

Lecture 4: Convexity (1-D case)

Goals:

1. For 1-D problems, lower semicontinuity \iff convex
2. Existence
3. Uniform convexity \implies uniqueness
4. Improvement to strong convergence.

Notation:

- $\Omega \subset \mathbb{R}^n$ bounded set with smooth boundary

- $L: \mathbb{R}^n \times \mathbb{R} \times \Omega \rightarrow \mathbb{R}$ is the Lagrangian.

- We will write

$$L(p, z, x) = L(p_1, \dots, p_n, z, x_1, \dots, x_n)$$

The variables are proxies for

$$p = \nabla f$$

$$z = f$$

$$-I[f] = \int_{\Omega} L(\nabla f, f, x) dx, \quad f = \gamma \text{ on } \partial\Omega.$$

I. Euler-Lagrange Equations

Lets do a formal calculation to derive the E-L equations (see lecture 2).

$$\delta I = \int_{\Omega} \left(\frac{\partial L}{\partial p} \cdot \nabla \delta f + \frac{\partial L}{\partial z} \delta f \right) dx$$

$$\delta I = \int_{\Omega} \left(\frac{\partial L}{\partial p} \cdot \nabla \delta f + \frac{\partial L}{\partial z} \delta f \right) dx$$

$$= \int_{\Omega} \left(-\nabla \cdot \frac{\partial L}{\partial p} + \frac{\partial L}{\partial z} \right) \delta f dx.$$

If $f \in C^2(\Omega)$ minimizes I then

$$\left(\frac{\partial L}{\partial z} - \sum_{i=1}^n \frac{\partial}{\partial x_i} \frac{\partial L}{\partial p_i} \right) \Big|_f = 0$$

Special Case:

1. If $\Omega \subset \mathbb{R}$ and L is independent of z then

$$\frac{\partial L}{\partial p} = c$$

2. $\Omega \subset \mathbb{R}$. The second form of the E-L equations

$$\left(\frac{d}{dx} \left[L - f'(x) \frac{\partial L}{\partial p} \right] = \frac{\partial L}{\partial x} \right) \Big|_f.$$

proof:

Differentiating we have that

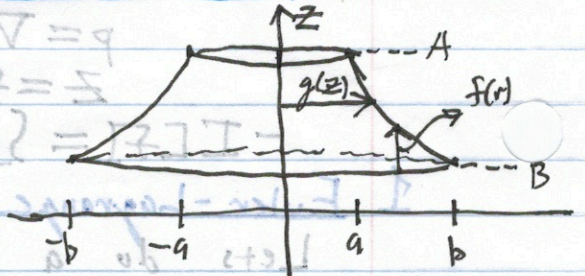
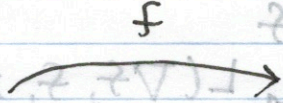
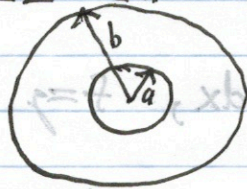
$$\begin{aligned} \frac{d}{dx} \left(L - f'(x) \frac{\partial L}{\partial p} \right) &= \frac{\partial L}{\partial x} + f'(x) \frac{\partial L}{\partial z} + f''(x) \frac{\partial L}{\partial p} \\ &\quad - f''(x) \frac{\partial L}{\partial p} - f'(x) \frac{d}{dx} \left(\frac{\partial L}{\partial p} \right) \\ &= \frac{\partial L}{\partial x} + f'(x) \left(\frac{\partial L}{\partial z} - \frac{d}{dx} \frac{\partial L}{\partial p} \right) \end{aligned} \quad \text{E-L.}$$

3. If L is independent of x then

$$L - f'(x) \frac{\partial L}{\partial p} = C \quad \text{or} \quad f'(x) = 0$$

2 Interesting Example - (Minimal Surfaces of Revolution)

Let $\Omega = \{a < r < b\} \subset \mathbb{R}^2$



Let $I: A \rightarrow \mathbb{R}$ be defined by

$$* I[f] = \int_{\Omega} \sqrt{1 + |\nabla f|^2} \, dx \, dy = 2\pi \int_a^b \sqrt{1 + f'(r)^2} \, r \, dr$$

where $A = \{f \in W^{1,1}(\Omega) : f(a) = A, f(b) = B\}$.

