

Lecture 5: Convex Duality

Goals:

1. Brief discussion of linear programming
2. Convex duality in P.D.E. setting
3. Derivation of dual problem
4. Calibration method.

1. Motivation

a.) In the homework we found an upper bound for the problem

$$\inf_{f \in A} I[f] = \inf_{f \in A} \left(\int_0^1 (f'(x)^2 - 1)^2 dx + \varepsilon^2 \int_0^1 f''(x)^2 dx \right) \leq \min \{1, C\varepsilon\}.$$

The upper bound is easy to solve find we just make a good guess. Finding a lower bound that scales in the same manner is more tricky. For problems of the form

$$\inf_{f \in A} I[f] = \inf_{f \in A} \int L(\nabla f) dx,$$

the convex dual provides a systematic approach.

b.) Sometimes we have convex but non-smooth Lagrangians:

$$\min_{\substack{f: f(x)=1 \\ f=0 \text{ on } \partial \Omega}} \int |\nabla f| dx$$

The convex-dual provides necessary + sufficient conditions for optimality.

2. Linear Programming

Consider the primal problem

$$(P) \min_{\substack{x_j \geq 0 \\ \sum_{j=1}^n a_{ij} x_j \geq b_i}} \sum_{j=1}^n c_j x_j, \quad x \in \mathbb{R}^n, \quad 1 \leq i \leq m.$$

Lets derive a lower bound. If

$$y_i \geq 0 \text{ and } \sum_{j=1}^n a_{ij} y_i \leq c_j \quad \left(\text{Notice index being summed over} \right)$$

Then,

$$\begin{aligned}
 y_i \sum_{j=1}^n a_{ij} x_j &\geq b_i y_i \\
 \Rightarrow \sum_{j=1}^n \sum_{i=1}^m y_i a_{ij} x_j &\geq \sum_{i=1}^m b_i y_i \\
 \Rightarrow \sum_{j=1}^n c_j x_j &\geq \sum_{i=1}^m b_i y_i
 \end{aligned}$$

Therefore,

$$\min_{\substack{\sum_{j=1}^n c_j x_j \geq \sum_{i=1}^m b_i y_i \\ x_j \geq 0, y_i \geq 0}} \sum_{j=1}^n c_j x_j \geq \max_{\substack{\sum_{i=1}^m b_i y_i \leq \sum_{j=1}^n c_j x_j \\ y_i \geq 0, x_j \geq 0}} \sum_{i=1}^m b_i y_i$$

The maximum problem is called the dual problem

$$(D) \max \sum_{i=1}^m b_i y_i \\
 \sum_{j=1}^n a_{ij} y_i \leq c_j \\
 y_i \geq 0$$

The duality theorem of linear programming says
 $\max(D) = \min(P)$.

Important - If y^* solves D and x^* solves P then

$$\sum_j c_j x_j^* = \sum_i b_i y_i^*$$

$$\Rightarrow \sum_{j=1}^n \sum_{i=1}^m y_i^* a_{ij} x_j^* = \sum_{i=1}^m b_i y_i^* = \sum_{j=1}^n c_j x_j^*$$

Optimizing gives

$$\begin{aligned}
 \forall_i, \quad y_i^* &\geq 0 \text{ and } \sum_j a_{ij} x_j^* \geq b_i \text{ (with equality in at least one)} \\
 \forall_j, \quad x_j^* &\geq 0 \text{ and } \sum_i a_{ij} y_i^* \leq c_j \text{ (with equality in at least one)}
 \end{aligned}$$

3. Example

Consider:

$$(P) \min \int_{\Omega} \frac{1}{2} |\nabla f|^2 dx - \int_{\Omega} f g dx$$

$$(D) \max \int_{\Omega} \frac{1}{2} |\sigma|^2 dx$$

$\nabla \cdot \sigma = 0$ in Ω
 $\sigma \cdot \vec{n} = 0$ on $\partial\Omega$

Note: a.) value of $D <$ value of P b.) Equality holds if f minimizes (P) and σ maximizes (D) .

