

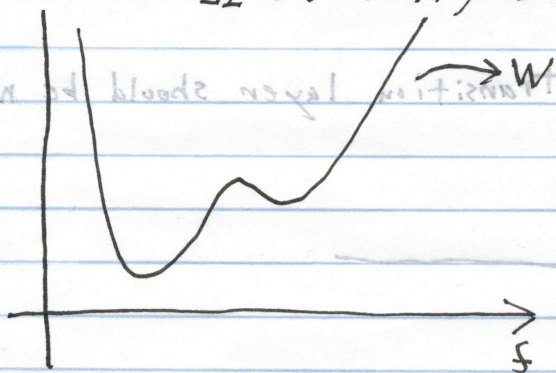
Lecture 8:  $\Gamma$ -convergence

Goals:

- $\Gamma$ -convergence for 1-D problems
- Gradient theory of phase transitions
- Dimension reduction
- Connection with relaxation.

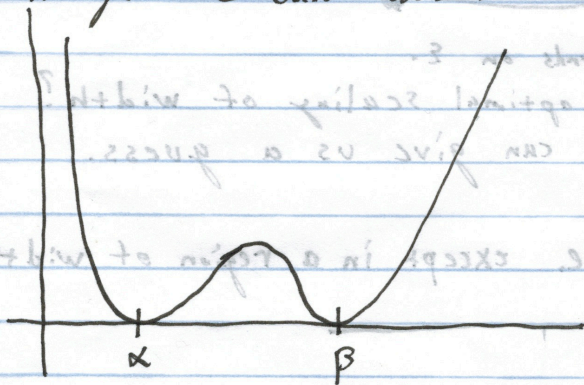
1. Example:

$I[f] = \int_{\Omega} W(f) dx, \quad A = \{f \in L^1(\Omega) : \int_{\Omega} f dx = C\}$



The two minimum of  $f$  are "phases" and  $W$  is the free energy.

W.l.o.g. we can assume  $W$  is of the following form



by make the affine change of coordinates

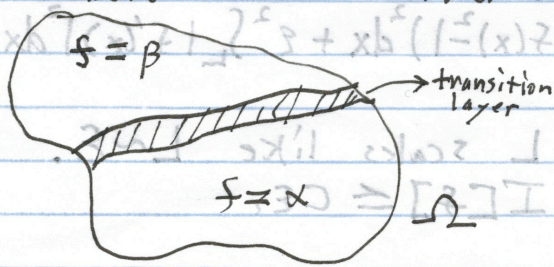
$W(f) + c_1 f + c_2$

since

$S(c_1 f + c_2) = c_1 C + c_2$

The minimizers are clearly any functions which equal  $\alpha, \beta$  a.e. and satisfy the density mass constraint.

Practically however the observed state looks like:



We can add in a penalty for transition layers

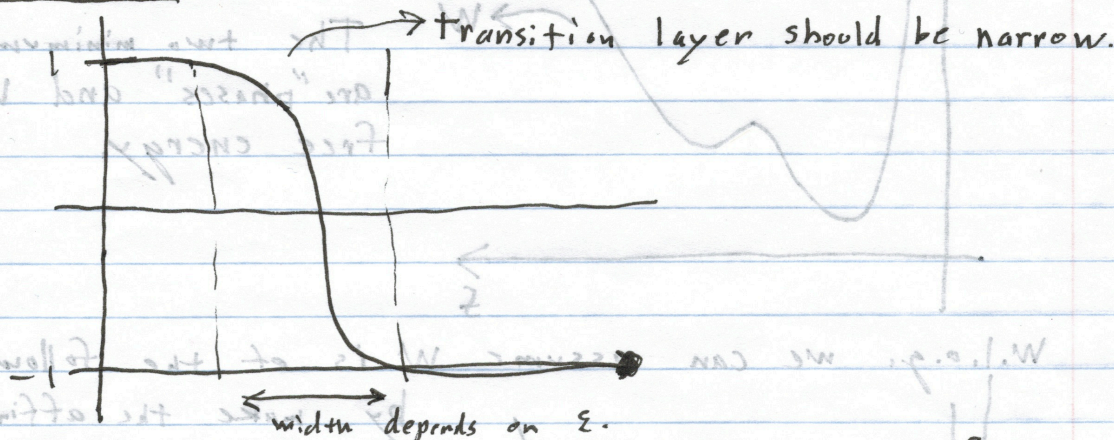
$$I[f] = \int_{\Omega} (W(f) + \varepsilon^2 |\nabla f|^2) dx,$$

with  $\varepsilon$  a small parameter. Lets consider the "simple" example.