Let g be the radial distance from the z -axis. We can also study

$$** I^*[g] = 2\pi \int_A^B g(z) \sqrt{1 + g'(z)^2} \, dz$$

A physical upper bound on I is the following:

$$\inf_{f \in A} I[f] \leq \pi(a^2 + b^2)$$

(Area of two disjoint discs)

$$\left| \frac{d}{dx} \left(\frac{-1/g}{x} \right) = \left[\frac{-1/g}{x} \right]' \right|$$

If we look at the 2nd version of the E-2 equations

for I^* we have:

$$-g(z)\sqrt{1+g'(z)^2} + g(z)g'(z)^2 = C$$

$$\Rightarrow -g(z)(1+g'(z)^2) + g(z)g'(z)^2 = C(1+g'(z)^2)^{1/2}$$

$$g(z)^2 = C^2(1+g'(z)^2)$$

The solution to this equation is then

$$g(z) = c_1^{-1} \cosh(c_1 z + c_2)$$

c_1 and c_2 are determined by boundary conditions $g(B) = b$ and $g(A) = a$.

From boundary conditions we have that:

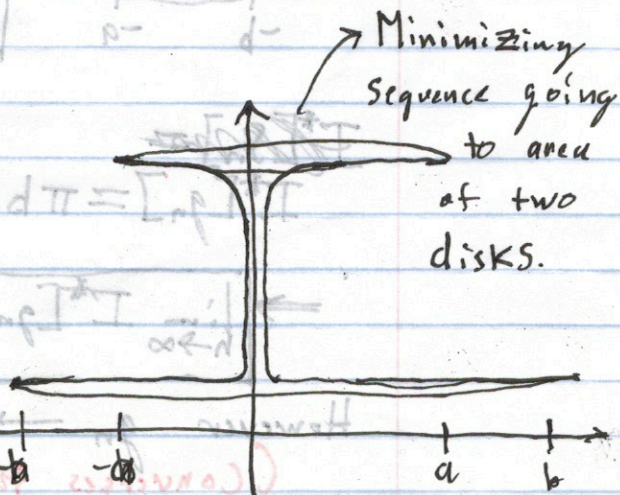
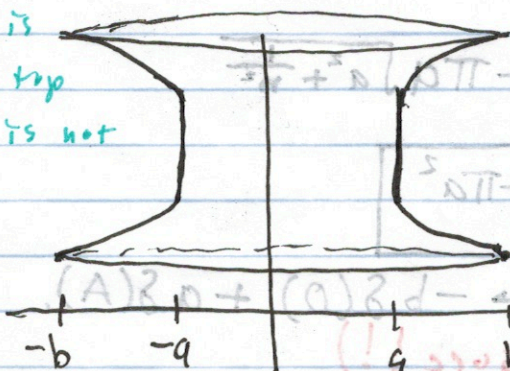
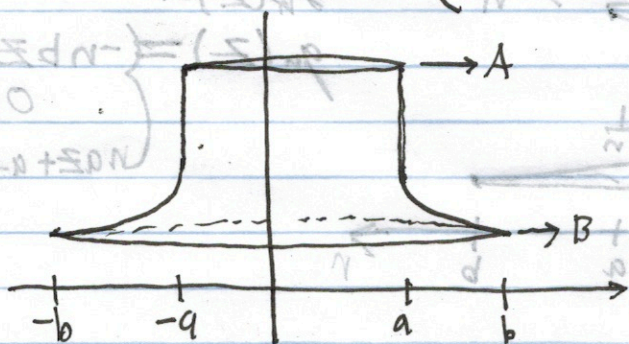
$$A - B = c_1^{-1} (\cosh(c_1 a + c_2) - \cosh(c_1 b + c_2)) > 0$$

This cannot be satisfied if $b - a$ is too large.