proof:

$$a.) \int_{\Omega} \frac{1}{2} |\sigma - \nabla f|^2 dx \geq 0$$

$$\Rightarrow \frac{1}{2} \|\sigma\|_{L^2}^2 - \langle \sigma, \nabla f \rangle + \frac{1}{2} \|\nabla f\|_{L^2}^2 \geq 0$$

$$\Rightarrow \frac{1}{2} \|\sigma\|_{L^2}^2 - \int_{\Omega} \sigma \cdot \vec{n} + \int_{\Omega} (\nabla \cdot \sigma) f dx + \frac{1}{2} \|\nabla f\|_{L^2}^2 \geq 0$$

$$\Rightarrow (P) \geq (D).$$

b.) To prove (b), suppose f^* solves (P) then setting $\sigma^* = \nabla f^*$

we get equality of the bounds. (This is the only solution

by strict convexity of D). Euler-Lagrange equations arethen Equation satisfied by σ is then

$$\nabla \cdot \sigma = 0 \text{ in } \Omega, \quad \sigma \cdot \vec{n} = 0 \text{ on } \partial\Omega$$

4. Legendre - Fenchel Transform

Focus on

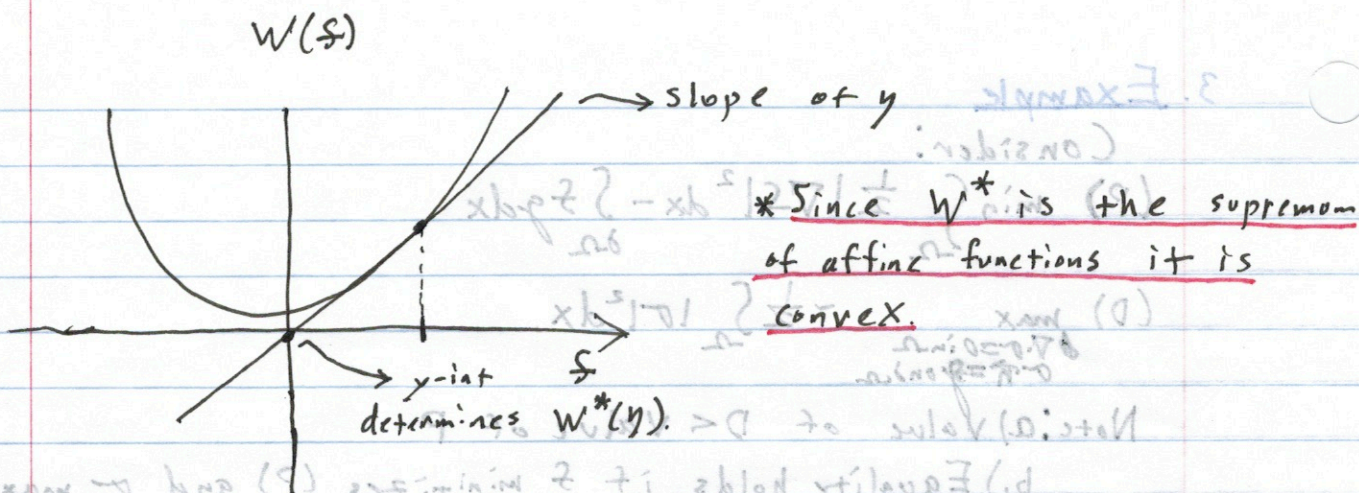
$$(P) \min_f \int_{\Omega} L(\nabla f) - \int_{\Omega} f g dx$$

with L convex and $\int_{\Omega} g dx = 0$.Key point: L convex $\Leftrightarrow$ sup of supporting hyperplanes

