begin{aligned} (\eta * L, \varphi) &= \int_{\mathbb{R}^n} (\eta * f)(x)\varphi(x)\mathrm{d}x \\ &= \int_{\mathbb{R}^n} \int_{\mathbb{R}^n} \eta(x-y)f(y)\mathrm{d}y\varphi(x)\mathrm{d}x \\ &= \int_{\mathbb{R}^n} \left(\int_{\mathbb{R}^n} \eta(x-y)\varphi(x)\mathrm{d}x\right)f(y) \\ &= \int_{\mathbb{R}^n} (R\eta * \varphi)(y)f(y)\mathrm{d}y. \end{aligned}$$

Theorem 2.43. $D(\mathbb{R}^n)$ is dense in $D'(\mathbb{R}^n)$. That is, if f is a distribution, then there exists a sequence of $L_k \in D$ such that $L_k \to L$ in D'.

Proof. By 1) Mollification and 2) Truncation.

Proposition 2.44. $L * \eta$ is a C^{∞} function. More precisely, $L * \eta$ is equivalent to the distribution defined by the C^{∞} function

$$\gamma(x) = (L, \tau_x(R\eta)),$$

where $\tau_x f(y) = f(y - x)$.

Proof. 1) $\gamma : \mathbb{R}^n \to \mathbb{R}$ is clear.

2) γ is continuous: If $x_k \to x$, then $\gamma(x_k) \to \gamma(x)$. Check

$$\gamma(x_k) = (L, \tau_{x_k}(R\eta)).$$

And $\tau_{x_k}(R\eta) \rightarrow \tau_x(R\eta)$ in D.

- We can choose F s.t. $\operatorname{supp}(\tau_{x_k}(R\eta)) \subset F$ for all k.
- $R\eta(y-x_k) \to R\eta(y-x),$
- $\partial^{\alpha}(R\eta)(y-x_k) \rightarrow \partial^{\alpha}R\eta(y-x),$

where the last two properties hold uniformly on F.

3) $\gamma \in C^1$: Use finite differences. Consider

$$\frac{\gamma(x+h\,e_j)-\gamma(x)}{h} = \left(L, \frac{\tau_{x+he_j}(R\eta)-\tau_x(R\eta)}{h}\right).$$
$$\frac{1}{h} \Big[\tau_{x+he_j}(R\eta)-\tau_x(R\eta)\Big] \to \tau_x(\partial_{x_j}R\eta)$$

Observe that

in
$$D$$
.

4) $\gamma \in C^{\infty}$: Induction.

5) Show that $L * \eta \stackrel{D'}{=} \gamma$. That is

$$(L*\eta,\varphi)^{\text{Def}}(L,R\eta*\varphi)^{?} = \int_{\mathbb{R}^{n}} \gamma(x)\varphi(x)dx.$$
$$\int_{\mathbb{R}^{n}} \gamma(x)\varphi(x)dx = \lim_{h \to 0} h^{-n} \sum_{\substack{y \in h\mathbb{Z}^{n} \\ y \in h\mathbb{Z}^{n}}} \gamma(y)\varphi(y)$$
$$= \lim_{h \to 0} h^{-n} \sum_{\substack{y \in h\mathbb{Z}^{n} \\ y \in h\mathbb{Z}^{n}}} (L,\tau_{y}(R\eta))\varphi(y)$$
$$= \lim_{h \to 0} \left(L,h^{-n} \sum_{\substack{y \in h\mathbb{Z}^{n} \\ y \in h\mathbb{Z}^{n}}} \tau_{y}(R\eta)\varphi(y)\right).$$

Show that the Riemann sum

$$h^{-n}\sum_{y\in h\mathbb{Z}^n}\,\tau_y(R\eta)\varphi(y)\,{\rightarrow}\,R\eta\ast\varphi$$

in D.

Operations with *:

1. $\eta * L := L * \eta$. 2. $\partial^{\alpha} (L * \eta) \stackrel{D'}{=} \partial^{\alpha} L * \eta \stackrel{D'}{=} L * \partial^{\alpha} \eta$.