However, we can construct a weak solution

$$g(z) = \begin{cases} c_1^{-1} \cosh(c_1 z + c_2), & B < z < z^* \\ a, & z^* < z < A \end{cases}$$

However if $A - B$ is large enough then this cannot beat area of two disks.



(picture is incorrect, top radius is not a).

3. Existence

If $I: A \rightarrow \mathbb{R}$, with $A = \{f \in W^{1,p}(\Omega) : f = g \text{ on } \partial\Omega\}$ is convex defined by

$$I[f] = \int_{\Omega} W(\nabla f) + f \cdot h \, dx$$

satisfies

1. W is convex

2. W has "pth power growth"

$$C_1(|\nabla f|^{p-1}) \leq W(\nabla f) \leq C_2(|\nabla f|^p + 1)$$

then if $p > 1$, $\exists f^* \in W^{1,p}(\Omega)$ such that

$$I[f^*] = \liminf_{f \in A} I[f].$$

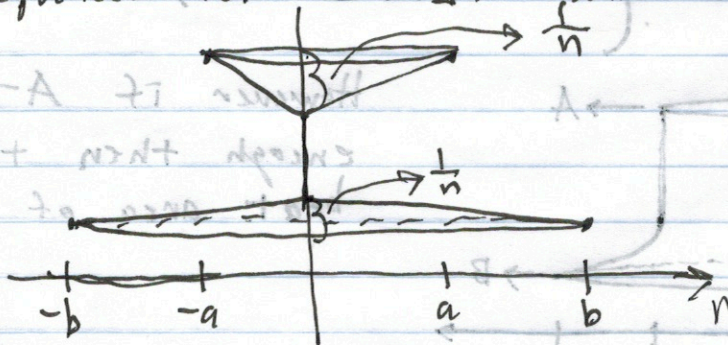
Lets find a lower bound:

$$I[f] = 2\pi \int_a^b r \sqrt{1+f'(r)^2} \, dr \geq 2\pi a \int_a^b -f'(r) \, dr = 2\pi a(A-B).$$

If A is large enough then

$$I[f] \geq \pi(b^2 + a^2) \quad (\text{In class we found a lower bound for } I^*)$$

Now, how can we show that $\pi(b^2 + a^2)$ is in some sense an optimal upper bound. Lets look at minimizing sequences for $I^*[f]$. (Assume $B=0$).



$$g_n(z) = \begin{cases} -nbz + b, & z < \frac{1}{n} \\ 0, & \frac{1}{n} < z < A - \frac{1}{n} \\ na z + a - naA, & A - \frac{1}{n} < z < A. \end{cases}$$

$I^*[g_n]$

$$I^*[g_n] = \pi b \sqrt{b^2 + \frac{1}{n^2}} + \pi a \sqrt{a^2 + \frac{1}{n^2}}$$

$$\Rightarrow \lim_{n \rightarrow \infty} I^*[g_n] = \pi b^2 + \pi a^2$$

However $g_n \rightarrow 0$, $g_n' \rightarrow -b\delta(0) + a\delta(A)$.
(Converges to a measure!!)

3. Existence

What structure on L might give us existence??

Assume the following problem:

$$I[f] = \int_{\Omega} L(p, z, x) dx = \int_{\Omega} L(\nabla f, f, x) dx$$

with $A = \{f \in W^{1,q}(\Omega) : f = g \text{ on } \partial\Omega\}$. We assume the following coercivity condition for $1 < q \leq \infty$:

$$L(p, z, x) \geq \alpha |p|^q - \beta.$$

Let $\{f_n\}$ be a minimizing sequence for I . Coercivity gives \exists a subsequence $\{f_{n_k}\}$ and f^* such that

$$\nabla f_{n_k} \xrightarrow{L^q} \nabla f^* \text{ and } f_{n_k} \xrightarrow{L^q} f^*.$$

