

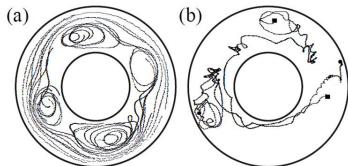
# Open Issues in Boundary Conditions of FPDEs and the Generalized Feynman-Kac Equation

Weihua Deng

School of Mathematics and Statistics, Lanzhou University

Joint work with Buyang Li, Wenyi Tian, and Pingwen Zhang

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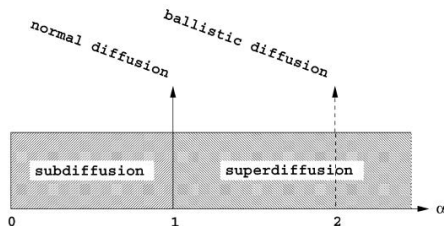


- 1 Introduction
- 2 Anomalous Diffusion
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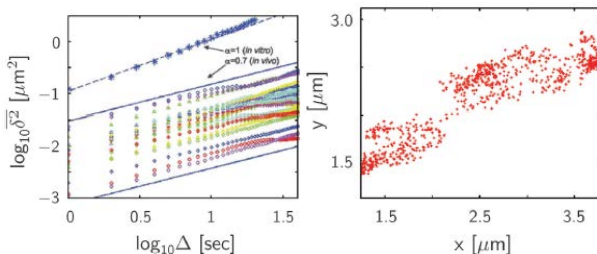
The types of diffusion are usually classified according to the relation of the mean squared displacement (MSD) of a particle to the time  $t$ .

- **Subdiffusion**,  $\langle x^2(t) \rangle \sim t^\alpha$  with  $0 < \alpha < 1$ ;
- **Normal diffusion** (Brownian motion),  $\langle x^2(t) \rangle \sim t$ ;
- **Superdiffusion**,  $\langle x^2(t) \rangle \sim t^\alpha$  with  $\alpha > 1$ .



When  $\alpha \neq 1$ , the corresponding diffusion is called **anomalous diffusion**.

Subdiffusion can be found in various natural phenomena, such as motion of labelled messenger RNA molecules in a living coli cell.



**Figure:** Motion of labelled messenger RNA molecules. Left: time averaged MSD of individual trajectories plotted as a function of the lag time  $\Delta$  shows pronounced trajectory-to-trajectory scatter. All exhibit approximately the same anomalous diffusion exponent  $\alpha \approx 0.7$  with some local variations. Right: points of the trajectory of an individual messenger RNA in the coli cell, showing that the molecule explores a major fraction of the bacterium's volume.

The other applications of anomalous diffusion:

- **Subdiffusion** can also be found in the following systems: charge carrier transport in amorphous semiconductors, nuclear magnetic resonance (NMR) diffusometry in percolative, Rouse or reptation dynamics in polymeric systems, transport on fractal geometries, the diffusion of a scalar tracer in an array of convection rolls, the dynamics of a bead in a polymeric network, etc.

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- **Superdiffusion** can model the food searching strategies of seagulls. It can also be used to determine the positions of locating  $N$  radar stations to optimize the searching for  $M$  targets. Superdiffusion is also observed in special domains of rotating flows, in collective slip diffusion on solid surfaces, in layered velocity fields, etc.



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$W(x, t)$  – The probability density function (PDF) to find the particle under observation at position  $x$  at time  $t$ .

The classical Fokker-Planck equation.

$$\frac{\partial W(x, t)}{\partial t} = K_1 \frac{\partial^2 W(x, t)}{\partial x^2}$$

- $K_1$  – Coefficient of diffusion with the dimension of  $[K_1] = cm^2/s$ .
- If the particle is released at the origin at time  $t = 0$  in an unbounded space, the solution is  $W(x, t) = \frac{1}{\sqrt{4\pi K_1 t}} \exp\left(-\frac{x^2}{4K_1 t}\right)$ .
- The variance  $\langle x^2(t) \rangle = 2K_1 t$ .

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This equation is indeed equivalent to **Fick's second law** for the concentration of a chemical substance originally presented by Adolf Fick from a combination of **the continuity equation** and the **constitutive equation** (Fick's first law). Using **Taylor expansion** can also obtain the master equation for Brownian motion instead of Fick's first law.

