

# Group Session 2

Thursday, July 2nd

## Problem 1

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In this problem, we will solve example 3 from class using the concept of matrix exponentials.

1. First, calculate the eigenvalues and eigenvectors of matrix  $A = \begin{bmatrix} 1 & 2 \\ 3 & 2 \end{bmatrix}$  (or find them from your class notes).
  2. Is matrix  $A$  diagonal/diagonalizable/not diagonalizable? Why?
  3. Find the transformation matrix  $T$  for  $A$ .
  4. Calculate  $T^{-1}AT$ . Call this matrix  $D$  and have a member of your group explain why the result makes sense given your answer to part 2.
  5. Calculate  $e^{Dt}$ . Recall that this is a fundamental matrix for  $\mathbf{y}' = D\mathbf{y}$  where  $\mathbf{x} = T\mathbf{y}$ .
  6. Use this matrix to calculate the fundamental matrix for the system of differential equations in  $\mathbf{x}$ :  $\mathbf{x}' = A\mathbf{x}$ .
  7. Have another member in your group summarize the steps you took in this problem and check with your instructors.
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**Problem 2**

In this problem, we consider example 3 in section 7.6 in the book, but solve it in a different way. Let

$$m_1 \frac{d^2 x_1}{dt^2} = -(k_1 + k_2)x_1 + k_2 x_2, \quad (1)$$

$$m_2 \frac{d^2 x_2}{dt^2} = k_2 x_1 - (k_2 + k_3)x_2. \quad (2)$$

These equations describe the motion of 2 masses and 3 springs.

1. Re-write the system in matrix form:  $\mathbf{x}'' = \mathbf{A}\mathbf{x}$ , where  $\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ .
2. Let  $m_1 = 2$ ,  $m_2 = \frac{9}{4}$ ,  $k_1 = 1$ ,  $k_2 = 3$ ,  $k_3 = \frac{15}{4}$ . Write down the matrix  $\mathbf{A}$  in this case, and make sure it is correct before you proceed.
3. Let  $\mathbf{x} = \mathbf{v}e^{rt}$  and plug it into the  $\mathbf{x}'' = \mathbf{A}\mathbf{x}$  equation. Show that  $(\mathbf{A} - r^2\mathbf{I})\mathbf{v} = \mathbf{0}$ . Note that now  $r^2$  (as opposed to  $r$ ) are eigenvalues of matrix  $\mathbf{A}$ .
4. Compute the eigenvalues of matrix  $\mathbf{A}$ , and then find  $r$  and  $\mathbf{v}$  from part 3.
5. Find  $x_1$  and  $x_2$  by recalling the solution guess in part 3. Note that there should be 4 arbitrary constants in these expressions.

6. Have another member in your group summarize the steps you took in this problem and check with your instructors.
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### Problem 3

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In class, we only looked at solutions of equation  $\mathbf{x}' = A\mathbf{x}$  for  $A$  a real-valued matrix. In this problem, we examine what happens in the case of a specific type of complex matrix.

A square matrix  $A$  is called **Hermitian** if  $A = \bar{A}^T$  (in other words, if it equals the conjugate of its transpose). This is usually denoted as  $A = A^*$ . Note that  $(AB)^* = B^*A^*$ , and  $(A\mathbf{x})^* = \mathbf{x}^*A^*$ .

**Note:** If there is not enough time, go straight to part 4 of this question.

1. What properties does a Hermitian matrix with real entries have?
2. If a Hermitian matrix has complex entries, what can you say about its diagonal elements?
3. In this part, we will prove that all eigenvalues of a Hermitian matrix are real.
  - (a) Start with the definition of an eigenvalue-eigenvector pair:

$$A\mathbf{v} = \lambda\mathbf{v}. \tag{3}$$

Apply  $*$  to both sides of this equation, then multiply the right of both sides by  $\mathbf{v}$ .

- (b) Use the fact that  $A$  is Hermitian:  $A = A^*$  and equation (3) to simplify your result from part (b).
- (c) Conclude that  $\lambda = \lambda^*$  and discuss with this group what this suggests about the eigenvalues of a Hermitian matrix.

It can also be shown that a Hermitian matrix  $A$  must have a full set of linearly independent eigenvectors.

4. Let

$$H = \begin{bmatrix} 1 & 2 + i \\ 2 - i & 5 \end{bmatrix}.$$

(a) Verify that matrix  $H$  is Hermitian.

(b) Find the eigenvalues and eigenvectors of matrix  $H$ .

(c) Discuss any observations with your group.

(d) Write down the general solution of  $\mathbf{x}' = H\mathbf{x}$ .

Have someone in your group explain what this problem suggests about solving  $\mathbf{x}' = A\mathbf{x}$  where  $A$  a Hermitian matrix.

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#### Problem 4

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In the last part of the problem session, we will show you an example of a numerical tool that can create the phase portraits for a given planar (2-equation) system of differential equations. We will be using the tool later in the course as well.

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