$$I[f] = \int_0^1 (f(x)^2 - 1)^2 + \varepsilon^2 \int_0^1 |f'(x)|^2 dx.$$

The question we are interested in is what is the behaviour of the minimizers as  $\varepsilon \rightarrow 0$ ?

Intuition:

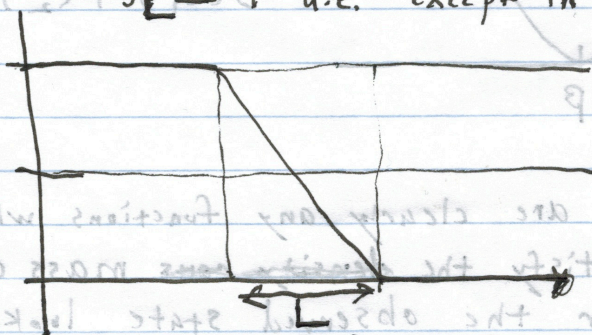


1. How can we guess optimal scaling of width?

An upper bound can give us a guess.

Let

$f_L = 1$  a.e. except in a region of width  $L$



$$I[f_L] = \int_L (f(x)^2 - 1)^2 dx + \varepsilon^2 \int_L |f'(x)|^2 dx \leq 4L + \frac{\varepsilon^2}{L}$$

The optimal  $L$  scales like  $L \sim \varepsilon$ .

$$\Rightarrow \min I[f] \leq C\varepsilon$$

$$\Sigma \geq 1 + \int_{-1}^1 (f(x)^2 - f'(x)^2) dx$$

$$\int_{-1}^1 (f(x)^2 - f'(x)^2) dx \geq 0$$

2. We would guess that the width scales like  $\epsilon$ . We can get better information by finding a lower bound.

$$\int_0^1 (f(x)^2 - 1)^2 dx + \epsilon^2 \int_0^1 f'(x)^2 dx \geq 2\epsilon \int_0^1 |f(x)^2 - 1| \cdot |f'(x)| dx = 2\epsilon \int_0^1 \left| \frac{d}{dx} g(f(x)) \right| dx$$

where

$$g'(t) = |t^2 - 1| \Rightarrow g(t) = \int_{-1}^t |1 - s^2| ds$$

For  $-1 < t < 1$  we have that  $g(t) = t - \frac{1}{3}t^3 \Big|_{-1}^t$

Consequently,

$$2\epsilon \int_0^1 \left| \frac{d}{dx} g(f(x)) \right| dx = 2(g(1) - g(-1))\epsilon = \frac{8}{3}\epsilon$$

So we have that

$$\int_0^1 (f(x)^2 - 1)^2 dx + \epsilon^2 \int_0^1 f'(x)^2 dx \geq \frac{8}{3}\epsilon$$

Note we can get the optimal form of the transition

layer by setting

$$|f(x)^2 - 1| = \epsilon |f'(x)| \Rightarrow f_\epsilon(x) = \tanh\left(\frac{x - x_0}{\epsilon}\right)$$

for a transition layer centered at  $x_0$ .

From this construction we see that 1-transition layer is ~~preferred~~ preferred.

Can we make this intuitive construction rigorous in some way? What would really like is a limit process for functionals

\* The inequality above is known (as) the Modica-Mortola inequality.