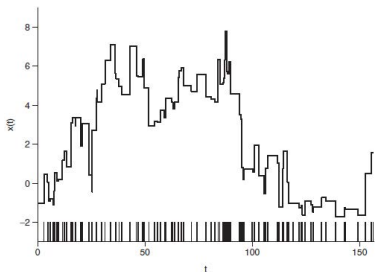
Another derivation of Brownian motion was published in 1980 by Paul Langevin using the concept of a stochastic force.

$$m \frac{dv}{dt} = -\zeta v + F(t)$$

- $m$  and  $v$  are the mass and velocity of Brownian particle respectively.
- $\zeta$  – The frictional constant.
- $F(t)$  – The white Gaussian noise:  $\langle F(t) \rangle = 0$  and  $\langle F(t)F(t') \rangle = 2\zeta k_B T \delta(t - t')$ , where  $k_B$  is the Boltzman constant and  $T$  is absolute temperature.
- $\langle x^2(t) \rangle = (2k_B T / \zeta)t$ .
- The Langevin equation is actually obtained from **Newton's second law**.

## CTRW Model.

Considering a particle, which starts at the origin. It has to wait for a random waiting (trapping) time  $\tau$  drawn from the **waiting time PDF**  $\phi(\tau)$ , before it makes a jump to left or right. The **length of the jump** can also be chosen to be a random variable,  $\delta x$ , distributed in terms of the PDF  $\lambda(\delta x)$ . After the jump, a new pair of waiting time and jump length are drawn from the PDFs  $\phi(\tau)$  and  $\lambda(\delta x)$ .



**Figure:** A trajectory of a CTRW with exponential distribution of waiting times ( $\lambda = 1$ ) and Gaussian distribution of step lengths (with zero mean and unit dispersion).

For the space-time decoupled case, the PDF  $W(x, t)$  obeys the algebraic relation in Fourier-Laplace space

$$W(k, s) = \frac{1 - \phi(s)}{s} \frac{W_0(k)}{1 - \lambda(k)\phi(s)}.$$

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- $W_0(k)$  – The Fourier transform of the initial condition  $W(x, t = 0)$ .
- The way of diffusion (sub-, normal or super diffusion) is determined by
  - 1 **First moment of waiting time**  $\langle \tau \rangle = \int_0^\infty \tau \phi(\tau) d\tau,$
  - 2 **Second moment of jump length**  $\langle (\delta x)^2 \rangle = \int_{-\infty}^\infty (\delta x)^2 \lambda(\delta x) d(\delta x).$

Quantities/PDFs	Normal Diffusion	Subdiffusion	Lévy flight
$\langle \tau \rangle$	Finite	Infinite	Finite
$\langle (\delta x)^2 \rangle$	Finite	Finite	Infinite
$\phi(\tau)$	Exponential	Power-law	Exponential
$\lambda(\delta x)$	Normal	Normal	Lévy distribution
Equation of $W(x, t)$	Classical	Time fractional	Space fractional
MSD $\langle x^2(t) \rangle$	$2K_1 t$	$\frac{2K_\alpha}{\Gamma(1+\alpha)} t^\alpha, 0 < \alpha < 1$	$t^{2/\mu}, 0 < \mu < 2$

## Distributions in the table

- Exponential distribution:  $\phi(\tau) = \gamma^{-1} \exp(-\tau/T)$  with  $\langle \tau \rangle = \gamma$ .
- Power-law distribution:  $\phi(\tau) \sim (\gamma/\tau)^{1+\alpha}, 0 < \alpha < 1$  with Laplace transform  $\phi(s) \sim 1 - (\gamma s)^\alpha$ .
- Normal distribution:  $\lambda(\delta x) = (4\pi\sigma^2)^{-1/2} \exp(-(\delta x)^2/(4\sigma^2))$ .
- Lévy distribution: the definition is given through its Fourier transform,  $\lambda(k) = \exp(-\sigma^\mu |k|^\mu) \sim 1 - \sigma^\mu |k|^\mu$  for  $0 < \mu < 2$ . The asymptotic behaviour is  $\lambda(\delta x) \sim \sigma^{-\mu} |(\delta x)|^{-1-\mu}$  for  $|(\delta x)| \gg \sigma$ .



Equations for anomalous diffusion in the above table ( $0 < \alpha < 1$ ,  $0 < \mu < 2$ )

- **Time fractional** Fokker-Planck equation (subdiffusion):

$$\frac{\partial}{\partial t} W(x, t) = {}_{\text{RL}} D_t^{1-\alpha} K_\alpha \frac{\partial^2}{\partial x^2} W(x, t), \quad K_\alpha \equiv \sigma^2 / \gamma^\alpha.$$

The fractional operator of the **Riemann-Liouville** form is defined as <sup>1</sup>

$${}_{\text{RL}} D_t^{1-\alpha} W(x, t) = \frac{1}{\Gamma(\alpha)} \frac{\partial}{\partial t} \int_0^t \frac{W(x, t')}{(t-t')^{1-\alpha}} dt'.$$

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<sup>1</sup>M. M. Meerschaert and A. Sikorskii, Stochastic Models for Fractional Calculus (Walter de Gruyter, Berlin, 2012).