Proof of Theorem: Fix $\eta \in D(\mathbb{R}^n)$ with $\int_{\mathbb{R}^n} \eta(x) dx = 1$. Let $\eta_m(x) = m^n \eta(m x)$. Then

$$\int_{\mathbb{R}^n} \eta_m(x) \,\mathrm{d}x = 1.$$

We know from our proposition from that $\eta_m * L$ is C^{∞} . Consider the cutoff function

$$\chi_m(x) := \begin{cases} 1 & |x| \leq m, \\ 0 & |x| > m. \end{cases}$$

Consider $L_m = \chi_m(\eta_m * L)$. $L_m \in D(\mathbb{R}^n)$.

$$\partial^{\alpha}(\chi_{m}\gamma_{m}) = \sum {\binom{\alpha}{\beta}} \partial^{\alpha-\beta}\chi_{m}\partial^{\alpha-\beta}\gamma_{m}$$

Claim: $L_m \rightarrow L$ in D'.

$$(L_m, \varphi) = (\chi_m(\eta_m * L), \varphi) = (\eta_m * L, \chi_m \varphi)$$

$$\stackrel{\text{Def}}{=} (L, (R\eta_m) * (\chi_m \varphi)).$$

Finally, show

$$(R\eta_m) * \varphi \stackrel{m \text{ large}}{=} (R\eta_m) * \chi_m \varphi \to \varphi \text{ in } D'$$

Definition 2.45. Suppose $K: S \to S$ is linear. We define $K^t: S' \to S'$ as the linear operator

$$(K^tL,\varphi) := (L,K\varphi).$$

Proposition 2.46. Suppose $K: S \to S$ is linear and continuous. Suppose that $K_t|_S$ is continuous. Then, there exists a unique, continuous extension of K^t to S'.

Corollary 2.47. $\mathcal{F}: \mathcal{S}' \to \mathcal{S}'$ is continuous.

Let's go back to PDE now. Examples:

- 1. $\mathcal{F}\delta = 1/(2\pi)^{n/2}$.
- 2. Let $0 < \beta < n$ and $C_{\beta} = \Gamma((n \beta)/2)$. Then $\mathcal{F}(C_{\beta}|x|^{-\beta}) = C_{n-\beta}|x|^{-(n-\beta)}$. Why we care: $\Delta u = \delta_0$. In Fourier space:

$$-|\xi|^{2}\hat{u} = \frac{1}{(2\pi)^{n/2}}$$

$$\Rightarrow \hat{u} = \frac{-1}{(2\pi)^{n/2}}|\xi|^{-2}.$$

$$\Rightarrow \mathcal{F}^{-1}\hat{u} = \frac{-1}{(2\pi)^{n/2}}\frac{C_{n-2}}{C_{2}}|x|^{2-n}.$$

1

Prove (1) and (2) by testing against Gaussians.

2.3 Duhamel's Principle

Consider constant coefficient linear PDE

$$\partial_t^m u + \partial_t^{m-1} \left(\sum_{|\alpha|=?1} c_{1,\alpha} \partial^\alpha \right) u + \partial_t^{m-2} \left(\sum_{|\alpha|=?2} c_{2,\alpha} \partial^\alpha \right) u + \dots + \sum_{|\alpha|\leqslant m} c_{m,\alpha} \partial^\alpha u = 0.$$

Here $u: \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$, *m* is the order of the equation, $c_{m,\alpha} \in \mathbb{R}$. Shorthand $P(D, \tau)u = 0$. Herre $D = (\partial_{\alpha_1}, ..., \partial_{\alpha_n})$ and $\tau = \partial_t$. Differentiation operators

$$P(D,\tau) = \tau^{m} + \tau^{m-1} P_1(D) + \dots + P_m(D).$$

 $P_k(D) =$ polynomial in D of order $\leq k$. General Problem:

$$P(D,\tau)u = \omega$$

for $x \in \mathbb{R}^n$, t > 0 with

$$u = f_0$$

$$\partial_t u = \tau u = f_1$$

$$\vdots \qquad \vdots$$

$$\partial_t^{m-1} u = \tau^{m-1} u = f_{m-1}$$

at t = 0.