To show f^* is a minimizer we must prove lower semicontinuity

$$I[f^*] \leq \liminf_{k \rightarrow \infty} I[f_{n_k}]$$

If f is a smooth minimizer then if we define

$$i(t) = I[u + tv], \quad v \in C_c^\infty(\Omega) \text{ (actually need } v \in C_c^{0,1})$$

then

$$i''(0) = \int_{\Omega} (v_{x_i} L_{p_i p_i} v_{x_i} + 2 v_{x_i} v L_{p_i z} + v^2 L_{zz}) dx \geq 0.$$

Set

$$v(x) = \varepsilon \eta(x) \varphi\left(\frac{x \cdot \xi}{\varepsilon}\right), \quad \xi \in \mathbb{R}^n, \eta \in C_c^\infty(\Omega)$$

and φ is the 2-periodic function defined by

$$\varphi(x) = \begin{cases} x, & x \in (0, 1) \\ 2-x, & x \in (1, 2) \end{cases}$$



Substituting this in we obtain

$$i''(0) = \int_{\Omega} \left(\eta(x)^2 \xi_i L_{p_i p_i} \xi_j \cdot \varphi'^2 + 2 \varepsilon \eta_{x_i} \varphi L_{p_i p_i} \xi_j \cdot \varphi' \right. \\ \left. + \varepsilon^2 \eta_{x_i} \varphi L_{p_i p_i} \eta_{x_j} \varphi + 2 \varepsilon \eta_{x_i} \eta \varphi^2 L_{p_i z} + 2 \varepsilon \eta^2 \xi_i \varphi' L_{p_i z} \right. \\ \left. + \varepsilon^2 \eta^2 \varphi'^2 \right) dx$$

Taking limit $\epsilon \rightarrow 0$ we have the Legendre Hadamard necessary condition:

$$\xi_i L_{p_i p_j} \xi_j \geq 0$$

→ This means the function is convex in its highest derivative.

For now, lets just consider

$$I[f] = \int_{\Omega} L(\nabla f) dx$$

Theorem - I is lower semicontinuous with respect to weak convergence in $W^{1,p}(\Omega)$ if and only if L is convex.

proof:

(\Rightarrow)

Fix $p \in \mathbb{R}^n$, we want to show $\nabla^2 L|_p \geq 0$. Construct a sequence as follows: (For simplicity we assume Ω is a cube).

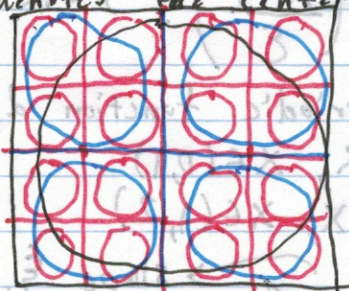
a.) Fix any $v \in C_c^\infty(\Omega)$,

b.) For $k \in \mathbb{N}$, subdivide Ω into disjoint subcubes $\{Q_k\}_{k=1}^{2^{kn}}$ of side length $\frac{1}{2^k}$.

c.) Define

$$u_k = \frac{1}{2^k} v(2^k(x-x_c)) + \vec{p} \cdot \vec{x}, \quad x \in Q_k$$

x_c denotes the center of Q_k and $u = p \cdot x$.



Clearly $u_k \rightarrow u$ in $W^{1,p}(\Omega)$. Since I is weakly lower semicontinuous we have that:

$$|\Omega| L(p) = I[u] \leq \liminf_{k \rightarrow \infty} I[u_k]$$

However, we know that

$$I[u_k] = \int_{\Omega} \nabla v(2^k(x-x_c)) + \vec{p} \cdot \vec{x}, \quad x \in Q_k$$

$$I[u_k] = \int_{Q_k} L(p + Dv(2^k(x-x_c))) dx$$

$$I[u_k] = 2^{kn} \int_{Q_k} L(p + Dv(2^k(x-x_c))) dx = \int_{Q_k} L(p + Dv) dx.$$

Therefore, $I[u] \leq I[u+v]$. → Mistake this should be $I[u] \leq I[u+v]$

Consequently, $u = p \cdot x$ is a minimum subject to its own boundary conditions. Therefore, L is convex.

(\Leftarrow).