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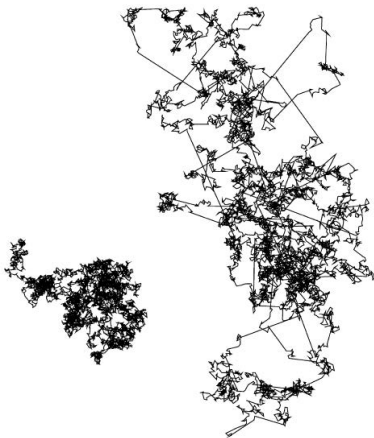
- **Space fractional** equation (superdiffusion):

$$\frac{\partial}{\partial t} W(x, t) = K^\mu \nabla_x^\mu W(x, t), \quad K^\mu \equiv \sigma^\mu / \gamma.$$

The Fourier transform of the fractional operator is

$$\mathcal{F} \{ \nabla_x^\mu W(x, t) \} = -|k|^\mu W(k, t).$$

<sup>1</sup>M. M. Meerschaert and A. Sikorskii, Stochastic Models for Fractional Calculus (Walter de Gruyter, Berlin, 2012).



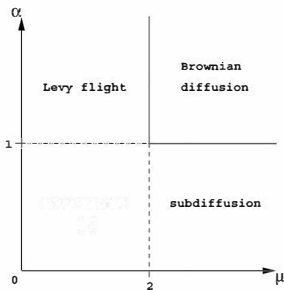
**Figure:** Comparison of the trajectories of a Brownian or subdiffusive random walk (left) and a Lévy flight (right)).

The composite between long rests and long jumps.

$$\frac{\partial}{\partial t} W(x, t) = {}_{\text{RL}} D_t^{1-\alpha} K_\alpha^\mu \frac{\partial^\mu}{\partial x^\mu} W(x, t), \quad K_\alpha^\mu = \sigma^\mu / \gamma^\alpha.$$

$$\langle |x|^2(t) \rangle \propto t^{2\alpha/\mu}$$

According to the MSD, we have the following classification



## Tempered Distribution.

Tempered power-law waiting time distribution:

$$\phi(\tau) \sim \frac{1}{-\Gamma(-\alpha)} \tau^{-(1+\alpha)} \exp(-\lambda\tau)$$

- The purpose of tempering: comparing with a sharp cutoff, the exponential tempering has both mathematical and practical advantages, i.e., the tempered process is still an infinitely divisible Lévy process.
- The process with tempered power-law waiting time distribution and normal jump length distribution become **Brownian motion** when time is sufficiently long. However, when time is short, **subdiffusion** is observed because the exponential tempering has little influence on the motion.
- Similarly, we can also define the tempered jump length distribution.

▲ Define the functional:

$$A = \int_0^t U[x(\tau)] d\tau$$

- $x(\tau)$  – Trajectory of a particle.
- $U(x)$  – A prescribed function.

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▲ Applications:

- $U(x) = \begin{cases} 1, & \text{if } x > 0 \\ 0, & \text{otherwise.} \end{cases}$

$A$  means the occupation time in the positive half space.

- $U(x) = \begin{cases} 1, & \text{if } |x| \leq b \\ 0, & \text{otherwise.} \end{cases}$

$A$  means the total residence time of the particle in the interval  $[-b, b]$ .

- $U(x) = x$ .

$A$  represents the total area under the random walk curve  $x(t)$ .


- Denoting  $G(x, A, t)$  the joint pdf of  $x$  and  $A$  at time  $t$ .
- $G(x, p, t) = \int_0^\infty \exp(-pA)G(x, A, t)dA$  (Fourier transform w.r.t.  $A$  also makes sense).
- **The classical Feynman-Kac equation**<sup>2</sup>:

$$\frac{\partial}{\partial t} G(x, p, t) = D \frac{\partial^2}{\partial x^2} G(x, p, t) - pU(x)G(x, p, t)$$

$D$  represents the diffusion coefficient.

Note:  $p = 0 \Rightarrow$  The diffusion equation  $\frac{\partial}{\partial t} G(x, t) = D \frac{\partial^2}{\partial x^2} G(x, t)$ .

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<sup>2</sup>M. Kac, On distributions of certain Wiener functionals. Trans. Am. Math. Soc. **65**, **1** (1949). 



