

Lecture 2: Variational Derivative

Goals:

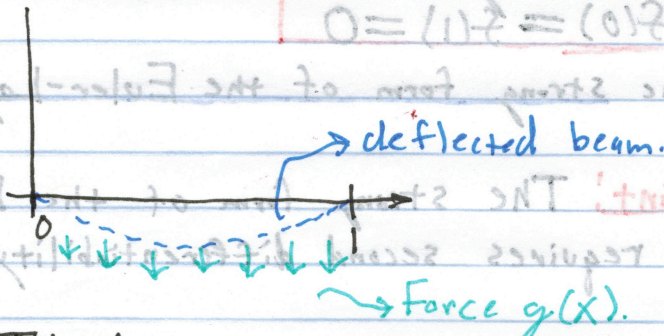
1. Derive Euler-Lagrange equations.
2. Discuss Dirichlet's principle.
3. Example from minimal surfaces.
4. Discuss "natural" boundary conditions.

Key Points:

1. How to derive Euler-Lagrange equations.

1. Formal Recipe

Elastic beam



$I: A \rightarrow \mathbb{R}$ is defined by

$$I[f] = \int_0^1 [f'(x)^2 + g(x) \cdot f(x)] dx$$

where $A = \{f \in C^\infty(\mathbb{R}) : f(0) = f(1) = 0\}$.

1. Assume that $f(x) \in A$ is a minimum.

2. Let $y \in C^\infty$ be a perturbation of f meaning $\forall t \in (0,1)$
 $(f + ty) \in A$. This means $y(0) = y(1) = 0$.

3. Since f is a minimum it follows that

$$\frac{d}{dt} (I[f + ty]) \Big|_{t=0} = 0.$$

$$I[f + ty] = \int_0^1 [(f'(x) + ty'(x))^2 + g(x)(f(x) + ty(x))] dx$$

$$\Rightarrow \frac{dI}{dt} = \int_0^1 [2(f'(x) + ty'(x))y'(x) + g(x)y(x)] dx$$

$$\Rightarrow \frac{dI}{dt} \Big|_{t=0} = \int_0^1 [2f'(x)y'(x) + g(x)y(x)] dx.$$

why can we differentiate inside the integral?

5. The weak form of the Euler-Lagrange equations is

$$\int_0^1 [2f'(x)y'(x) + g(x)y(x)] dx = 0$$

$$\forall y \in C_c^\infty(\mathbb{R}) \text{ satisfying } y(0) = y(1) = 0.$$

These are necessary conditions for a minimizer.

6. Integrate by parts:

$$\int_0^1 [-2f''(x) + g(x)] y(x) dx = 0.$$

Since this is true for all $y(x) \in C_c^\infty(\mathbb{R})$ we can conclude that

$$\begin{aligned} -2f''(x) + g(x) &= 0 \\ f(0) = f(1) &= 0 \end{aligned}$$

This is the strong form of the Euler-Lagrange equations.

Critical Point! The strong form of the Euler-Lagrange equations requires second differentiability.

7. Lets solve if $g(x) = g$ a constant.

$$f(x) = -\frac{1}{4}gx(x-1). \rightarrow \text{Very simple model of deflection.}$$

Elastic beam with thickness

$$I: A \rightarrow \mathbb{R} \text{ is defined by } \rightarrow \text{thickness of beam}$$

$$I[f] = \int_0^1 f'(x)^2 dx + h^2 \int_0^1 f''(x)^2 dx + \int_0^1 g(x)f(x) dx$$

$$f(0) = f(1) = 0$$

$$f'(0) = f'(1) = 0 \rightarrow \text{clamped boundary conditions.}$$

1. Assume $f(x)$ is a minimum. Let $y(x)$ be a perturbation meaning $y(0) = y(1) = y'(0) = y'(1) = 0$.

2. Now,

$$\frac{d}{dt} I[f + ty] \Big|_{t=0} = \int_0^1 [2f'(x)y'(x) + 2h^2 f''(x)y''(x) + g(x)y(x)] dx$$

3. Integrating by parts:

$$-2f''(x) + 2h^2 f'''(x) + g(x) = 0$$

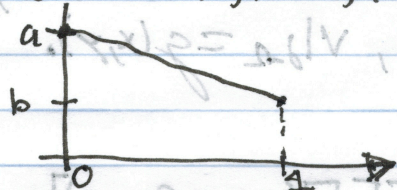
$$f(0) = f(1) = 0, \quad f'(0) = f'(1) = 0.$$

Elastic beam with thickness (no clamping)

$I: A \rightarrow \mathbb{R}$ is defined by

$$I[f] = \int_0^1 [f'(x)^2 + h^2 f''(x)^2 + g(x)f(x)] dx.$$

~~$A = \{f \in C^2(\mathbb{R}) : f(0) = f(1) = 0\}$~~
 $A = \{f \in C^\infty(0,1) : f(0) = a, f(1) = b\}$.