Standard Problem:

$$P(D,\tau)u=0$$

with

$$u = 0$$

$$\partial_t u = \tau u = 0$$

$$\vdots \qquad \vdots$$

$$\partial_t^{m-1} u = \tau^{m-1} u = g$$

at t = 0. (Initial conditions). Solution of General Problem from Standard Problem. First, suppose $\omega \neq 0$ and $f_0 = f_1 = \cdots = f_{m-1} = 0$.

Consider the solution to a family of standard problems:

$$\begin{array}{rcl} P(D,\tau)U(x,t,s) &=& 0 & (s\leqslant t) \\ \tau^{m-1}U(x,t,s) &=& \omega(x,s) & (t=s) \\ \tau^k U(x,t,s) &=& 0 & (t=s,0\leqslant k\leqslant m-2) \end{array}$$

Consider

$$u(x,t) = \int_0^t U(x,t,s) \mathrm{d}s.$$

This gives us

$$\begin{split} P(D,z)u(x,t) &= \int_0^t P(D,\tau)U(x,t,s)\mathrm{d}s + (\tau^{m-1} + \tau^{m-2}P_1(D) + \dots + P_{n-1}(D))U(x,t,t) \\ &= 0 + \omega(x,t) + 0 \end{split}$$

as desired. Similarly, getting rid of non-standard initial conditions involves consideration of

$$P(D,\tau) = 0$$

$$u = f_0$$

$$\tau u = f_1$$

$$\vdots \qquad \vdots$$

$$\tau^{m-1}u = f_{m-1}$$

Let u_g denote the solution to the standard problem. Consider

 $u = u_{f_{m-1}} + (\tau + P_1(D))u_{f_{m-2}} + (\tau^2 + P_1(D)\tau + P_2(D))u_{f_{m-3}} + \dots + (\tau^{m-1} + P_1(D)\tau^{m-2} + \dots + P_{m-1}(D))u_{f_0}.$

Then

$$P(D,\tau)u = P(D,\tau)u_{f_{m-1}} + (\tau + P_1(D))P(D,\tau)u_{f_{m-2}} + \cdots$$

= 0

since $P(D, \tau)u_{f_k} = 0$ for $0 \le k \le m - 1$. We need to check the initial conditions: At t = 0, $\tau^l u_{f_k} = 0$, $0 \le l \le m - 2$. Thus, all terms except the last one are 0. The last term is

$$\left[\tau^{m-1} + P_1(D)\tau^{m-2} + \dots + P_{n-1}(D)\right]u_{f_0} = \tau^{m-1}u_{f_0} + \text{time derivatives of order } \leqslant m-2 \ (=0) = f_0.$$

Henceforth, only consider the standard problem

$$\begin{array}{rcl} P(D,\tau) &=& 0,\\ \tau^k u(x,0) &=& 0 & (0 \leqslant k \leqslant m-2),\\ \tau^{m-1} u(x,0) &=& g. \end{array}$$

Solve by Fourier analysis:

$$\hat{u}(\xi,t) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-ix \cdot \xi} u(x,t) \mathrm{d}x.$$

Fourier transform of the above standard problem yields

$$P(i\xi,\tau)\hat{u} = 0, \tau^{k}\hat{u}(\xi,\tau) = 0, \tau^{m-1}\hat{u}(\xi,0) = \hat{g}(\xi)$$

Fix ξ and suppose $Z(\xi, t)$ denotes the solution t_0 to the ODE

$$P(i\xi,\tau)Z(\xi,t) = 0$$

with initial conditions

$$\tau^k Z(\xi, 0) = 0 \quad (0 \leqslant k \leqslant m - 1), \quad \tau^{m-1} Z(\xi, 0) = 1.$$

This is a constant coefficients ODE, an analytic solution for it exists for all t. Clearly, by linearity

$$\hat{u}(\xi,t) = Z(\xi,t)\hat{g}(\xi)$$

and

$$u(x,t) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{ix\cdot\xi} Z(\xi,t) \hat{g}(\xi) \mathrm{d}\xi.$$