The forward equation for Lévy flights (with power-law waiting time):

$$\frac{\partial}{\partial t} G(x, p, t) = K_{\alpha}^{\mu} \nabla_x^{\mu} \mathcal{D}_t^{1-\alpha} G(x, p, t) - pU(x)G(x, p, t)$$

- $\nabla_x^{\mu}$  – **Riesz spatial fractional derivative operator** defined in Fourier space as  $\nabla_x^{\mu} \rightarrow -|k|^{\mu}$  ( $x \rightarrow k$ ).
- $\mathcal{D}_t^{1-\alpha}$  – **Substantial fractional derivative operator**, defined as

$$\mathcal{D}_t^{1-\alpha} G(x, p, t) = \frac{1}{\Gamma(\alpha)} \left[ \frac{\partial}{\partial t} + pU(x) \right] \int_0^t \frac{\exp[-(t-\tau)pU(x)]}{(t-\tau)^{1-\alpha}} G(x, p, \tau) d\tau.$$

- $\alpha = 1 \Rightarrow$  The classical Feynman-Kac equation.
- $p = 0 \Rightarrow$  The fractional Fokker-Planck equation.

Note: For the **backward** or **tempered** fractional Feynman-Kac equation please see <sup>3</sup> <sup>4</sup>.

<sup>3</sup>S. Carmi, L. Turgeman, and E. Barkai, On Distributions of Functionals of Anomalous Diffusion Paths, J. Stat. Phys. **141**, 1071 (2010).

<sup>4</sup>X. C. Wu, W. H. Deng, and E. Barkai, Tempered fractional Feynman-Kac equation: Theory and examples, Phys. Rev. E **93**, 032151 (2016).

Brownian motion (normal diffusion) {  
Classical Fokker-Planck equation  
Classical Langevin equation

CTRW model (anomalous diffusion) {  
Introduction of the model  
Fractional Fokker-Planck equations  
Tempered distribution  
Fractional Feynman-Kac equation.

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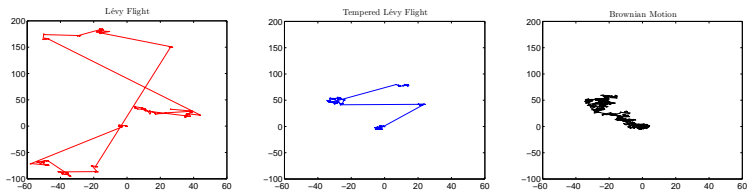


Figure: Random trajectories (1000 steps) of Lévy flight, tempered Lévy flight, and Brownian motion.

For Lévy processes, **except Brownian motion**, all others have **discontinuous paths**.

- Most of the research works on the mean first exit time or escape probability appear in the mathematical, physical, and engineering literatures, with the Langevin type dynamical system

$$dX_t = F(X_t)dt + \sigma(X_t)dW_t.$$

- If  $W_t$  denotes a non-Gaussian  $\beta$ -stable type Lévy process whose trajectories are not continuous, **escape probability** in this case <sup>5</sup> represents the probability of a particle starting at a point  $x$  in  $D$ , first escaping a domain  $D$  and landing in a subset  $E$  of  $D^c$  (the complement of  $D$ ).

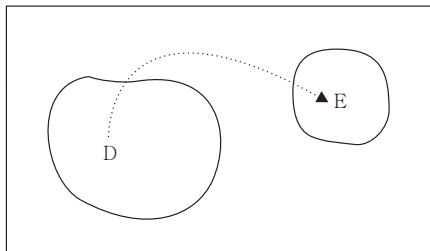
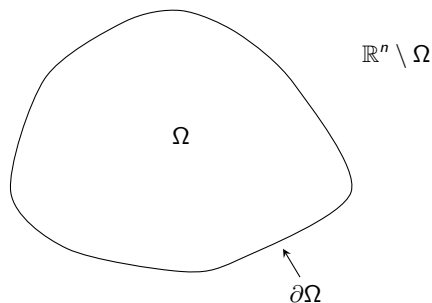


Figure: The exit phenomenon of Lévy flight with discontinuous paths.

<sup>5</sup>W. H. Deng, X. C. Wu, and W. L. Wang, Mean exit time and escape probability for the anomalous processes with the tempered power-law waiting times, EPL, 117(2017), p. 10009.



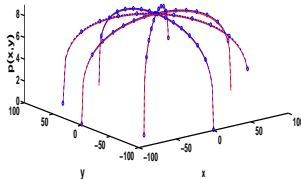
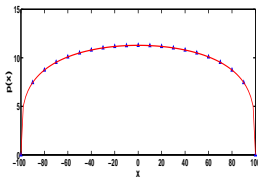
- The boundary  $\partial\Omega$  itself can not be hit by the majority of discontinuous sample trajectories.
- The **generalized boundary conditions** must be introduced, which must contain the information on the domain  $\mathbb{R}^n \setminus \Omega$ .