Suppose $u_n \rightarrow u$ in $W^{1,p}(\Omega)$ and assume L is the max of finitely many affine functions

$$L(p) = \max_{j=1, \dots, m} (b^j \cdot p + c^j)$$

Write

$$E_j = \{x \in \Omega : L(\nabla f) = b^j \cdot \nabla f + c^j\}. \quad \text{should be } \nabla u$$

Then $\Omega = \bigcup_{j=1}^m E_j$, and we may as well assume the sets to be disjoint. From weak convergence we have

$$\begin{aligned} L[u] &= \int_{\Omega} L(\nabla u) dx = \sum_{j=1}^m \int_{E_j} (b^j \cdot \nabla u + c^j) dx \\ &= \lim_{k \rightarrow \infty} \sum_{j=1}^m \int_{E_j} (b^j \cdot \nabla u_k + c^j) dx \\ &= \liminf_{k \rightarrow \infty} \sum_{j=1}^m \int_{E_j} L(\nabla u_k) dx \\ &= \liminf_{k \rightarrow \infty} L[u_k]. \end{aligned}$$

The inequality is a result of the max formula. In the general case, we can write $F(p) = \lim_{m \rightarrow \infty} F^m(p)$ for $F^m(p) = \max_{j=1, \dots, m} (b^j \cdot p + c^j)$ and apply monotone convergence theorem.

Remark: This works since affine functions are weakly continuous and a convex function is the supremum of affine functions. Convexity gives us the natural nonlinearity that is compatible with the linear structure of weak convergence.

Theorem - Assume L is smooth, and in addition T the mapping

$p \mapsto L(p, z, x)$ is convex for each $z \in \mathbb{R}, x \in \Omega$. Then,

$I[\cdot]$ is weakly lower semicontinuous in $W^{1,2}(\Omega)$.

proof:

The idea of the proof is like we did before, except we need to use if $f_n \xrightarrow{w^{1,2}} f$ then $f_n \xrightarrow{L^q} f$. We then have to use Egoroff's theorem to deduce uniform convergence

$$\int_{G_\varepsilon} L(\nabla f, f, x) dx \leq \liminf_{k \rightarrow \infty} I[f_k]$$

Where G_ε is a set satisfying $|G_\varepsilon - \Omega| \rightarrow 0$. Then apply monotone convergence theorem. ■

Theorem (Existence): Assume L satisfies the coercivity condition

$$L(p, z, x) \geq \alpha |p|^q - \beta$$

and is convex in p . Suppose also $A \neq \emptyset$. Then there exists $f^* \in A$ such that

$$I[f^*] = \min_{f \in A} I[f].$$

proof:

Let $\{f_n\}$ be a minimizing sequence and w.l.o.g. assume $\beta = 0$. Therefore,

$$I[f] \geq \alpha \|\nabla f\|_{L^q(\Omega)}^q.$$

Therefore,

$$\sup_k \|\nabla f_k\|_{L^q(\Omega)} < \infty.$$

Now, let $w \in A \Rightarrow f_k - w \in W_0^{1,q}(\Omega)$. Therefore, by Poincaré's inequality we have that

$$\|f_k\|_{L^q(\Omega)} \leq \|f_k - w\|_{L^q(\Omega)} + \|w\|_{L^q(\Omega)} \leq C \|\nabla f_k - \nabla w\|_{L^q(\Omega)} + C \leq C.$$

Therefore, $\|\nabla f_k\|_{W^{1,q}(\Omega)}$ is bounded.

Therefore, there exists a subsequence f_{n_k} such that $f_{n_k} \xrightarrow{W^{1,p}} f^*$. From lower semi-continuity we have that

$$I[f^*] \leq \liminf_{k \rightarrow \infty} I[f_{n_k}].$$

Definition - $L(p, x)$ is **uniformly convex** if there exists $\theta > 0$

such that

$$L(p, x) \leq \frac{\xi_1 + \xi_2}{2} - \theta |\xi|^2$$

Theorem - Suppose $L(p, x)$ is uniformly convex. Then a minimizer $f \in A$ of $I[\cdot]$ is unique.

proof: $u, \tilde{u} \in A$

Suppose $u, \tilde{u} \in A$ both minimize I over A . Then $v = \frac{u + \tilde{u}}{2} \in A$.