We want $u \in C^m$ ("classical solution"). Problem: Need to show that $Z(\xi, t)$ does not grow too fast (=faster than a polynomial) in ξ . Formally,

$$\partial^{\alpha} \tau^{k} u(x,t) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^{n}} e^{ix \cdot \xi} (i\xi)^{\alpha} \tau^{k} Z(\xi,t) \hat{g}(\xi) \mathrm{d}\xi.$$

Key estimate: For any T > 0, there exists C_T , N such that

$$\max_{0 \leqslant k \leqslant m} \sup_{0 \leqslant \tau \leqslant T} \sup_{\xi \in \mathbb{R}^n} \left| \tau^k Z(\xi, t) \right| \leqslant C_T (1 + |\xi|)^N$$

Definition 2.48. The above standard problem is called hyperbolic if there exists a C^m solution for every $g \in \mathcal{S}(\mathbb{R}^n)$.

Theorem 2.49. (Gårding's criterion) The problem is hyperbolic iff $\exists c \in \mathbb{R}$ such that $P(i\xi, \lambda) \neq 0$ for all $\xi \in \mathbb{R}^n$ and λ with $\operatorname{Im}(\lambda) \leq -c$.

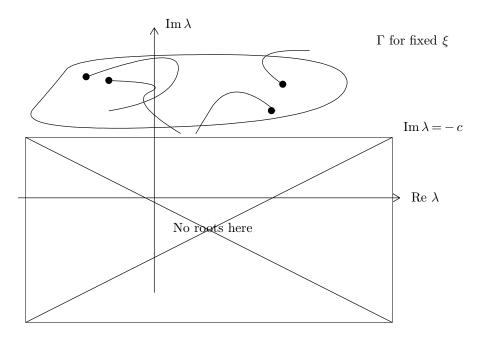


Figure 2.1. Nice cartoon.

Proof. Cartoon: Typical solutions to $P(i\xi, \tau)Z = 0$ are of the form $Z = e^{i\lambda t}$ with $P(i\xi, i\lambda) = 0$. We will only prove " \Leftarrow ": We'll prove the estimate

$$\max_{0 \leqslant k \leqslant m} \sup_{0 \leqslant \tau \leqslant T} \sup_{\xi \in \mathbb{R}^n} |Z(\xi, t)| \leqslant C_T (1 + |\xi|)^N$$

assuming $P(i\xi, i\lambda) \neq 0$ for $\text{Im}(\lambda) \ge -c$. Formula for $Z(\xi, t)$:

$$Z(\xi,t) = \frac{1}{2\pi} \int_{\Gamma} \frac{e^{i\lambda t}}{P(i\xi,i\lambda)} \mathrm{d}\lambda.$$

 $\label{eq:Claim:} \text{Claim:} \ P(i\xi,\tau)Z = 0 \ (t>0), \ \tau^kZ = 0 \ (0\leqslant k\leqslant m-2, \ t=0), \ \tau^{m-1}Z = 1 \ (t=0).$

$$\tau^k Z = \frac{1}{2\pi} \int_{\Gamma} \frac{(i\lambda)^k e^{i\lambda t}}{P(i\xi, i\lambda)} \mathrm{d}\lambda.$$

Therefore

$$P(i\xi,\tau)Z = \frac{1}{2\pi} \int_{\Gamma} P(i\xi,i\lambda) \frac{e^{i\lambda t}}{P(i\xi,i\lambda)} d\lambda$$
$$= \frac{1}{2\pi} \int_{\Gamma} e^{i\lambda t} d\lambda = 0$$

by Cauchy's Theorem. Suppose $0 \le k \le m-2$. Let $t = 0 \Rightarrow e^{i\lambda t} = 1$.

$$\tau^k Z = \frac{1}{2\pi} \int_{\Gamma} \frac{(i\lambda)^k}{(i\lambda)^n \left(1 + o\left(\frac{1}{|\lambda|}\right)\right)} \mathrm{d}\lambda.$$