\* We have shown that the optimal solution has two phases with a transition layer of width  $L \geq \epsilon$ . We will make this precise in a bit. For now, let's look at the analogous problem in 2-d.

$$f(x)^4 - 2f(x)^2 + 1 \leq 2$$

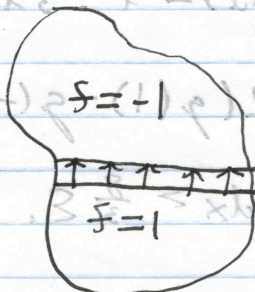
$$0 \leq (a-b)^2 \leq a^2 + b^2 \Rightarrow a^2 + b^2 \geq 2|a| \cdot |b|$$

2. Example:

~~$$I[f] = \int_{-2}^2 (f(x)^2 - 1)^2 dx + \epsilon \int_{-2}^2 |\nabla f|^2 dx,$$~~

with again the constraint  $\int_{-2}^2 f(x) dx = C$ . By taking an ansatz of a linear transition layer we obtain the upper bound

$$\inf_{f \in A} I[f] \leq |\epsilon \epsilon| = \epsilon^2$$



A lower bound for the energy of a transition layer can also be found!

$$\int_{-2}^2 (f(x)^2 - 1)^2 dx + \epsilon^2 \int_{-2}^2 |\nabla f|^2 dx \geq 2\epsilon \int_{-2}^2 |\nabla f| \cdot |f(x)^2 - 1| dx$$

$$= 2\epsilon \int_{-2}^2 |\Psi'(f)| dx$$

where  $\Psi = |x^2 - 1| \Rightarrow \Psi(x) = \int_{-1}^x |s^2 - 1| ds,$

Integrating across the "jump" we have that:

$$\int_{-2}^2 (f(x)^2 - 1)^2 dx + \epsilon^2 \int_{-2}^2 |\nabla f|^2 dx \geq 2[\Psi(1) - \Psi(-1)] \cdot \text{Length(T.L.)}$$

(T.L. = transition layer).

$$\Rightarrow \int_{-2}^2 (f(x)^2 - 1)^2 dx + \epsilon^2 \int_{-2}^2 |\nabla f|^2 dx \geq \frac{8}{3} \epsilon \text{Per}_{-2} \{x: f(x) = 1\}.$$

\* The previous calculation is very formal!

\* Remark: optimal transition layer is then given by  $f_\epsilon(x) = \tanh\left(\frac{d(x, \text{T.L.})}{\epsilon}\right)$

### 3. Our first $\Gamma$ -limit

We would like to say in some sense that

$$\lim_{\varepsilon \rightarrow 0} \left( \frac{1}{\varepsilon} I_{\varepsilon}[f] = \int_{\Omega} (f(x)^2 - 1)^2 dx + \varepsilon \int_{\Omega} |\nabla f|^2 dx \right) = \frac{8}{3} \text{Per}_{\Omega} \{f(x) = \pm 1 \text{ a.c.}\} + \text{l.o.t}$$

Of course this doesn't even make sense formally since the r.h.s. contains  $\varepsilon$ .

$$\Gamma\text{-lim}_{\varepsilon \rightarrow 0} \left( \frac{1}{\varepsilon} I_{\varepsilon}[f] \right) = \begin{cases} \frac{8}{3} \text{Per}_{\Omega} \{f(x) = \pm 1 \text{ a.c.}\}, & \text{if } f(x) = \pm 1 \text{ a.c.} \\ \infty, & \text{o.w.} \end{cases}$$

Let  $\bar{I}_{\varepsilon} = \frac{1}{\varepsilon} I_{\varepsilon}$  and

$$I_0 = \begin{cases} \frac{8}{3} \text{Per}_{\Omega} \{f(x) = \pm 1 \text{ a.c.}\} & \text{if } f(x) = \pm 1 \text{ a.c.} \\ \infty & \text{o.w.} \end{cases}$$

Observations:

1. If  $f_{\varepsilon} \rightarrow f_0$  in  $L^1$  as  $\varepsilon \rightarrow 0$ , then

$$I_0[f_0] \leq \liminf_{\varepsilon \rightarrow 0} I_{\varepsilon}[f_{\varepsilon}] \quad (\text{liminf inequality})$$