We claim $I[v] \leq \frac{I[u] + I[\tilde{u}]}{2}$.

From uniform convexity we have that

$$L(p, x) \geq L(q, x) + D_p L(q, x) \cdot (p - q) + \frac{\theta}{2} |p - q|^2.$$

Set $q = \frac{D_u + D_{\tilde{u}}}{2}$, $p = D_u$ and integrate

$$I[u] \geq I[v] + \int_{\Omega} D_p L\left(\frac{D_u + D_{\tilde{u}}}{2}, x\right) \cdot (D_u - D_{\tilde{u}}) + \frac{\theta}{8} |D_u - D_{\tilde{u}}|^2 dx$$

Similarly

$$I[\tilde{u}] \geq I[v] + \int_{\Omega} D_p L\left(\frac{D_u + D_{\tilde{u}}}{2}, x\right) \cdot (D_{\tilde{u}} - D_u) + \frac{\theta}{8} |D_u - D_{\tilde{u}}|^2 dx$$

$$\Rightarrow I[v] + \frac{\theta}{8} \int_{\Omega} |D_u - D_{\tilde{u}}|^2 dx \leq \frac{I[u] + I[\tilde{u}]}{2}$$

$$\Rightarrow I[v] \leq \frac{I[u] + I[\tilde{u}]}{2}$$

Since u and \tilde{u} are minimizers we have that

$$I[v] = I[u]$$

$$\Rightarrow \int_{\Omega} |D_u - D_{\tilde{u}}|^2 dx = 0$$

$\Rightarrow u = \tilde{u}$ in $W^{1,p}(\Omega)$ from boundary conditions.

4. Improvement to Strong Convergence

Theorem - If $A = \{f \in W^{1,q}(\Omega) : f = g \text{ on } \partial\Omega\}$ and $q=2$ then if $L(p)$ is strictly convex meaning $\xi^T \cdot D^2 L \xi \geq \delta |p|^2, \delta > 0$

then a minimizing sequence converges strongly to $f \in W^{1,2}(\Omega)$,

if $|L(p)| \leq C(1+|p|^2)$ (growth condition)

proof.

From strict convexity we have that $\forall q, p \in \mathbb{R}^n$
 $F(q) \geq F(p) + DF(p) \cdot (q-p) + \frac{\delta}{2} |q-p|^2$

Set $p = Df$ and $q = Df_k$ and integrate over Ω to find

$$I[f_k] \geq I[f] + \int_{\Omega} DL(Df) \cdot (Df_k - Df) dx + \frac{\delta}{2} \int_{\Omega} |Df_k - Df|^2 dx$$

Now, $|DF(p)| \leq C(1+|p|)$ from convexity and the growth condition. Since $Df_k \rightarrow Df$ in L^2 it follows that since $DF \in L^2$ and $I[f_k] \rightarrow I[f]$ that

$$Df_k \rightarrow Df$$

5. Euler-Lagrange Equations Returned.

Definition - We say $f \in A$ is a weak solution of the E-L equations provided

$$\int_{\Omega} [L_p(Df, f, x) v_x + L_z(Df, f, x) v] dx = 0$$

for all $v \in W^{1,q}(\Omega)$. Here we assume that

$$A = \{f \in W^{1,q}(\Omega) : f = g \text{ on } \partial\Omega\}$$

Theorem - Assume L satisfies the following growth conditions.