Suppose that Γ is the circle of radius $R \gg 1$ with center at 0. Then

$$|\tau^k Z| \leq \frac{1}{2\pi} \frac{R^k}{R^n \left(1 + o\left(\frac{1}{R}\right)\right)} \cdot 2\pi R = R^{k - (m-1)} \left(1 + o\left(\frac{1}{R}\right)\right) \to 0$$

if $k \leq m-2$. Thus, $\tau^k Z = 0$ for any Γ enclosing all roots. When k = m - 1, we have

$$\tau^{m-1}Z = \frac{1}{2\pi i} \int_{\Gamma} \frac{1}{\lambda \left(1 + \underbrace{o\left(\frac{1}{\lambda}\right)}_{\text{analytic}}\right)} d\lambda = 1.$$

Step 2) Claim: Any root of $P(i\xi, i\lambda)$ staisfies

$$|\lambda(\xi)| \leq M(1+|\xi|).$$

Estimate growth of roots: Suppose λ solves $P(i\xi, i\lambda) = 0$. Then

$$(i\lambda)^n + (i\lambda)^{n-1}P_1(i\xi) + \dots + P_m(i\xi) = 0.$$

Thus,

$$-(i\lambda)^m = (i\lambda)^{m-1} P_1(i\xi) + (i\lambda)^{m-2} P_2(i\xi) + \dots + P_m(i\xi).$$

Observe that

$$|P_k(i\xi)| \leqslant C_k(1+|\xi|)^k \tag{2.2}$$

for every $k, 1 \leq k \leq m$. Therefore,

$$|\lambda|^m \leq C \sum_{k=1}^m |\lambda|^{m-k} (1+|\xi|)^k.$$

Claim: this implies:

$$|\lambda| \leqslant (1+C)(1+|\xi|).$$

Let

$$\theta = \frac{|\lambda|}{1+|\xi|}.$$

Then (2.2) implies

$$\theta^m \leqslant C \sum_{k=1}^m \, \theta^k \! \Rightarrow \! \theta^m \! \leqslant \! \frac{\theta^m - 1}{\theta - 1} \quad (\theta \neq 1).$$

Cases:

- $\theta \leq 1 \Leftrightarrow |\lambda| \leq 1 + |\xi| \Rightarrow$ nothing to prove.
- $\bullet \quad \theta > 1 \Rightarrow \theta^m \leqslant C \theta^m / (\theta 1) \Rightarrow \theta \leqslant 1 + C \Rightarrow |\lambda| \leqslant (1 + C)(1 + |\xi|).$

Step 3. Claim:

$$|\tau^k Z(\xi, t)| \leqslant M m \, e^{(1+c)t} (1+|\xi|)^k.$$

Here M=bound from step 2, m=order of $P(D, \tau)$, c=constant in Gårding's criterion.

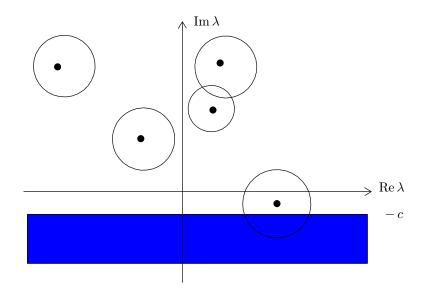


Figure 2.2. Sketch.

Fix $\xi \in \mathbb{R}^n$. Let Γ =union of circles of unit radius abound each λ_k . (wlog, no λ_k on the boundary, else consider circles of radius $1 + \varepsilon$)

$$P(i\xi,i\lambda) = i^m \prod_{k=1}^m (\lambda - \lambda_k(\xi)).$$

On Γ we have $|\lambda - \lambda_k(\xi)| \ge 1$ for all λ . Therefore $|P(i\xi, i\lambda)| \ge 1$ on Γ .

$$\tau^k Z(\xi,t) = \frac{1}{2\pi} \int_{\Gamma} \frac{(i\lambda)^k e^{i\lambda t}}{P(i\xi,i\lambda)} \mathrm{d}\lambda$$

Bound on $|e^{i\lambda t}|$ on Γ . we have $\operatorname{Im}(\lambda) \ge -c - 1$ by Gårding's assumption.