$$\Leftrightarrow W(f) = \sup \{ \langle \eta, f \rangle - W^*(\eta) \}$$

where W^* is the Fenchel transform defined by

$$W^*(\eta) = \sup_f \{ \langle \eta, f \rangle - W(f) \}$$



Therefore,

$$\min_f \int_{\Omega} L(\nabla f) dx - \int_{\Omega} f \cdot g ds = \min_f \max_{\sigma} \int_{\Omega} \langle \sigma, \nabla f \rangle - W^*(\sigma) dx - \int_{\Omega} f g ds$$

$$= \min_f \max_{\sigma} \left\{ \int_{\Omega} (\sigma \cdot \vec{n}) f ds - \int_{\Omega} f g ds \right\}$$

$$= \int_{\Omega} ((\nabla \cdot \sigma) f + W^*(\sigma)) dx.$$

If we can switch min and max. Then,

$$\min_f \int_{\Omega} L(\nabla f) dx - \int_{\Omega} f g ds = \max_{\sigma} \min_f \int_{\Omega} ((\sigma \cdot \vec{n}) f ds - \int_{\Omega} f g ds$$

$$= \int_{\Omega} (\nabla \cdot \sigma) f + W^*(\sigma) dx.$$

$$\Rightarrow \min_f \int_{\Omega} L(\nabla f) dx - \int_{\Omega} f g ds = \max_{\substack{\nabla \cdot \sigma = 0 \\ \sigma \cdot \vec{n} = f|_{\partial \Omega}}} \int_{\Omega} W^*(\sigma) dx. \rightarrow (D).$$

If $\nabla \cdot \sigma \neq 0$ or $\sigma \cdot \vec{n} \neq f$ then minimum would be $-\infty$.

Why is $\min \max = \max \min$?

$$1. \min_y F(x, y) \leq F(x, y_0)$$

$$\Rightarrow \max_x \min_y F(x, y) \leq \max_x F(x, y_0)$$

$$\Rightarrow \max_x \min_y F(x, y) \leq \min_y \max_x F(x, y).$$

2. Pointwise inequality

$$L(\nabla f) \geq \langle \nabla f, \sigma \rangle - W^*(\sigma)$$

$$\Rightarrow \int_{\Omega} L(\nabla f) - \int_{\Omega} f \cdot g ds \geq \int_{\Omega} W^*(\sigma).$$

Equality is nontrivial in general, it is really a saddle point principle. If (P) and (D) have E-L equations then we have a direct proof:

* E-L: $\nabla \cdot \left(\frac{\partial L}{\partial \nabla f} \right) = 0$ in Ω , $\frac{\partial L}{\partial f} = g$ on $\partial\Omega$

Take $\sigma = \frac{\partial L}{\partial \nabla f} \Big|_{f=f^*}$

5. Example 1

Let λ_0 = 1st Dirichlet eigenvalue of $\Omega \subset \mathbb{R}^n$

$$\lambda_0 = \min_{f=0, \text{ on } \partial\Omega} \frac{\int_{\Omega} |\nabla f|^2 dx}{\int_{\Omega} f^2 dx} = \min_{\substack{f=0, \text{ on } \partial\Omega \\ \int_{\Omega} f^2 dx = 1}} \int_{\Omega} |\nabla f|^2 dx.$$

1. Sufficient to consider $f \geq 0$

2. Let $g = u^2$

$$\Rightarrow \lambda_0 = \min_{\substack{\int_{\Omega} g dx = 1 \\ g \geq 0 \text{ in } \Omega \\ g = 0 \text{ on } \partial\Omega}} \int_{\Omega} \frac{|\nabla g|^2}{4g} dx$$

3. The function $-p^2/4z$ is convex and in fact:

$$\frac{p^2}{4z} = \max_{\sigma} \{ \langle \sigma, p \rangle - z |\sigma|^2 \}. \quad (\text{Legendre Transform}).$$

$\Rightarrow \lambda_0 = \max_{\sigma} \min_{\substack{g=0, \text{ on } \partial\Omega \\ g \geq 0 \\ \int_{\Omega} g = 1}} \int_{\Omega} \langle \sigma, \nabla g \rangle - g |\sigma|^2$