~~Proof: Let  $f_{\varepsilon} \rightarrow f_0$  in  $L^1$ .~~

~~Then either  $f_{\varepsilon} \rightarrow f_0$  in  $L^4$  in which case taking limit  $\varepsilon \rightarrow 0$  yields  $I_{\varepsilon}[f_{\varepsilon}] \rightarrow \infty$  or  $f_{\varepsilon} \not\rightarrow f_0$  in  $L^4$  meaning  $\|f_{\varepsilon}\|_4 = \infty$  which yields the same result upon taking limits.~~

is is  
barassing  
berish.

2. There exists  $f_{\varepsilon} \rightarrow f_0$  in  $L^1$  as  $\varepsilon \rightarrow 0$  such that

$$I_{\varepsilon}[f_{\varepsilon}] \rightarrow I_0[f_0] \quad (\text{recovery sequence})$$

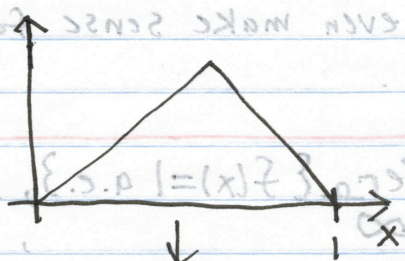
3. If  $f_{\varepsilon}$  satisfies  $I_{\varepsilon}[f_{\varepsilon}]$  is uniformly bounded then  $f_{\varepsilon}$  is compact in  $L^1(\Omega)$ . This is why it is important to use  $L^1$  topology.

\* We will make these statements precise in a bit.  
\* Items 1 and 2 comprise the definition of a  $\Gamma$ -lim.

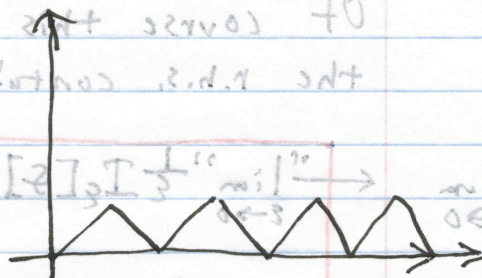
Consequences:

$$1. I_\epsilon = \int_0^1 [\epsilon f''(x)^2 + \frac{1}{2}(f'(x)^2 + 1)^2 + \lambda f(x)^2] dx$$

$$\Gamma\text{-}\lim_{\epsilon \rightarrow 0} I_\epsilon[f] = \begin{cases} \int_0^1 \lambda f(x)^2 + \frac{2}{3} \# \text{ teeth}, & \text{if } |f'(x)| = 1 \text{ a.e.} \\ \infty, & \text{o.w.} \end{cases}$$



optimum for small  $\lambda$



optimum for large  $\lambda$

Remark:  $\Gamma$ -convergence is stable under ~~higher~~ lower order perturbations. The relevant topology of the  $\Gamma$ -lim is  $W^{1,1}$  the lower order term  $\lambda f(x)^2$  is compact in this topology for a minimizing sequence so it does not affect the  $\Gamma$ -lim.

~~Gamma~~ ~~Gamma~~ ~~Gamma~~

$$\Gamma\text{-}\lim_{\epsilon \rightarrow 0} (I_\epsilon + J) = J_0 + J$$

2. Claim:  $\Gamma$ -convergence  $\Rightarrow$  convergence of minimizers, and convergence of minimizing value.

proof:

a.) If  $\Gamma\text{-}\lim_{\epsilon \rightarrow 0} I_\epsilon = I_0$  then  $\limsup_{\epsilon \rightarrow 0} (\min I_\epsilon) \leq \min I_0 \leftarrow (\text{claim!})$

This follows from the recovery sequence.