$$|e^{i\lambda t}| = e^{-(\operatorname{Im}\lambda)t} \leqslant e^{(1+c)t}.$$

Thus,

$$\begin{aligned} |\tau^{k}Z(\xi,t)| &\leqslant \frac{1}{2\pi} \bigg(\sup_{\lambda \in \Gamma} |\lambda|^{k} \bigg) e^{(1+c)t} \underbrace{(2\pi m)}_{\text{length of } \Gamma} \\ &\leqslant m \, e^{(1+c)t} \bigg(\sup_{l} \left(|\lambda_{l}(\xi)| + 1 \right) \bigg)^{k} \\ &\leqslant m \, e^{(1+c)t} (M(1+|\xi|)+1)^{k} \end{aligned}$$

since each $\lambda(\xi) \leqslant M(1+|\xi|).$

$$|\tau^k Z(\xi,t)| \leqslant C M^k m \, e^{(1+c)t} (1+|\xi|)^k.$$

Step 4. This implies that

$$\begin{aligned} |\partial^{\alpha} \tau^{k} u(x,t)| &\leqslant \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^{n}} |\tau^{k} Z(\xi,t)| \, |\xi|^{\alpha} \hat{g}(\xi) \mathrm{d}\xi. \\ &\leqslant \frac{C M^{k} e^{(1+c)t}}{(2\pi)^{n/2}} \int_{\mathbb{R}^{n}} (1+|\xi|)^{k} |\xi|^{\alpha} |\hat{g}|(\xi) \mathrm{d}\xi < \infty \end{aligned}$$

because $\hat{g} \in \mathcal{S}$.

Theorem 2.50. Assume $P(D, \tau)$ satisfies Gårding's criterion. Then there exist C^{∞} solutions for all $g \in S(\mathbb{R}^n)$.

 \leq

For finite regularity, we only need check for $k + |\alpha| \leq m$. We need

$$(1+|\xi|)^m |\hat{g}(\xi)| \in L^1(\mathbb{R}^n).$$

Need for every $\varepsilon > 0$

or

$$(1+|\xi|)^m |\hat{g}(\xi)| \leq \frac{C_{\varepsilon}}{(1+|\xi|^{n+\varepsilon})}$$
$$|\hat{g}(\xi)| \leq C_{\varepsilon} (1+|\xi|)^{-(m+n)-\varepsilon}.$$

m=order of $P(D, \tau)$ =regularity of solution, n=space dimension.

Example 2.51. $\partial_t^2 - \Delta u = 0$. $(i\lambda)^2 - (i|\xi|)^2 = 0$, $\lambda = \pm |\xi| \rightarrow$ Growth estimate can't be improved.

Gårding stated wrongly!!!

Question: Is a hyperbolic equation hyperbolic in the sense that it is "wavelike" (meaning if g has compact support, u(x,t) has compact support (in x) for each t > 0.

Theorem 2.52. (Paley-Wiener) Suppose $g \in L^1(\mathbb{R}^n)$ with compact support. Then $\hat{g}: \mathbb{C}^n \to \mathbb{C}^n$ is entire.

$$\hat{g}(\xi) = \frac{1}{(2\pi)^{n/2}} \int_{B(0,R)} e^{-ix \cdot \xi} g(x) \mathrm{d}x.$$

Formally differentiate once, then C^{∞} follows.

Theorem 2.53. Assume Gårding's criterion (restriction on roots). Then there is a C^{∞} solution to the standard problem for $g \in S(\mathbb{R}^n)$.

Example 2.54.

Proof.

$$P(D,\tau)u = u_{tt} - \Delta u$$

$$P(i\xi, i\lambda) = -\lambda^2 + |\xi|^2$$

The roots are $\lambda = \pm |\xi|$, which satisfies (GC).

Example 2.55. Suppose $P(i\xi, i\lambda)$ is homogeneous

$$P(i\,s\xi,i\,s\,\lambda) = s^n P(i\xi,i\lambda)$$

for every $s \in \mathbb{R}$. (GC) holds \Leftrightarrow all roots are real-otherwise, we can scale them out as far as we need to.

In general, we can write

$$P(i\xi, i\lambda) = p_{m-1}(i\xi, i\lambda) + \dots + p_0(i\xi, i\lambda),$$

where p_k is homogeneous of degree k.

Corollary 2.56. Suppose $P(D,\tau)$ is hyperbolic. Then all roots of $p_m(i\xi,i\lambda)$ are real for every $\xi \in \mathbb{R}^n$.