Consider the steady state fractional diffusion equation

$$\begin{cases} \Delta^{\beta/2} p(\mathbf{X}) = -1 & \text{in } \Omega, \\ p(\mathbf{X}) = 0 & \text{in } \mathbb{R}^n \setminus \Omega. \end{cases} \quad (1)$$

The meaning of the solution  $p(\mathbf{X})$  is the **mean first exit time** of particles performing Lévy flights; if taking  $\Omega = \{\mathbf{X} : |\mathbf{X}| < r\}$ , then <sup>6</sup>

$$p(\mathbf{X}) = \frac{\Gamma(n/2)(r^2 - |\mathbf{x}|^2)^{\beta/2}}{2^\beta \Gamma(1 + \beta/2) \Gamma(n/2 + \beta/2)}. \quad (2)$$



<sup>6</sup>R. K. Gettoor, First passage times for symmetric stable processes in space, Trans. Amer. Math. Soc., 101 (1961).

Another steady state fractional diffusion equation

$$\begin{cases} \Delta^{\beta/2} p(\mathbf{X}) = 0 & \text{in } \Omega, \\ p(\mathbf{X}) = g(\mathbf{X}) & \text{in } \mathbb{R}^n \setminus \Omega. \end{cases} \quad (3)$$

- Given a domain  $E \subset \mathbb{R}^n \setminus \Omega$ , if taking  $g(\mathbf{X}) = 1$  for  $\mathbf{X} \in E$  and 0 for  $\mathbf{X} \in (\mathbb{R}^n \setminus \Omega) \setminus E$ , then the solution  $p(\mathbf{X})$  is the **escape probability** undergoing Lévy flights.
- If  $g(\mathbf{X}) \equiv 1$  in  $\mathbb{R}^n \setminus \Omega$ , then  $p(\mathbf{X})$  equals to 1 in  $\Omega$  because of the probability interpretation.



- The initial and boundary value problem (**anisotropy**):

$$\left\{ \begin{array}{l} \frac{\partial p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial t} = \frac{\partial^{\beta_1} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_1|^{\beta_1}} + \frac{\partial^{\beta_2} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_2|^{\beta_2}} \\ \quad + \dots + \frac{\partial^{\beta_n} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_n|^{\beta_n}} \quad \text{in } \Omega, \\ p(\mathbf{x}_1, \dots, \mathbf{x}_n, 0) = p_0(\mathbf{x}_1, \dots, \mathbf{x}_n) \quad \text{in } \Omega, \\ p(\mathbf{x}_1, \dots, \mathbf{x}_n, t) = g(\mathbf{x}_1, \dots, \mathbf{x}_n, t) \quad \text{in } \mathbb{R}^n \setminus \Omega. \end{array} \right.$$

- $g(\mathbf{x}_1, \dots, \mathbf{x}_j, \dots, \mathbf{x}_n, t)$  should satisfies that there exist positive  $M$  and  $C$  such that for  $j = 1, \dots, n$ , when  $|\mathbf{x}_j| > M$ ,

$$\frac{|g(\mathbf{x}_1, \dots, \mathbf{x}_j, \dots, \mathbf{x}_n, t)|}{|\mathbf{x}_j|^{\beta_j - \varepsilon}} < C \quad \text{for positive small } \varepsilon.$$

- Another initial and boundary value problems (**isotropic**):

$$\begin{cases} \frac{\partial p(\mathbf{X}, t)}{\partial t} = \Delta^{\beta/2} p(\mathbf{X}, t) \\ p(\mathbf{X}, 0) = p_0(\mathbf{X}) \quad \text{in } \Omega, \\ p(\mathbf{X}, t) = g(\mathbf{X}, t) \quad \text{in } \mathbb{R}^n \setminus \Omega. \end{cases} \quad (4)$$

- $g(\mathbf{X}, t)$  should satisfy that there exist positive  $M$  and  $C$  such that when  $|\mathbf{X}| > M$ ,

$$\frac{|g(\mathbf{X}, t)|}{|\mathbf{X}|^{\beta-\varepsilon}} < C \quad \text{for positive small } \varepsilon.$$

**Absorbing boundary conditions** correspond to  $g(\mathbf{X}, t) = 0$ .

▲ Sending  $\beta \rightarrow 2$  in Eq. (4), the classical Dirichlet boundary conditions is recovered.

- ▲ Sending  $\beta \rightarrow 2$  in Eq. (4), the classical Dirichlet boundary conditions is recovered.
- ▲ The fractional laplacian operator in Eq. (4) reduces to classical laplacian operator. Thus only  $g(\mathbf{X}, t)$  on  $\partial\Omega$  will be used when solving this equation.