$$\limsup_{\epsilon \rightarrow 0} (\min I_\epsilon [X_\epsilon]) \leq \limsup_{\epsilon \rightarrow 0} I_\epsilon [X_\epsilon] = \min I_0$$

b.) By  $\Gamma$ -lim inf inequality we have

$$\min I_0 \leq \liminf_{\epsilon \rightarrow 0} \min I_\epsilon$$

This is the recovery sequence

\* Items 1 and 2 comprise the definition of a  $\Gamma$ -lim. \* Will make these statements precise in a bit

4.  $\Gamma$ -lim

Definition - A sequence  $I_\varepsilon: X \rightarrow \mathbb{R}$   $\Gamma$ -converges in  $X$  to  $I_0: X \rightarrow \mathbb{R}$  if  $\forall f \in X$ :

1.  $I_0[f] \leq \liminf_{\varepsilon \rightarrow 0} I_\varepsilon[f_\varepsilon]$ , if  $f_\varepsilon \rightarrow f$  (liminf inequality).
2. There exists  $f_\varepsilon \rightarrow f$  such that  $I_0[f] \geq \limsup_{\varepsilon \rightarrow 0} I_\varepsilon[f_\varepsilon]$  (recovery sequence).

We then write  $\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} I_\varepsilon = I_0$ .

Comment: Property can be equivalently written as there exists  $f_\varepsilon \rightarrow f$  such that

$$I_0[f] = \lim_{\varepsilon \rightarrow 0} I_\varepsilon[f_\varepsilon].$$

Comment: The previous definition consists of upper and lower estimates. Moreover, it gives us l.s.c. for free (we will see this later). To obtain a decent notion for existence of a minimum we will also need a notion of coercivity.

Definition: A functional  $I: X \rightarrow \mathbb{R}$  is coercive if for all  $M \in \mathbb{R}$  the set  $\{I \leq M\}$  is precompact in  $X$  with its equipped topology. A functional is mildly coercive if  $\exists K \subset X$  compact such that  $\inf I[f] = \inf I|_K[f]$ . A sequence is mildly equi-coercive if  $\exists K \subset X$  compact such that  $\inf I[f] = \inf I_\varepsilon|_K[f]$  for all  $\varepsilon$ .

Theorem - If  $\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} I_\varepsilon = I_0$  then  $\inf I_0 = \lim_{\varepsilon \rightarrow 0} \inf I_\varepsilon$ .

proof:

We will assume that the minimum is obtained since it changes the arguments little.

a.) Let  $f_\varepsilon^*$  be a recovery sequence for a minimizer  $f^*$  of  $I_0$ . Then,

$$\limsup_{\varepsilon \rightarrow 0} \min_X I_\varepsilon[f] \leq \limsup_{\varepsilon \rightarrow 0} I_\varepsilon[f_\varepsilon] = \min_X I_0[f^*]$$

b.) By the limit inequality we have that

$$\min_X I_0[f] \leq \liminf_{\varepsilon \rightarrow 0} \min_X I_\varepsilon[f]$$

$$\text{Items a) and b)} \Rightarrow \min_X I_0 = \lim_{\varepsilon \rightarrow 0} \min_X I_\varepsilon$$

Theorem - If  $\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} I_\varepsilon = I_0$  and  $I_\varepsilon$  is mildly equi-coercive then if  $f_\varepsilon$  minimizes  $I_\varepsilon$  then there exists a subsequence  $f_{\varepsilon_k}$  and  $f^* \in X$  such that  $f_{\varepsilon_k} \rightarrow f^*$  and  $\min_X I_0[f] = I_0[f^*]$ .

proof: From equi-coercivity we get compactness so that there exists  $f^*$  and a subsequence such that  $f_{\varepsilon_k} \rightarrow f^*$ . Therefore,  $I_0[f^*] \leq \liminf_{\varepsilon \rightarrow 0} I_\varepsilon[f_{\varepsilon_k}] = \lim_{\varepsilon \rightarrow 0} \min_X I_\varepsilon[f] = \min_X I_0[f]$ .  
 $\Rightarrow f^*$  is a minimum.