$= \max_{\sigma} \min_A \int_{\Omega} g \cdot \nabla \cdot \sigma - \int_{\Omega} [\nabla \cdot \sigma + |\sigma|^2] g dx.$

$= \max_{\sigma} \nu$ Again we place restrictions on σ that prevent going to $-\infty$.

$$- [\nabla \cdot \sigma + |\sigma|^2] \geq \nu$$

= largest const ν such that $\exists$ vector field σ on Ω with $\nabla \cdot \sigma + |\sigma|^2 \leq -\nu$.

Example 2

The problem is:

$$\min_{\substack{\sigma \in L^\infty \\ \nabla \cdot \sigma = 1 \text{ on } \Omega}} \|\sigma\|_{L^\infty}.$$

$$\Omega \subset \mathbb{R}^2.$$

It is raining on Ω , the water wants to minimize accumulation.

Observation: $I +$ is equivalent to solve

$$\max_{\substack{|\sigma| \leq 1 \\ \nabla \cdot \sigma = \lambda}} \lambda$$

Since if $\lambda_{\max}$ is optimal then

$$\nabla \cdot \sigma = \lambda \text{ (constant)} \Rightarrow \lambda \leq \lambda_{\max}$$

$$|\sigma| \leq 1$$

$$\Rightarrow \nabla \cdot \left(\frac{\sigma}{\lambda} \right) = 1 \Rightarrow \frac{1}{\lambda} \geq \frac{1}{\lambda_{\max}}$$

Therefore, $\frac{1}{\lambda_{\max}}$ is the optimal solution for the first problem.

We now construct a dual problem

$$\max_{\substack{|\sigma| \leq 1 \\ \nabla \cdot \sigma = \lambda}} \lambda = \max_{|\sigma| \leq 1} \min_{\substack{f=0 \text{ on } \partial\Omega \\ \int_{\Omega} f dx = 1}} - \int_{\Omega} \langle \sigma, \nabla f \rangle dx.$$

$$\begin{aligned} &= - \int_{\Omega} \langle \sigma, \nabla f \rangle dx \\ &= - \int_{\partial\Omega} \langle \sigma, n \rangle f ds + \int_{\Omega} (\nabla \cdot \sigma) f dx \\ &= + \lambda \int_{\Omega} f dx \\ &= + \lambda. \end{aligned}$$

Switching, we have that

$$\max_{\substack{|\sigma| \leq 1 \\ \nabla \cdot \sigma = \lambda}} \lambda = \min_{\substack{f=0 \text{ on } \partial\Omega \\ \int_{\Omega} f dx = 1}} \max_{|\sigma| \leq 1} - \int_{\Omega} \langle \sigma, \nabla f \rangle dx$$

$$\Rightarrow \max_{\substack{|\sigma| \leq 1 \\ \nabla \cdot \sigma = \lambda}} \lambda = \min_{\substack{f=0 \text{ on } \partial\Omega \\ \int_{\Omega} f dx = 1}} \int_{\Omega} |\nabla f| dx$$

Note: E

$$|\sigma| \leq 1, \nabla \cdot \sigma = \lambda \Rightarrow \int_{\Omega} \langle \sigma, \nabla f \rangle \leq \int_{\Omega} |\nabla f| dx$$

$$f=0 \text{ on } \partial\Omega, \int_{\Omega} f dx = 1$$

$$\text{So, } (P) \leq (D).$$

This is known as an L^1 - L^∞ pair. Generally, one is much easier to solve than the other.

$$* \min_{\substack{f=0 \text{ on } \partial\Omega \\ \int_{\Omega} f = 1}} \int_{\Omega} |\nabla f| dx = \min_{D \subset \Omega} \frac{\text{length}(\partial D)}{\text{Area}(D)} **$$

proof:

A key idea is the Coxe formula:

$$\int_{\Omega} f(x) |\nabla u| dx = \int_0^{\infty} \left(\int_{\partial \{u \geq t\}} f ds \right) dt$$