Now we assume a perturbation satisfying $\eta(0) = \eta(1) = 0$ so that $f + t\eta \in A$. Then,

$$0 = \frac{d}{dt} I[f + t\eta] \Big|_{t=0} = -2 \int_0^1 [f''(x)h^2 \eta'(x) + f(x)g(x)] \eta(x) dx$$

$$\Rightarrow -2f''(x) + 2h^2 f'''(x) + g(x) = 0$$

$f(0) = a, f(1) = b$
 $f''(0) = f''(1) = 0$ Natural Boundary Conditions.

Dirichlet's Principle

$I: A \rightarrow \mathbb{R}$ is defined by

$$I[f] = \int_{\Omega} |\nabla f|^2 dA + \int_{\Omega} fg dA,$$

where $A = \{f \in C^\infty(\mathbb{R}^n) : f(x) = h(x) \text{ on } \partial\Omega\}$. Let η be a perturbation satisfying $f + t\eta \in A$, i.e. $\eta = 0$ on $\partial\Omega$. Then,

$$\frac{d}{dt} I[f + t\eta] = \frac{d}{dt} \left(\int_{\Omega} |\nabla f + t\nabla\eta|^2 dA + \int_{\Omega} (f + t\eta)g dA \right)$$

$$= \int_{\Omega} 2\nabla\eta \cdot (\nabla f + t\nabla\eta) dA + \int_{\Omega} \eta g dA$$

$$\Rightarrow \int_{\Omega} 2\nabla\eta \cdot \nabla f dA + \int_{\Omega} \eta g dA = 0. \quad \rightarrow \text{Weak form.}$$

Apply Gauss-Green Theorem:

$$\int_{\partial\Omega} \nabla f \cdot \vec{n} \, ds - \int_{\Omega} (\Delta f - g) \, dA = 0$$

$$0 = \int_{\Omega} (\Delta f - g) \, dA \Rightarrow \Delta f = \frac{1}{2}g$$

→ Strong-form

$$f|_{\partial\Omega} = 0$$

Parametric Example

$\Gamma: A \rightarrow \mathbb{R}$ defined by

$$I[F] = \int_{\Omega} [(u_x + v_y)^2 + (u_y + v_x)^2] \, dx \, dy$$

where $F: \Omega \rightarrow \mathbb{R}^2$ is C^∞ and $F(x, y) = (u(x, y), v(x, y))$
and $u|_{\partial\Omega} = f(x, y)$, $v|_{\partial\Omega} = g(x, y)$.

Define,

$$\frac{\delta F}{\delta u} = \lim_{t \rightarrow 0} \frac{d}{dt} I[F(u + t\delta u, v)]$$

This is the Gateaux differential in the direction δu .

Calculating,

$$\frac{\delta F}{\delta u} = \int_{\Omega} [2(u_x + v_y)\delta u_x + 2(u_y + v_x)\delta u_y] \, dx \, dy$$

$$= \int_{\Omega} [2(u_x + v_y, u_y + v_x) \cdot \nabla \delta u] \, dx \, dy$$

$$= \int_{\partial\Omega} \delta u \cdot 2(u_x + v_y, u_y + v_x) \cdot \vec{n} \, ds - \int_{\Omega} 2(u_{xx} + 2v_{xy} + u_{yy}) \delta u \, dx \, dy$$

$$\Rightarrow u_{xx} + 2v_{xy} + u_{yy} = 0$$

Likewise,

$$v_{xx} + 2u_{xy} + v_{yy} = 0$$

$$\Rightarrow u_{xx} + 2v_{xy} + u_{yy} = 0$$

$$v_{xx} + 2u_{xy} + v_{yy} = 0$$

$$u|_{\partial\Omega} = f(x, y)$$

$$v|_{\partial\Omega} = g(x, y)$$