Theorem - If  $\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} I_\varepsilon = I_0$  then  $I_0$  is l.s.c.

proof:

Otherwise  $\exists$  some  $f \in X$  and a sequence  $f_\varepsilon \rightarrow f$  such that

$$I_0[f] > \lim_{\varepsilon \rightarrow 0} I_0[f_\varepsilon]$$

By  $\Gamma$ -convergence  $\exists$  a sequence  $f_{\varepsilon_s}$  such that

$$\lim_{s \rightarrow \infty} f_{\varepsilon_s} = f_\varepsilon$$

and

$$\lim_{s \rightarrow \infty} I_{\varepsilon_s}[f_{\varepsilon_s}] = I_0[f_\varepsilon]$$

Let  $\eta = \frac{1}{4}(I_0[f] - \lim_{\varepsilon \rightarrow 0} I_0[f_\varepsilon]) > 0$ . For every  $\varepsilon > 0$

we can find  $\delta(\varepsilon)$  with

$$I_{\delta(\varepsilon)}[f_{\varepsilon, \delta(\varepsilon)}] - I_0[f_\varepsilon] < \eta \quad *$$

Choose  $\varepsilon$  small enough that

$$I_0[f] - I_0[f_\varepsilon] > 3\eta \quad ** \text{ (Follows from def.)}$$

and

$$I_0[f] - I_{\delta(\varepsilon)}[f_{\varepsilon, \delta(\varepsilon)}] < \eta \quad *** \text{ (limit inequality)}$$

$\Rightarrow \eta < I_{\delta(\varepsilon)}[f_{\varepsilon, \delta(\varepsilon)}] - I_{\delta(\varepsilon)}[f_{\varepsilon, \delta(\varepsilon)}] = 0$   
 which is a contradiction.  $\blacksquare$

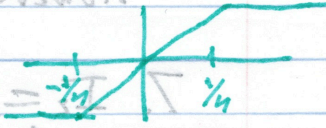


examples:

1.  $X = [0, 1]$ ,  $f_n(x) = nx^2$

$$\Gamma\text{-}\lim_{n \rightarrow \infty} f_n(x) = \begin{cases} 0, & x=0 \\ \infty, & x \neq 0 \end{cases}$$

2.  $X = \mathbb{R}$ ,  $f_n(x) = \begin{cases} 1, & x \geq \frac{1}{n} \\ nx, & -\frac{1}{n} \leq x \leq \frac{1}{n} \\ -1, & x \leq -\frac{1}{n} \end{cases}$



$$\Gamma\text{-}\lim_{n \rightarrow \infty} f_n(x) = \begin{cases} 1, & x > 0 \\ -1, & x \leq 0 \end{cases}$$

\* Pointwise and  $\Gamma$ -lim are not the same.

3. example:

$X = [0, 1]$ ,  $f_n(x) = n(x - \frac{1}{n})^2 = nx^2 - 2 + \frac{1}{n}$

$$\Gamma\text{-}\lim_{n \rightarrow \infty} f_n(x) = \begin{cases} 0, & x=0 \\ \infty, & x \neq 0 \end{cases}$$

\* Lower order perturbations do not contribute to the  $\Gamma$ -lim. Take the sequence  $X_n = \frac{1}{n}$ .

4. example:

$f_n(x) = \frac{1}{nx} + x$ ,  $X = [0, 1]$

\* Note: if  $g_n(x) = x$  then  $\Gamma\text{-}\lim_{n \rightarrow \infty} g_n = x$ .

If there exists  $x_n$  such that  $f_n(x_n) \rightarrow \Gamma\text{-}\lim_{n \rightarrow \infty} f_n(x_n) = x$  then

$$\Gamma\text{-}\lim_{n \rightarrow \infty} f_n(x) = \lim_{n \rightarrow \infty} f_n(x_n) \geq \inf_{x_n \rightarrow x} \liminf_{n \rightarrow \infty} f_n(x_n) \geq \Gamma\text{-}\lim_{n \rightarrow \infty} f_n(x) \geq \Gamma\text{-}\lim_{n \rightarrow \infty} g_n(x)$$

$$\Rightarrow \Gamma\text{-}\lim_{n \rightarrow \infty} f_n = \Gamma\text{-}\lim_{n \rightarrow \infty} g_n$$