Consider the time-dependent problem:

$$\begin{cases} \frac{\partial p}{\partial t} - \Delta \frac{\beta}{2} p = f & \text{in } \Omega, \\ p(\cdot, 0) = p_0 & \text{in } \Omega, \\ p = g & \text{in } \mathbb{R}^n \setminus \Omega. \end{cases} \quad (5)$$

Consider the time-dependent problem:

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The weak formulation of (5) is to find  $p = g + \phi$  such that

$$\phi \in L^2(0, T; H_0^{\frac{\beta}{2}}(\Omega)) \cap H^1(0, T; H^{-\frac{\beta}{2}}(\Omega)) \hookrightarrow C([0, T]; L^2(\Omega))$$

and  $\forall q \in L^2(0, T; H_0^{\frac{\beta}{2}}(\Omega))$

$$\int_0^T \int_{\Omega} \partial_t \phi q \, d\mathbf{X} dt + \int_0^T \int_{\mathbb{R}^n} \Delta^{\frac{\beta}{4}} \phi \Delta^{\frac{\beta}{4}} q \, d\mathbf{X} dt = \int_0^T \int_{\Omega} (f + \Delta^{\frac{\beta}{2}} g - \partial_t g) q \, d\mathbf{X} dt. \quad (6)$$

- $a(\phi, q) := \int_{\mathbb{R}^n} \Delta^{\frac{\beta}{4}} \phi \Delta^{\frac{\beta}{4}} q \, d\mathbf{X}$  is a **coercive** bilinear form on  $H_0^{\frac{\beta}{2}}(\Omega) \times H_0^{\frac{\beta}{2}}(\Omega)$ ,
- $l(q) := \int_{\Omega} (f + \Delta^{\frac{\beta}{2}} g - \partial_t g) q \, d\mathbf{X}$  is a **continuous** linear functional on  $L^2(0, T; H_0^{\frac{\beta}{2}}(\Omega))$ .

Such a problem as (6) has a unique weak solution <sup>7</sup>.

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<sup>7</sup>E. Zeidler, *Nonlinear Functional Analysis and its Applications II/B: Nonlinear Monotone Operators*, Springer Science+Business Media, LLC, 1990.

- Consider the classical diffusion equation:

$$\begin{cases} \frac{\partial \rho(\mathbf{X}, t)}{\partial t} = \Delta \rho(\mathbf{X}, t) & \text{in } \Omega, \\ \rho(\mathbf{X}, 0) = \rho_0(\mathbf{X}) & \text{in } \Omega, \\ \nabla \rho(\mathbf{X}, t) = g(\mathbf{X}, t) & \text{in } \partial\Omega. \end{cases} \quad (7)$$

- This equation can be derived by:

- mass conservation:  $\frac{\partial \rho(\mathbf{X}, t)}{\partial t} = -\nabla \cdot \mathbf{j}$ ,
- Fick's law:  $\mathbf{j} = -\nabla \rho(\mathbf{X}, t)$ .

- The reflecting boundary condition  $g = 0$  corresponds to  $\mathbf{j} = 0$ , which means that the particles will reflect once they hit the boundary  $\partial\Omega$ .



- Consider the anomalous diffusion equation:

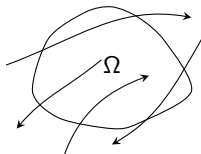
$$\left\{ \begin{array}{l} \frac{\partial p(\mathbf{X}, t)}{\partial t} = \Delta^{\beta/2} p(\mathbf{X}, t) \quad \text{in } \Omega, \\ p(\mathbf{X}, 0) = p_0(\mathbf{X}) \quad \text{in } \Omega, \\ \text{Neumann type boundary conditions.} \end{array} \right. \quad (8)$$

- We can

- maintain** mass conservation:  $\frac{\partial p(\mathbf{X}, t)}{\partial t} = -\nabla \cdot \mathbf{j}$ ,
- generalize** Fick's law:  $\mathbf{j} = \text{something}$ , such that  $\Delta^{\frac{\beta}{2}} p(\mathbf{X}, t) = -\nabla \cdot \mathbf{j}$ .

Thus Eq. (8) is established.

- ▲ The reflecting boundary condition  $\mathbf{j} = 0$  here means differently with the classical case.



**Figure:** Sketch map of particles jumping into, or jumping out of, or passing through the domain  $\Omega$ . But the number of particles inside  $\Omega$  is **conservative**.