1. $|L(p, z, x)| \leq C(|p|^q + |z|^q + 1)$
2. $|D_p L(p, z, x)| \leq C(|p|^{q-1} + |z|^{q-1} + 1)$
3. $|D_z L(p, z, x)| \leq C(|p|^{q-1} + |z|^{q-1} + 1)$

and $f^* \in A$ satisfies $I[f^*] = \inf_{f \in A} I[f]$ then f^* satisfies is a weak solution of the E-L equations.

proof:

Let $\tau \neq 0$ and write the difference quotient

$$\begin{aligned} \frac{i(\tau) - i(0)}{\tau} &= \int_{\Omega} \frac{L(\nabla f + \tau \nabla v, f + \tau v, x) - L(\nabla f, f, x)}{\tau} dx \\ &= \int_{\Omega} L^{\tau}(x) dx, \end{aligned}$$

where for $v \in W_0^{1,q}(\Omega)$, $i(\tau) = I[f + \tau v]$. Clearly,

$$L^{\tau}(x) \rightarrow L_{p_i}(\nabla f, f, x) v_{x_i} + L_z(\nabla f, f, x)$$

pointwise. We would like to use D.C.T. to put the limit inside.

We have a candidate for the limit ^{use} so let's rewrite:

$$\begin{aligned} L^{\tau}(x) &= \frac{1}{\tau} \int_0^{\tau} d L(\nabla f + s \nabla v, f + s v, x) ds \\ &= \frac{1}{\tau} \int_0^{\tau} [L_{p_i}(\nabla f + s \nabla v) v_{x_i} + L_z(\nabla f + s \nabla v, f + s v, x)] ds \end{aligned}$$

We now use Young's inequality and our growth conditions:

$$|L_{p_i}(\nabla f + s \nabla v) v_{x_i}| \leq c(|\nabla f + s \nabla v|^{p-1} + |v_{x_i}|^{p-1})$$

$$|L_z(\nabla f + s \nabla v, f + s v, x)| \leq c(|\nabla f + s \nabla v|^{q-1} + |f + s v|^{q-1} + |v|^{q-1} + 1)$$

$$\begin{aligned} |L_{p_i}(\nabla f + s \nabla v, f + s v, x) v_{x_i}| &\leq c(|\nabla f + s \nabla v|^{p-1} + |f + s v|^{p-1} + |v|^{p-1} + 1) |v_{x_i}| \\ &\leq c(|\nabla f|^{p-1} + |s|^{p-1} + |\nabla v|^{p-1} + |v|^{p-1} + 1) |v_{x_i}| \\ &\leq c(|\nabla f|^{p-1} + |f|^{p-1} + |\nabla v|^{p-1} + |v|^{p-1} + 1) |v_{x_i}| \end{aligned}$$

Similarly,

$$|L_z(\nabla f + s \nabla v, f + s v, x)| \leq c(|\nabla f|^{q-1} + |f|^{q-1} + |\nabla v|^{q-1} + |v|^{q-1} + 1) + |v|^{q-1}$$

This gives us our bounding function. Passing to the limit gives us the result.

Theorem - If the joint mapping $(p, z) \mapsto L(p, z, x)$ is convex for each x , then each weak solution is a minimizer.

proof:

From convexity $(p, z) \mapsto L(p, z, x)$ we have

$$L(\nabla f^*, f^*, x) + D_p L(\nabla f^*, f^*, x) \cdot (\nabla h - \nabla f^*) + D_z L(\nabla f^*, f^*, x) \cdot (h - f^*) \leq L(\nabla h, h, x),$$

for all $h \in A$. Consequently, $h - f^* \in W_0^{1,2}(\Omega)$ and integrating we have that

$$I[f^*] \leq I[h],$$

where the second term on the left vanishes since f^* solves the weak E-L equations. ▀

6. Summary:

1. Coercivity:

$$L(p, z, x) \geq \alpha |p|^q - \alpha z$$

2. If the mapping $p \mapsto L(p, z, x)$ is convex then L is w.l.s.c.

3. coercivity + w.l.s.c. \implies existence

4. If $L(p, z, x) = L(p, x)$ and the mapping $p \mapsto L(p, x)$ is uniformly convex then and coercive the minimizer is unique.

5. If $|L(p)| \leq C(1 + |p|^2)$ ~~is~~ this growth condition guarantees strong convergence of minimizing sequence.

6. Growth conditions also imply weak solutions of E-L equations are minimizers.

7. Growth conditions + convexity in p and z guarantee solutions of (weak) E-L equations are minimizers (not just local minimizers).