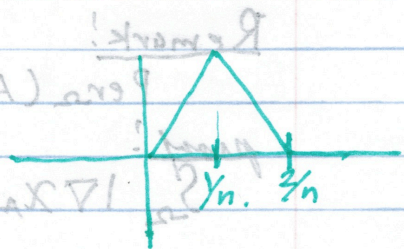
Take,  $x_n = \begin{cases} x, & x \neq 0 \\ \frac{1}{\sqrt{n}}, & x = 0 \end{cases}$  This comes from balancing the two terms.

5. example:

Does  $\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} (-I_\varepsilon) = -\Gamma\text{-}\lim_{\varepsilon \rightarrow 0} I_\varepsilon$ ?

No, let

$$f_n(x) = \begin{cases} nx, & 0 < x \leq \frac{1}{n} \\ 2-nx, & \frac{1}{n} < x \leq \frac{2}{n} \\ 0, & \text{o.w.} \end{cases}$$



6. example:

$$f_n(x) = \sin(nx)$$

$$\lim_{n \rightarrow \infty} f_n(x) = 0$$

However,  $f_n$  does not converge pointwise a.c.

7.  $I_\varepsilon = I$  for all  $\varepsilon$ .

$$\lim_{\varepsilon \rightarrow 0} I_\varepsilon = s.c.I = I^*$$

\* we have shown this before and it was one of the characterizations of the relaxation.

5. Modica-Mortola

Claim: If

$$I_\varepsilon = \frac{1}{\varepsilon} \int_{\Omega} (f(x)^2 - 1)^2 dx + \varepsilon \int_{\Omega} |\nabla f|^2 dx, \quad \int_{\Omega} f^2(x) dx = c$$

Then,

$$\lim_{\varepsilon \rightarrow 0} I_\varepsilon = \begin{cases} \frac{8}{3} \text{Per}_{\Omega} \{f(x) \geq 1\}, & \text{if } |f(x)| = 1 \text{ a.c.} \\ \infty & \text{o.w.} \end{cases}$$

w.r.t.  $L^1$  topology. Moreover,  $I_\varepsilon$  is equivariant in  $L^1$ .

Definition - Define the space of functions of bounded variation  $BV(\Omega)$  by

$$BV(\Omega) = \{f \in L^1(\Omega); \int_{\Omega} |\nabla f| < \infty\}$$

where we are using the notation,

$$\int_{\Omega} |\nabla f| = \sup_{\substack{g \in C_c^1(\Omega; \mathbb{R}^n) \\ |g| \leq 1}} \int_{\Omega} f \cdot \nabla g \, dx.$$

Remark:  $f \in B.V.(\Omega) \iff f \in L^1$  and  $\nabla f$  is a vector valued measure on  $\Omega$  with finite total variation  $\int |\nabla f|$ .

Remark:

$$\text{Per}_{\Omega}(A) = \int_{\Omega} |\nabla \chi_A|$$

proof:

$$\int_{\Omega} |\nabla \chi_A| = \sup_{\substack{g \in C_c^1 \\ |g| \leq 1}} \int_A \nabla \cdot g = - \sup_{\substack{g \in C_c^1 \\ |g| \leq 1}} \int_{\Omega \setminus A} \nabla \cdot g = \text{Per}_{\Omega}(A).$$

### properties of B.V.

1. If  $f_\varepsilon \rightarrow f$  in  $L^1(\Omega)$  then

$$\int_{\Omega} |\nabla f| \leq \liminf_{\varepsilon \rightarrow 0} \int_{\Omega} |\nabla f_\varepsilon|$$

proof:

Let  $g \in C_0^\infty$  with  $|g| \leq 1$ . Then

$$\int_{\Omega} f \nabla \cdot g \, dx = \lim_{n \rightarrow \infty} \int_{\Omega} f_n \nabla \cdot g \leq \liminf_{n \rightarrow \infty} \int_{\Omega} |\nabla f_n|$$