- ▲ If  $\mathbf{j}|_{\mathbb{R}^n \setminus \Omega} = 0$ , then  $\Delta^{\frac{\beta}{2}} p(\mathbf{X}, t) = -\nabla \cdot \mathbf{j} = 0$  in  $\mathbb{R}^n \setminus \Omega$ . The Neumann type boundary condition in (8) can be, heuristically, defined as

$$\Delta^{\frac{\beta}{2}} p(\mathbf{X}, t) = g(\mathbf{X}) \quad \text{in } \mathbb{R}^n \setminus \Omega.$$

- Another initial and boundary value problem (**anisotropy**):

$$\left\{ \begin{array}{ll} \frac{\partial p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial t} = \frac{\partial^{\beta_1} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_1|^{\beta_1}} + \frac{\partial^{\beta_2} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_2|^{\beta_2}} \\ \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad + \dots + \frac{\partial^{\beta_n} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_n|^{\beta_n}} & \text{in } \Omega, \\ p(\mathbf{x}_1, \dots, \mathbf{x}_n, 0) = p_0(\mathbf{x}_1, \dots, \mathbf{x}_n) & \text{in } \Omega, \\ \frac{\partial^{\beta_1} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_1|^{\beta_1}} + \frac{\partial^{\beta_2} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_2|^{\beta_2}} \\ \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad + \dots + \frac{\partial^{\beta_n} p(\mathbf{x}_1, \dots, \mathbf{x}_n, t)}{\partial |\mathbf{x}_n|^{\beta_n}} = g(\mathbf{X}, t) & \text{in } \mathbb{R}^n \setminus \Omega. \end{array} \right.$$

- ▲ Sending  $\beta \rightarrow 2$  in Eq. (8), the classical Neumann boundary condition is **recovered**.

▲ Sending  $\beta \rightarrow 2$  in Eq. (8), the classical Neumann boundary condition is **recovered**.

▲ The weak solution  $p : [0, +\infty) \rightarrow H^{\beta/2}(\mathbb{R}^n)$  of Eq. (8) satisfies

$$\int_{\Omega} p_t q d\mathbf{X} + \int_{\mathbb{R}^n} \Delta^{\beta/4} p \Delta^{\beta/4} q d\mathbf{X} = - \int_{\mathbb{R}^n \setminus \Omega} g q d\mathbf{X} \quad \forall q \in H^{\beta/2}(\mathbb{R}^n).$$

Taking  $\beta \rightarrow 2$ ,

$$\boxed{\int_{\Omega} p_t q d\mathbf{X} + \int_{\Omega} \nabla p \cdot \nabla q d\mathbf{X} = \int_{\partial\Omega} \frac{\partial p}{\partial n} q ds,}$$

since

$$\int_{\mathbb{R}^n \setminus \Omega} g q d\mathbf{X} = \int_{\mathbb{R}^n \setminus \Omega} (\Delta p) q d\mathbf{X} = - \int_{\partial\Omega} \frac{\partial p}{\partial n} q ds - \int_{\mathbb{R}^n \setminus \Omega} \nabla p \cdot \nabla q d\mathbf{X}$$

and

$$\int_{\mathbb{R}^n} \Delta^{1/2} p \Delta^{1/2} q d\mathbf{X} = \int_{\mathbb{R}^n} \nabla p \cdot \nabla q d\mathbf{X}.$$

Consider the problem:

$$\begin{cases} \frac{\partial p}{\partial t} - \Delta^{\frac{\beta}{2}} p = f & \text{in } \Omega, \\ \Delta^{\frac{\beta}{2}} p = g & \text{in } \mathbb{R}^n \setminus \Omega, \\ p(\cdot, 0) = p_0 & \text{in } \Omega. \end{cases} \quad (9)$$

### Definition (Weak solutions)

The weak formulation of (9) is to find  $p \in L^2(0, T; H^{\frac{\beta}{2}}(\mathbb{R}^n)) \cap C([0, T]; L^2(\Omega))$  such that

$$\partial_t p \in L^2(0, T; H^{\frac{\beta}{2}}(\Omega)') \text{ and } p(\cdot, 0) = p_0,$$

satisfying the following equation:  $\forall q \in L^2(0, T; H^{\frac{\beta}{2}}(\mathbb{R}^n))$

$$\begin{aligned} & \int_0^T \int_{\Omega} \partial_t p(\mathbf{X}, t) q(\mathbf{X}, t) d\mathbf{X} dt + \int_0^T \int_{\mathbb{R}^n} \Delta^{\frac{\beta}{4}} p(\mathbf{X}, t) \Delta^{\frac{\beta}{4}} q(\mathbf{X}, t) d\mathbf{X} dt \\ &= \int_0^T \int_{\Omega} f(\mathbf{X}, t) q(\mathbf{X}, t) d\mathbf{X} dt - \int_0^T \int_{\mathbb{R}^n \setminus \Omega} g(\mathbf{X}, t) q(\mathbf{X}, t) d\mathbf{X} dt. \end{aligned} \quad (10)$$