(If $u = |x - x_0|$ this gives the method of shells).

$$1. \min_{\substack{f=0 \text{ on } \partial\Omega \\ \int_{\Omega} f dx = 1}} \int_{\Omega} |\nabla f| dx = \min_{f=0 \text{ on } \partial\Omega} \frac{\int_{\Omega} |\nabla f| dx}{\int_{\Omega} f dx}.$$

2. We can assume $f \geq 0$ since changing f to $|f|$ leaves the derivative unchanged (thanks Mamikon).

$$3. \text{ For } f \geq 0, \int_{\Omega} f dx = \int_{\Omega} \left(\int_0^{f(x)} 1 dt \right) dx = \int_0^{\infty} \text{Area}\{f \geq t\} dt.$$

Fubini

$$4. \int_{\Omega} |\nabla f| dx = \int_0^{\infty} \text{length}\{f=t\} dt.$$

$$5. \text{ Let } \alpha \text{ be the minimum of } **. \text{ Then,}$$

$$\int_0^{\infty} \text{length}\{f=t\} dt \geq \alpha \int_0^{\infty} \text{Area}\{f \geq t\} dt.$$

$$\text{length}\{f=t\} \geq \alpha \text{Area}\{f \geq t\}$$

$$\Rightarrow \int_{\Omega} |\nabla f| dx \geq \alpha \int_{\Omega} f dx.$$

$$\Rightarrow * \geq **.$$

6. The opposite inequality is obtained by take a characteristic function.

Cheeger's Inequality: If λ_0 = 1st Dirichlet eigenvalue of Δ in Ω and

$$h = \min_{D \subset \Omega} \frac{\text{length}(\partial D)}{\text{area}(D)}$$

Then,

$$\frac{h^2}{4} \leq \lambda_0$$

proof:

$\exists \sigma$ s.t. $|\sigma| \leq 1$ and $\text{div} \sigma = h$. Let f_0 be the first Dirichlet Eigen function. Then,

$$h \int_{\Omega} f_0^2 = \int_{\Omega} \nabla \sigma \cdot \nabla f_0^2 = -2 \int_{\Omega} f_0 (\sigma \cdot \nabla f_0) dx$$

$$\begin{aligned} & \leq 2 \int_{\Omega} |f_0| \cdot |\nabla f_0| dx \\ & \leq 2 \|f_0\|_2 \cdot \|\nabla f_0\|_2 \\ \Rightarrow h & \leq 2 \|\nabla f_0\|_2 = 2 \lambda_0^{1/2} \end{aligned}$$

the derivative (Hadamard variation).

$$\frac{d}{dt} \int_{\Omega} |\nabla f_0|^2 = \int_{\Omega} \nabla f_0 \cdot \nabla \left(\frac{d}{dt} f_0^2 \right) = \int_{\Omega} \nabla f_0 \cdot \nabla (2 f_0 \sigma) = 2 \int_{\Omega} \nabla f_0 \cdot \nabla (f_0 \sigma)$$

$$= 2 \int_{\Omega} \nabla f_0 \cdot \nabla f_0 \sigma + 2 \int_{\Omega} f_0 \nabla f_0 \cdot \nabla \sigma$$

Let σ be the minimizer of

$$\int_{\Omega} |\nabla \sigma|^2 \quad \text{s.t.} \quad \text{div} \sigma = h$$

$$\int_{\Omega} \nabla f_0 \cdot \nabla f_0 \sigma = \int_{\Omega} \nabla f_0 \cdot \nabla (f_0 \sigma) = \int_{\Omega} \nabla f_0 \cdot \nabla f_0 \sigma$$

$$= \int_{\Omega} \nabla f_0 \cdot \nabla f_0 \sigma = \int_{\Omega} \nabla f_0 \cdot \nabla f_0 \sigma$$

The opposite inequality is obtained by taking a characteristic function.