Taking sup over both sides gives us the result. ■

2. If  $f_n \rightarrow f$  in  $L^1(\Omega)$  and  $\int_{\Omega} |\nabla f_n| < M$ , then  $f \in B.V.(\Omega)$

proof:

If  $g \in C_0^\infty$  then for  $i=1, \dots, n$

$$\lim_{n \rightarrow \infty} \int_{\Omega} g (D_i f_n) = - \lim_{n \rightarrow \infty} \int_{\Omega} f_n D_i g = - \int_{\Omega} f D_i g$$

$$\Rightarrow \left| \int_{\Omega} f D_i g \right| \leq \sup |g| \liminf_{n \rightarrow \infty} \int_{\Omega} |\nabla f_n| < \infty.$$

3. Bounded sets in B.V. are compact in  $L^1$ .

proof:

By mollification there exists  $h_n \in C_0^\infty$  with  $\|f_n - h_n\|_{L^1} < \frac{1}{n}$ ,  $\int_{\Omega} |\nabla h_n| \leq M + 1$

$\Rightarrow h_n$  is bounded in  $W^{1,1}(\Omega)$  so  $h_n$  is compact in  $L^1$ .

So,  $h_n \xrightarrow{L^1} f$  and  $f_n \xrightarrow{L^1} f$ . By property 2 it follows that  $f \in B.V.$  ■

### proof of $\Gamma$ -convergence

1. (limit inequality)

First we show that it suffices to consider  $f$  such that

$|f(x)| = 1$  a.e. since if  $f_\varepsilon \rightarrow f$  in  $L^1(\Omega)$  then

$$\liminf_{\varepsilon \rightarrow 0} \int (\varepsilon |\nabla f_\varepsilon|^2 + \frac{1}{\varepsilon} (f_\varepsilon^2 - 1)^2) dx \geq \liminf_{\varepsilon \rightarrow 0} \frac{1}{\varepsilon} \int (f_\varepsilon^2 - 1)^2 dx$$

$$\geq \liminf_{\varepsilon \rightarrow 0} \int \frac{1}{\varepsilon} (f_\varepsilon^2 - 1)^2 dx$$

$$= \infty \text{ if } f \neq 1 \text{ a.e.}$$

Now we show that it is sufficient to consider  $f_\epsilon$  such that

$$-1 \leq f_\epsilon \leq 1$$

since otherwise we could replace  $f_\epsilon$  by its truncation

$$f_\epsilon^* = \begin{cases} 1, & |f_\epsilon| \geq 1 \\ f_\epsilon, & -1 \leq f_\epsilon \leq 1 \\ -1, & f_\epsilon < -1 \end{cases}$$

without changing the  $L^1$  limit.

Now suppose  $-1 < f_\epsilon < 1$  and  $f_\epsilon \rightarrow f$  in  $L^1$  with  $|f| = 1$  a.e.

Then,

$$I_\epsilon[f_\epsilon] \geq 2 \int_{\Omega} |\nabla \psi(f_\epsilon)| dx,$$

where

$$\psi(t) = \int_{-1}^t |1 - x^2| dx \quad (\text{lower bound})$$

By D.C.T.  $\psi(f_\epsilon) \rightarrow \psi(f)$ . By l.s.c. of B.V. norm we have

$$\liminf_{\epsilon \rightarrow 0} I_\epsilon[f_\epsilon] \geq 2 \int_{\Omega} |\nabla \psi(f)| = \frac{2}{3} \text{Per} \{ \Omega \} = L^3.$$

### 2. (Recovery Sequence)

$$\int (\epsilon |\nabla f_\epsilon|^2 + \frac{1}{\epsilon} (f_\epsilon^2 - 1)^2) dx \geq 2 \int |\nabla \psi(f_\epsilon)| dx$$

Equality is obtained when

$$f_\epsilon = \pm \tanh\left(\frac{\text{dist}(x, \Gamma)}{\epsilon}\right)$$

This is essentially the recovery sequence.