Let  $t_k = k\tau$ ,  $k = 0, 1, \dots, N$ , be a partition of the time interval  $[0, T]$ , and define

$$f_k(\mathbf{X}) := \frac{1}{\tau} \int_{t_{k-1}}^{t_k} f(\mathbf{X}, t) dt, \quad k = 0, 1, \dots, N,$$

$$g_k(\mathbf{X}) := \frac{1}{\tau} \int_{t_{k-1}}^{t_k} g(\mathbf{X}, t) dt, \quad k = 0, 1, \dots, N.$$

Consider the time-discrete problem: for a given  $p_{k-1} \in L^2(\mathbb{R}^n)$ , find  $p_k \in H^{\frac{\beta}{2}}(\mathbb{R}^n)$  such that the following equation holds:

$$\begin{aligned} & \frac{1}{\tau} \int_{\Omega} p_k(\mathbf{X}) q(\mathbf{X}) d\mathbf{X} + \int_{\mathbb{R}^n} \Delta^{\frac{\beta}{4}} p_k(\mathbf{X}) \Delta^{\frac{\beta}{4}} q(\mathbf{X}) d\mathbf{X} \\ &= \frac{1}{\tau} \int_{\Omega} p_{k-1}(\mathbf{X}) q(\mathbf{X}) d\mathbf{X} + \int_{\Omega} f_k(\mathbf{X}) q(\mathbf{X}) d\mathbf{X} - \int_{\mathbb{R}^n \setminus \Omega} g_k(\mathbf{X}) q(\mathbf{X}) d\mathbf{X} \quad \forall q \in H^{\frac{\beta}{2}}(\mathbb{R}^n). \end{aligned} \quad (11)$$

If we define the piecewise constant functions

$$f^{(\tau)}(\mathbf{X}, t) := f_k(\mathbf{X}) = \frac{1}{\tau} \int_{t_{k-1}}^{t_k} f(\mathbf{X}, t) dt \quad \text{for } t \in (t_{k-1}, t_k], \quad k = 0, 1, \dots, N,$$

$$g^{(\tau)}(\mathbf{X}, t) := g_k(\mathbf{X}) = \frac{1}{\tau} \int_{t_{k-1}}^{t_k} g(\mathbf{X}, t) dt \quad \text{for } t \in (t_{k-1}, t_k], \quad k = 0, 1, \dots, N,$$

$$p_+^{(\tau)}(\mathbf{X}, t) := p_k(\mathbf{X}) \quad \text{for } t \in (t_{k-1}, t_k], \quad k = 0, 1, \dots, N,$$

and the piecewise linear function

$$p^{(\tau)}(\mathbf{X}, t) := \frac{t_k - t}{\tau} p_{k-1}(\mathbf{X}) + \frac{t - t_{k-1}}{\tau} p_k(\mathbf{X}) \quad \text{for } t \in [t_{k-1}, t_k], \quad k = 0, 1, \dots, N,$$

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<sup>8</sup>P. L. Lions, *Mathematical Topics in Fluid Mechanics: Volume 1: Incompressible Models*, Clarendon Press, Oxford, USA., 1996.



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$$g^{(\tau)}(\mathbf{X}, t) := g_k(\mathbf{X}) = \frac{1}{\tau} \int_{t_{k-1}}^{t_k} g(\mathbf{X}, t) dt \quad \text{for } t \in (t_{k-1}, t_k], \quad k = 0, 1, \dots, N,$$

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then (11) implies

$$\begin{aligned} & \int_0^T \int_{\Omega} \partial_t p^{(\tau)}(\mathbf{X}, t) q(\mathbf{X}, t) d\mathbf{X} dt + \int_0^T \int_{\mathbb{R}^n} \Delta^{\frac{\beta}{4}} p_+^{(\tau)}(\mathbf{X}, t) \Delta^{\frac{\beta}{4}} q(\mathbf{X}, t) d\mathbf{X} dt \\ &= \int_0^T \int_{\Omega} f^{(\tau)}(\mathbf{X}, t) q(\mathbf{X}, t) d\mathbf{X} dt - \int_0^T \int_{\mathbb{R}^n \setminus \Omega} g^{(\tau)}(\mathbf{X}, t) q(\mathbf{X}, t) d\mathbf{X} dt. \end{aligned} \quad (12)$$

By taking  $\tau = \tau_j \rightarrow 0$ <sup>8</sup>. in (12), we obtain (10).

<sup>8</sup>P. L. Lions, *Mathematical Topics in Fluid Mechanics: Volume 1: Incompressible Models*, Clarendon Press, Oxford, USA., 1996.

# Thanks for Your Attention!

## Main References:

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