Corollary 2.57. Suppose the roots of p_m are real and distinct for all $\xi \in \mathbb{R}^n$. Then P is hyperbolic. (m=order of P).

Proof. write $\xi = \rho \eta$, $\lambda = \rho \mu$. where $|\eta| = 1$, $\rho = |\xi|$.

$$P(i\xi,i\lambda) = 0 \Leftrightarrow p_m(i\eta,i\mu) + \frac{1}{\rho}p_{m-1}(i\eta,i\mu) + \dots + \frac{1}{\rho^n}p_0(i\eta,i\mu) = 0.$$

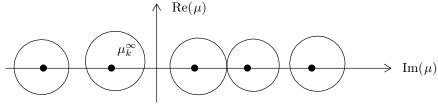


Figure 2.3. Illustrative Sketch. :-)

Use the Implicit Function Theorem to deduce that there exists $\delta > 0$ such that each μ_k^{∞} perturbs $\mu_k(p)$ for $1/\rho \leq \delta_0$.

$$|\mu_k^{\infty} - \mu_k(p)| \leqslant \frac{C}{\rho}.$$

We want $f(x(\varepsilon), \varepsilon) = 0$. We know $f(x_0, 0) = 0$. The distinctness is guaranteed by the derivative condition.

Definition 2.58. $P(D, \tau)$ is called strictly hyperbolic if all $\lambda(\xi)$ are real and distinct. Also say that $p_m(D, \tau)$ is strictly hyperbolic if roots are real and distinct.

Example 2.59. $u_{tt} - \Delta u = 0$ is strictly hyperbolic.

Example 2.60. (*Telegraph equation*) $u_{tt} - \Delta u + k u = 0$ with $k \in \mathbb{R}$. By Corollary 2.57, this equation is hyperbolic.

Theorem 2.61. Suppose $p_m(D, \tau)$ is strictly hyperbolic. Suppose $g \in \mathcal{S}(\mathbb{R}^n)$ and supp $g \subset B(0, a)$. Then there exists a c_* such that

$$\operatorname{supp} u \subset B(0, a + c_* t).$$

 c_* is the largest wave speed.

Proof. (Main ingredients)

• Paley-Wiener Theorem: Suppose $g \in L^1(\mathbb{R}^n)$ and supp $g \subset B(0, a)$. Then \hat{g} extends to an entire function $\mathbb{C}^n \to \mathbb{C}^n$ and

$$|\hat{g}(\xi + i\zeta)| \leq \frac{\|g\|_{L^1}}{(2\pi)^{n/2}} e^{a|\zeta|}.$$

(Proof see below)

- Heuristic:
 - Decay in $f \Rightarrow$ regularity of \hat{f} .
 - Regularity of $f \Rightarrow$ decay of \hat{f} .
- Estimates of $\text{Im}(\lambda)$ for complex $\xi + i\zeta$. Use strict hyperbolicity to show

$$\operatorname{Im}(\lambda_k) \leqslant c_*(1+|\zeta|)$$

for all $\zeta \in \mathbb{R}^n$.

• Plug into

Use

•

 $Z(i\xi,t) = \frac{1}{2\pi} \int_{\Gamma} \frac{e^{i\lambda t}}{P(i\xi-\zeta,\lambda)} d\lambda.$ $u(x,t) = \frac{1}{(2\pi)^{n/2}} \int_{\mathbb{R}^n} e^{-ix \cdot (\xi+i\zeta)} Z(\xi+i\zeta,\tau) g(\xi) d\xi.$

Proof. (of Paley-Wiener)

$$\begin{aligned} |\hat{g}(\xi + i\zeta)| &= \left| \frac{1}{(2\pi)^{n/2}} \int_{B(0,a)} e^{-ix \cdot (\xi + i\zeta)} g(x) dx \right| \\ &\leqslant \left| \frac{1}{(2\pi)^{n/2}} \int_{B(0,a)} |e^{-ix \cdot (\xi + i\zeta)}| |g(x)| dx \\ &\leqslant \left| \frac{1}{(2\pi)^{n/2}} e^{a|\zeta|} \int_{B(0,a)} |g(x)| dx. \end{aligned}$$